

# verification, validation, and basal strength in models for the present state of ice sheets

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# Outline

recent Greenland work

evaluating spun-up present-day states (is this model validation?)

subspace of basal strength parameters: the weak heart of ice dynamics modeling



# PISM in one slide

- PISM = Parallel Ice Sheet Model [www.pism-docs.org](http://www.pism-docs.org)
- physical model relevant to this talk:
  - mass continuity
  - polythermal conservation of energy
  - shallow hybrid stress balance:
    - shallow ice approximation (SIA)
    - + dragging-or-floating shallow shelf approximation (SSA) as a *sliding law for SIA*
- grid rectangular in horizontal & unequal (fine base) in vertical
- parallelism:
  - fields are PETSc Vecs with DA grid/topology
  - = MPI, but *not* by-hand
  - SSA stress balance:
    - by-hand “outer” viscosity iteration
    - + direct call to KSP for linear solve (= pc gmres)
  - Jed Brown

## PISM experiment: identify three parameters

- enhancement factor  $e$  in flow law:

$$D = e A |\tau|^{n-1} \tau$$

- exponent  $q$  in power law till, written as pseudo-plastic:

$$\vec{\tau}_b = -\tau_c \frac{\vec{u}_b}{|\vec{u}_b|^{(1-q)} u_0^q}$$

- allowed maximum  $\alpha$  for basal water pressure, as fraction of overburden pressure  $p_{\text{over}} = \rho g H$ :

$$p_w = \alpha \frac{W}{W_0} p_{\text{over}}$$

giving yield stress

→

by Mohr-Coulomb

$$\tau_c = (\tan \phi) (p_{\text{over}} - p_w)$$

## PISM experiment, cont.: parameter study

- these cases

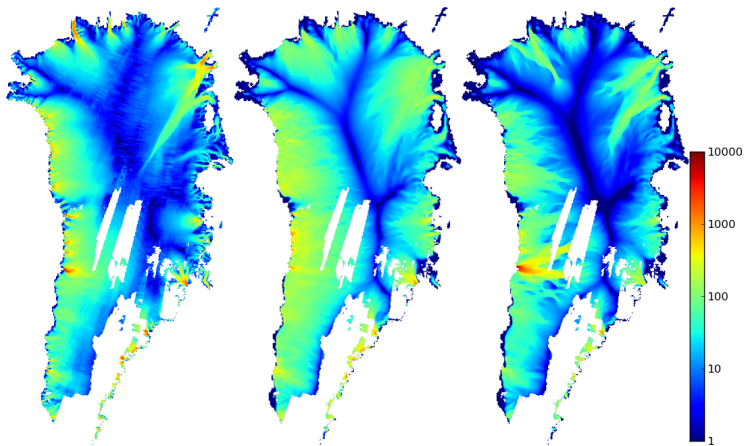
$$e = 1, 3, 5$$

$$q = 0.1, 0.25, 0.5$$

$$\alpha = 0.95, 0.98, 0.99$$

- not doing inverse modeling ... only *three* global, scalar parameters
- run on 3 km grid for 100 model years, from present thickness
- “spin-ups” also used these parameters (i.e. lots of spinups)
- *steady climate*
- on next slide: compare model snapshot to present-day observed

# present-day surface velocity: observed and modeled



observed

model

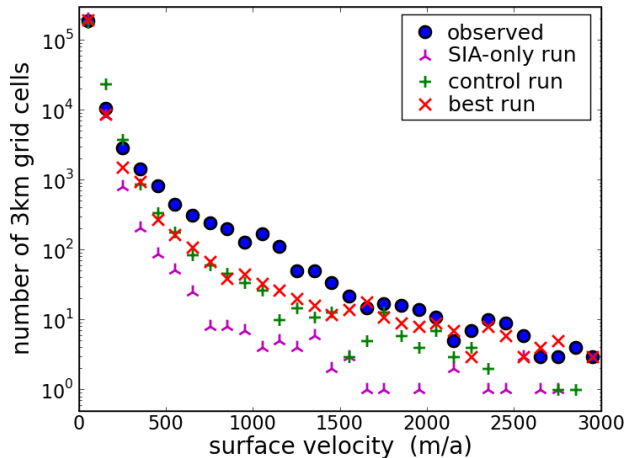
$e = 3$  and power law sliding  
( $u_b \sim \tau_b^4$ ) and modest allowed  
basal water pressure

model

$e = 1$  and nearly-plastic  
sliding and high allowed basal  
water pressure

Ed: pause for eyeball norm!

