

A 2-D subglacial drainage system model combining channels with sheet flow and water storage

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Motivation

So far there only few **2D-models** of the subglacial drainage system including both **channelized and distributed** drainage, none of which have been applied to real geometries.

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About water flow

Now some theory...

About water flow

Water flows down the hydraulic potential

$$\underbrace{\phi}_{\text{hydraulic potential}} = \underbrace{p_w}_{\text{pressure potential}} + \underbrace{\rho_w g H}_{\text{elevation potential}}$$

About water flow

Water flows down the hydraulic potential

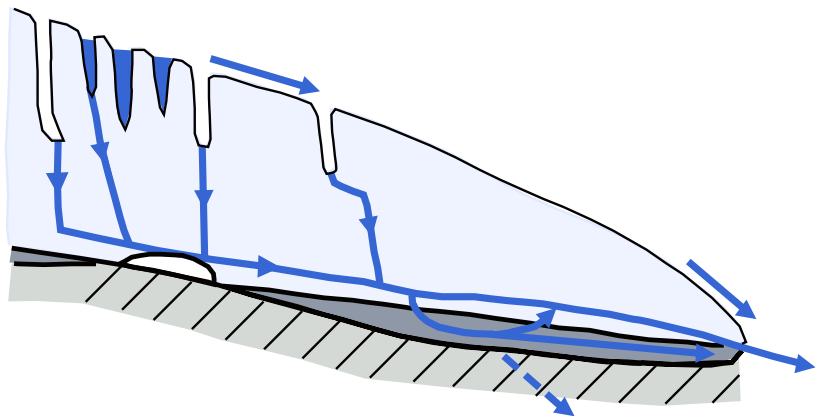
$$\underbrace{\phi}_{\text{hydraulic potential}} = \underbrace{p_w}_{\text{pressure potential}} + \underbrace{\rho_w g H}_{\text{elevation potential}}$$

For turbulent flow discharge is

$$q \propto -\sqrt{\nabla\phi}$$

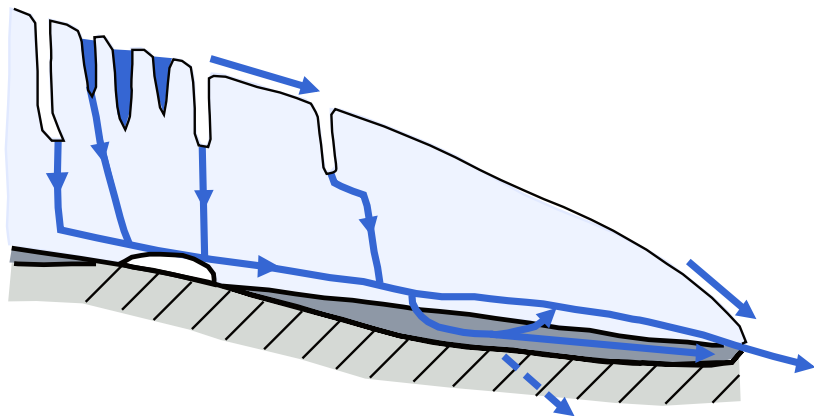
Water flow through a glacier

Cross-section of ablation area of glacier/ice sheet:



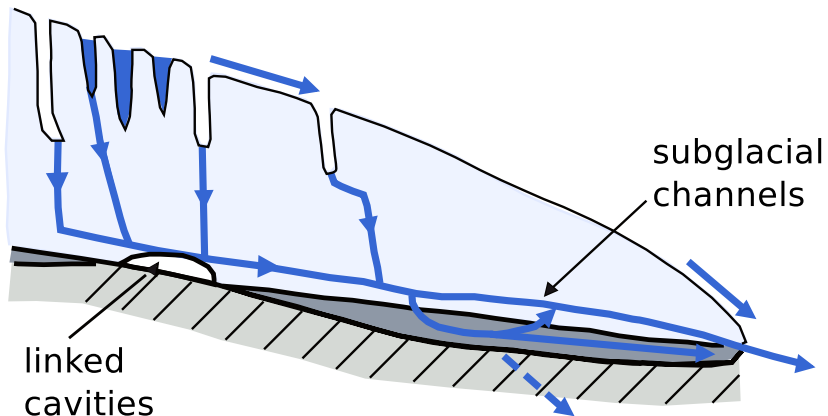
Water flow through a glacier

I'll focus on a **few components** of the drainage system,



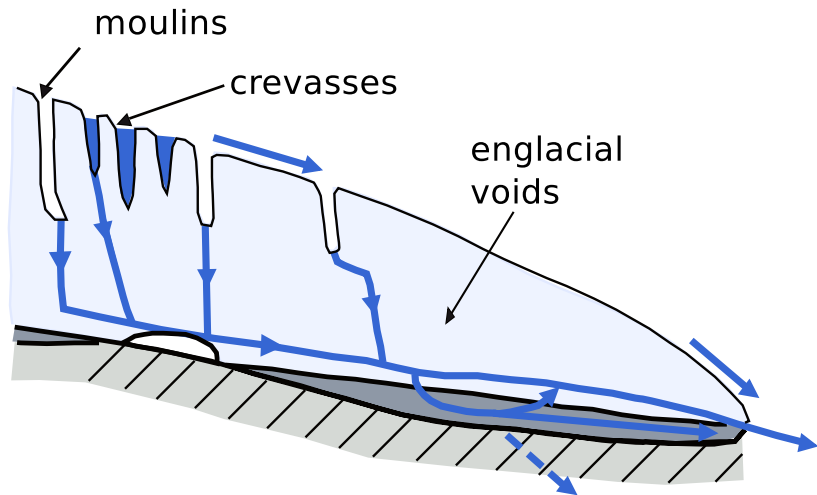
Water flow through a glacier

mainly on the **subglacial drainage** system



Water flow through a glacier

and a little on the **englacial drainage** system.



Model

This model

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This model = $\underbrace{\textit{sheet flow}}_{\text{linked cavities}}$

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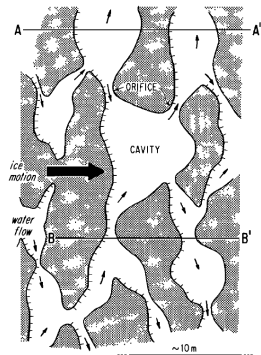
Two subglacial systems:

distributed: sheet flow

localized: R-channels

Sheet model

Porous sheet consisting of linked cavities:



Kamb 1987

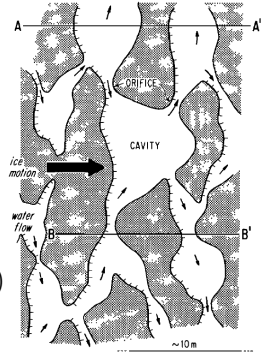
Sheet model

Porous sheet consisting of linked cavities:

mass conservation $\frac{\partial h}{\partial t} + \nabla \cdot \mathbf{q} = m$

turbulent flow $\mathbf{q} = -k_s h^\alpha |\nabla \phi|^{\beta-2} \nabla \phi$

opening and closure $\frac{\partial h}{\partial t} = v_{os}(u_b, h) - v_{cs}(\phi, h)$



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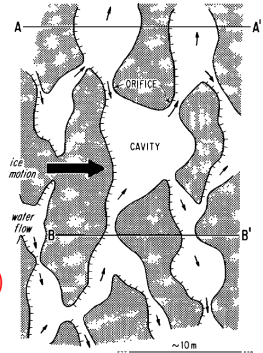
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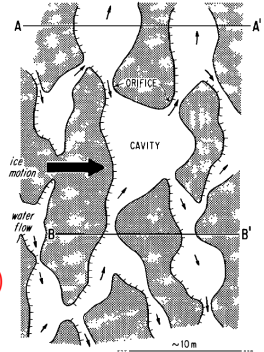
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→ elliptic equation for ϕ , ODE for h

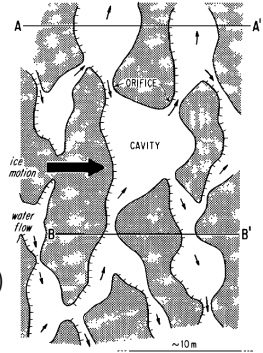
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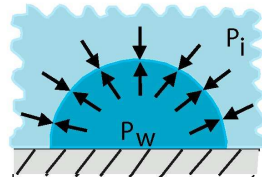
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Aside: u_b is the basal sliding velocity; with which two-way coupling to ice flow could be done (together with ϕ).