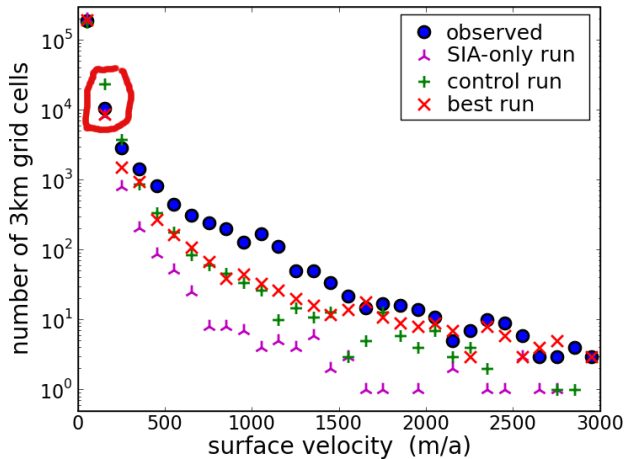
# comparison



- prev slide had 3 of 4:  
observed ●  
and  
model run +  
and  
model run ×
- note log scale on *y*-axis



# comparison



- prev slide had 3 of 4:
  - observed ●
  - and model run +
  - and model run ×
- note log scale on  $y$ -axis

## spin-up: we all do it . . .

- present day measurements not sufficient for initial values
- so we do modeling “before getting to” our proposed initial state
- . . . I’ll call that **spin-up** even if it is *inverse modeling*
- (and I am not trying to be precise about this language; I’m trying to avoid a false dichotomy)

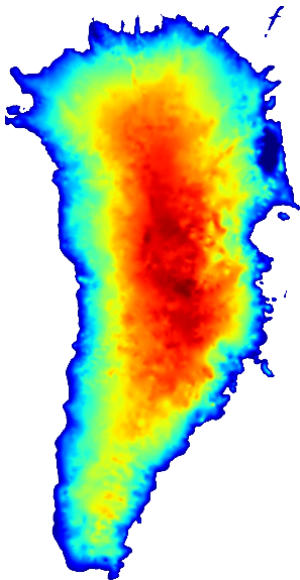
## spin-up: we all do it, cont.

- by what standard do we choose among spinup procedures?
- propose a metric or norm on modeled present state  $m_{PS}$  with several  $\Delta f = f_{\text{observed}} - f_{m_{PS}}$ :

$$\begin{aligned} J[m_{PS}] = & c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 \\ & + c_2 \|\Delta T_{\text{cores}}\|^2 \\ & + c_3 \|\Delta A_{\text{isochrone}}\|^2 \\ & + c_4 \left\| \Delta \frac{db}{dt} \right\|^2 \end{aligned}$$

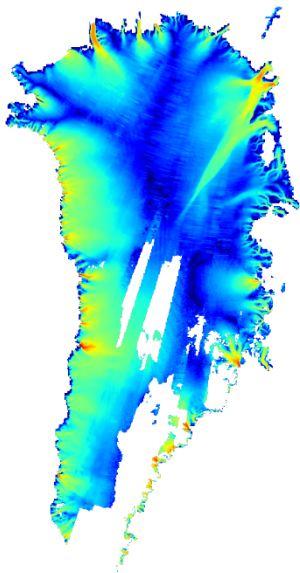
- my understanding of the paradigm:
  1. drop the terms which you have “already inverse-modeled”
  2. assign coefficients  $c_0, c_1, c_2, c_3, c_4$
  3. choose the spinup that minimizes  $J[\cdot]$

# Greenland ice thickness



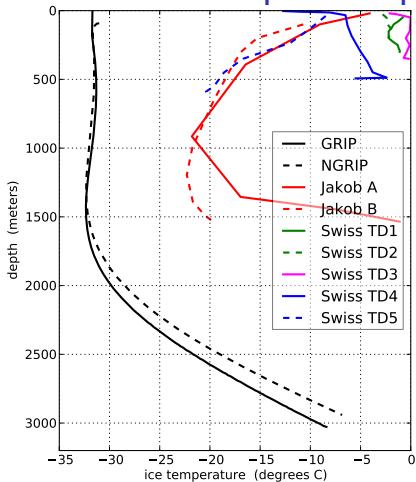
$$\begin{aligned} J[m_{PS}] = & c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 \\ & + c_2 \|\Delta T_{\text{cores}}\|^2 \\ & + c_3 \|\Delta A_{\text{isochrone}}\|^2 \\ & + c_4 \left\| \Delta \frac{db}{dt} \right\|^2 \end{aligned}$$

# Greenland surface velocity

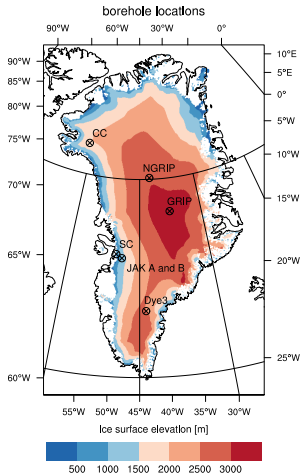


$$\begin{aligned} J[m_{PS}] = & c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 \\ & + c_2 \|\Delta T_{\text{cores}}\|^2 \\ & + c_3 \|\Delta A_{\text{isochrone}}\|^2 \\ & + c_4 \left\| \Delta \frac{db}{dt} \right\|^2 \end{aligned}$$

# measured temps at depth in Greenland holes/cores

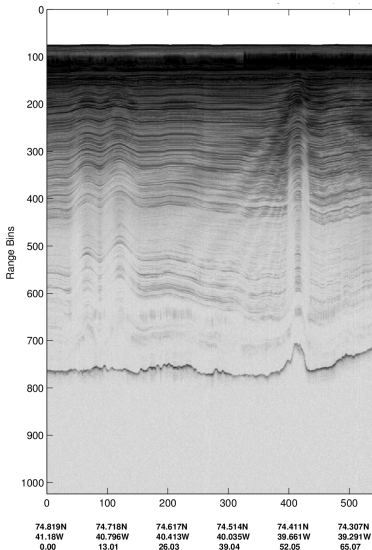


- sparse
- biased?



$$J[m_{PS}] = c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 + c_2 \|\Delta T_{\text{cores}}\|^2 + c_3 \|\Delta A_{\text{isochrone}}\|^2 + c_4 \left\| \Delta \frac{db}{dt} \right\|^2$$

# radar isochrones in Greenland



- ← CReSIS 2002 flightline, NE Greenland

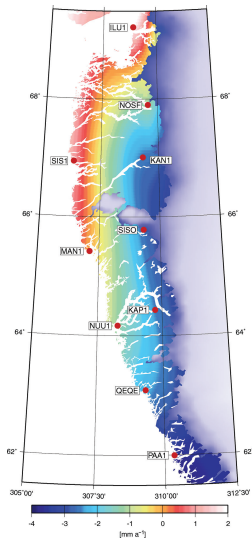
- $A =$  (ice age) solves

$$\partial_t A + u\partial_x A + v\partial_y A + w\partial_z A = 1$$

- isochrone = (level surface of  $A$ )
- best if isochrones are *dated* (but still provide  $\partial_{x,y,z} A$  if not)

$$\begin{aligned}
 J[m_{PS}] = & c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 \\
 & + c_2 \|\Delta T_{\text{cores}}\|^2 \\
 & + c_3 \|\Delta A_{\text{isochrone}}\|^2 \\
 & + c_4 \left\| \Delta \frac{db}{dt} \right\|^2
 \end{aligned}$$

# bedrock uplift rate in SW Greenland



- from Dietrich, Rülke, & Scheinert (2005)

$$J[m_{PS}] = c_0 \|\Delta H\|^2 + c_1 \|\Delta u_s\|^2 + c_2 \|\Delta T_{\text{cores}}\|^2 + c_3 \|\Delta A_{\text{isochrone}}\|^2 + c_4 \left\| \Delta \frac{db}{dt} \right\|^2$$