Channel model

Channels are modelled as R-channels:



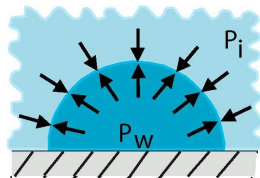
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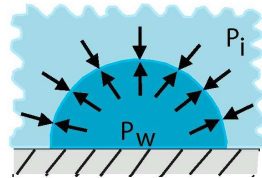
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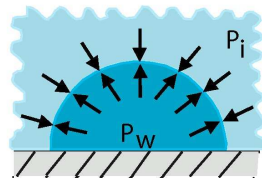
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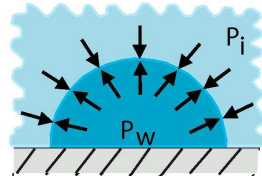
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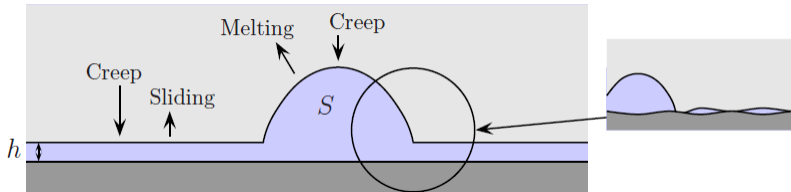
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Note that channels are 1-D creatures!

Channels vs sheet



Sheet opens by sliding
Channel opens by melt
Both close by creep

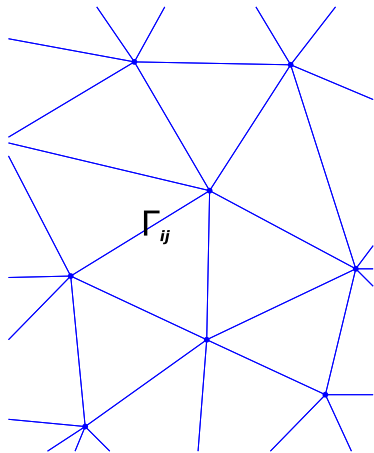
Coupled **2D** model

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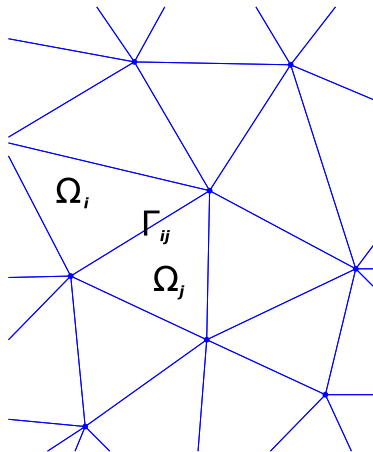
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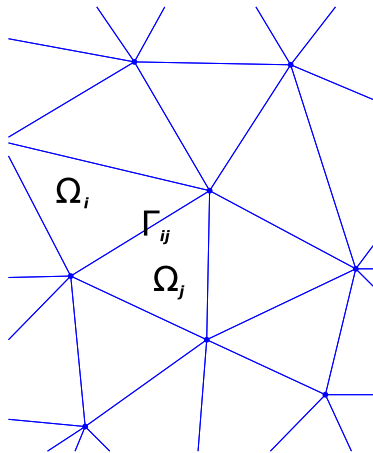
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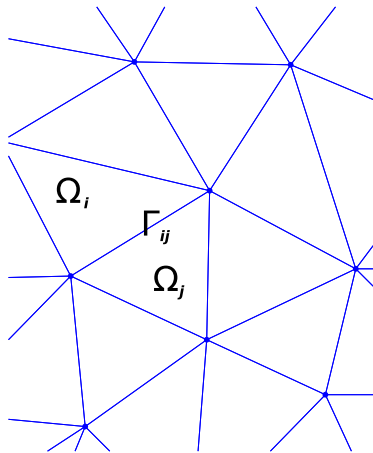
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Englacial storage

Observations show that a significant portion of water can be **temporarily stored** in a glacier, e.g., explaining the lag between peak surface melt and peak proglacial discharge.