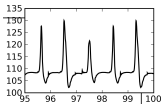
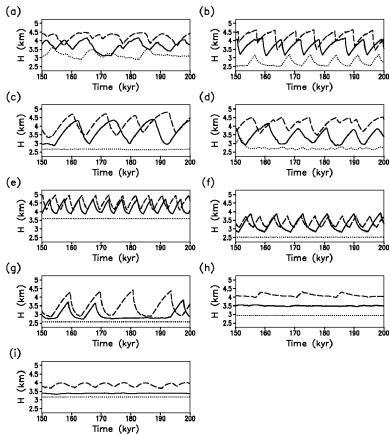
of course I have no idea how to

- ... assign values to  $c_0, c_1, c_2, c_3, c_4$

## dancing around the issue

- do the terms above, in the metric, strongly-control the critical model parameter subspace?
- here's what we believe is the critical subspace:
  - something like a sliding law exponent  $q$
  - something like a basal water pressure limit  $\alpha$
  - controls on thickness of near-basal temperate layer
  - controls on near-basal anisotropy
- in fact, are the parameters controlling **time-dependent basal strength** constrained by existing/available observations?
- the proposed metric is probably **dancing around this issue**

# warning for SeaRISE and ice2sea



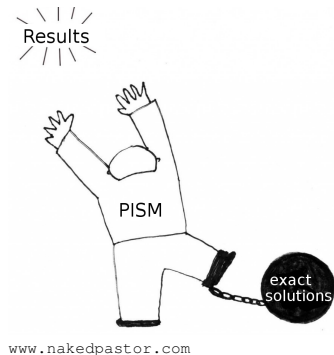
- as a community, we do not have a clue about the time-dependence of basal sliding:
  - ← **top**: average thickness over sediment area in HEINO intercomparison
  - ← **bottom**: average speed over one ice stream from Bueller & Brown (2009)

## goal is more than just a good present-day state

- it is not just that we want to get the present state right
- we want to know that the model **went through past states in a reasonable way**
- ... so the model might have **predictive capability in time**
- I'd like to learn more about
  - inverse modeling *in time*?
  - uncertainty quantification?

## role of verification in PISM

- yes, PISM has software unit tests
- ... but we are also dragging around exact solutions and running them as verification before almost every commit
- Q: is this good or sustainable?
- I feel the need for exact solutions to *significant coupled subsystems*
- for such exact solutions the numerical error is the most sensitive and comprehensive “unit test” for that subsystem



# exact solutions: also dancing around the issue

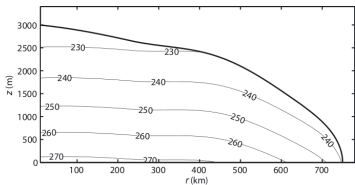


Fig. 2. Thickness and temperature field (K) in test G, evaluated at  $t = 500$  years.

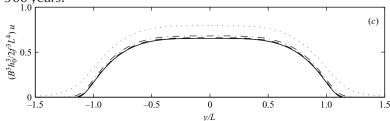


FIGURE 3. Numerical solutions of the depth-integrated ice flow problem compared with analytical solutions and solutions of the full Stokes equations. Each panel shows a numerical

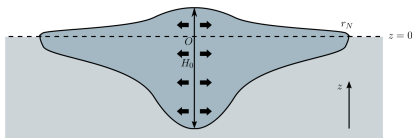


Figure 4: Cross-section of an axisymmetric shelf formed by a vertical line source, which is a point source in the horizontal plane.

Bueler et al. (2007);  
thermocoupled,  
non-sliding SIA; test  
G in PISM

Schoof (2006); SSA  
with pre-determined  
yield stress; test I in  
PISM

Sam Pegler (2009);  
spreading ice shelf  
with vertical-line  
source; not yet in  
PISM

## wanted: the *right* exact solution

- anyone out there have an exact formula for a **time-dependent grounded, sliding flow with SSA-type longitudinal stress?**
- ... it never hurts to ask ...
- MISMIP is in the right direction, but I'd rather have it exact-and-manufactured than asymptotically-matched-and-not-quite-a-solution-to-the-PDEs-I'm-solving