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→ now ϕ equation parabolic

And the last bit: moulins

Surface meltwater often collects in streams and enters the glacier through moulins. Presumably each **moulin connects to a subglacial channel** and also has some associated (storage) volume.

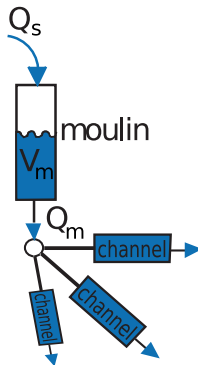
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Q_s surface input

V_m volume of water stored in moulin

Q_m discharge into channels



This concludes the description of the physical model

Numerics

Parabolic hydraulic potential (ϕ) equation solved:

- with finite elements
- on unstructured triangular mesh
(mesh = network of potential channels)
- backward Euler time step using hybrid Picard-Newton method

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Implemented in Matlab

- up to 20 000 total DOF, 8 000 ϕ DOF
- model runs ~ 10 min on laptop for 4000 DOF

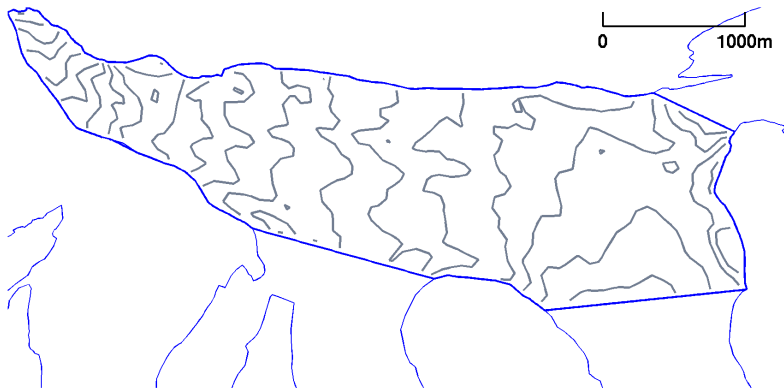
Real geometry: Gornergletscher

Model application to Gornergletscher, Switzerland



5 km by 1.5 km trunk
up to 400 m deep ice

Gornergletscher: Surface



Model domain with
surface elevation contours (interval 20m)

Gornergletscher: Bed



Bed elevation (contour interval 20m)

Run to steady state

Initial conditions

- Uniform sheet thickness = 5cm
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- sheet: uniform 0.3m/day ($\approx 20\text{m}^3/\text{s}$ total)
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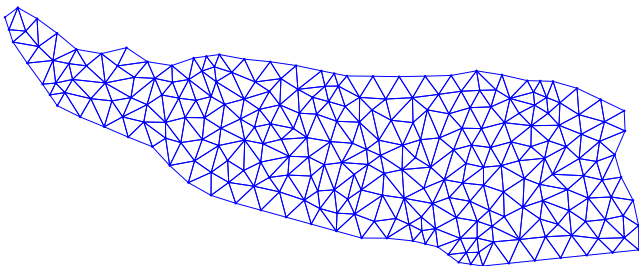
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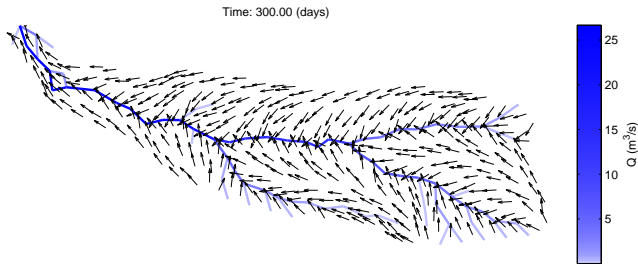
Example coarse mesh

Example (coarse) mesh with ~ 1000 DOF produced with Triangle



Example output

We'll be looking at animations of this form



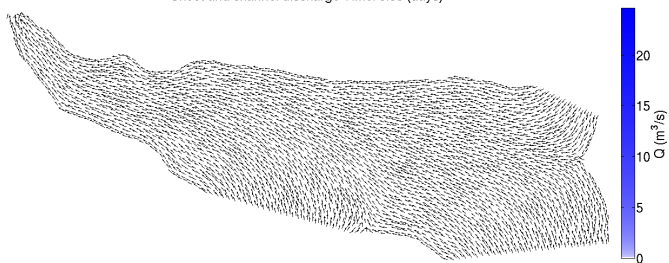
Blue edges:
channel discharge

Arrows:
flow direction in sheet

Run to steady state

Channel and sheet discharge

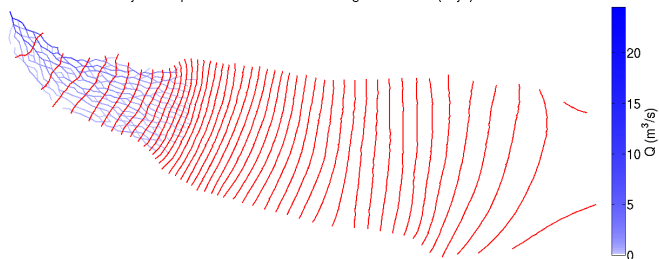
Sheet and channel discharge Time: 0.00 (days)



Run to steady state

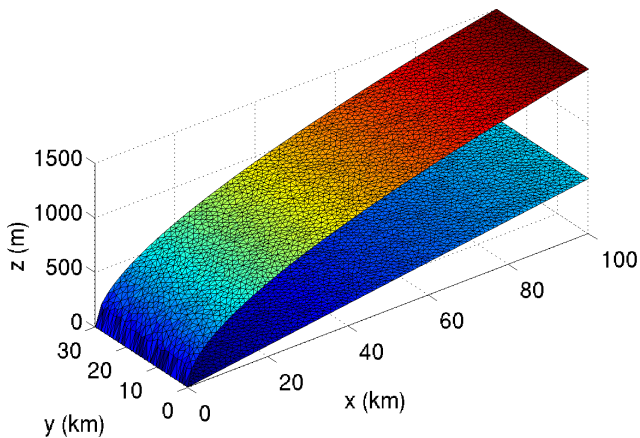
Channel discharge and contours of ϕ

Hydraulic potential and channel discharge. Time: 5.27 (days)



Model run on a square ice sheet catchment

Model application to 100x30km square ice sheet margin.



Topography

Model run on a square glacier

IC

Uniform sheet thickness = 5cm

Channel diameters = 0m

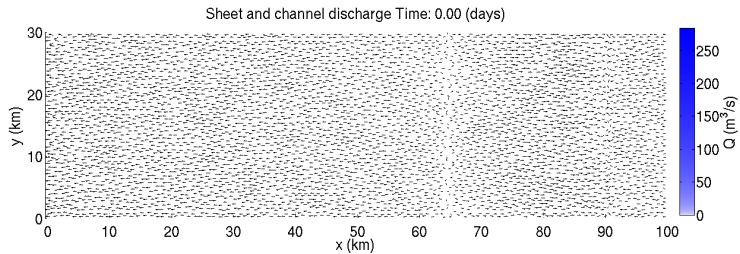
No storage

Sources

Sheet: input with lapse rate
(0.14-0.0m/day $\approx 1400\text{m}^3/\text{s}$ total)

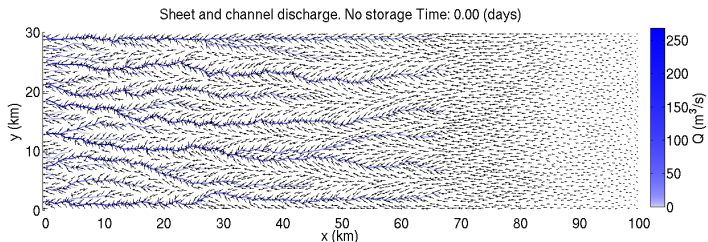
Channels: no input

Water flow



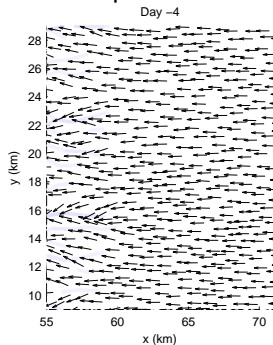
Switching on a moulin

Here a moulin is switched on ($50 \text{ m}^3/\text{s}$) draining into a steady state drainage system.



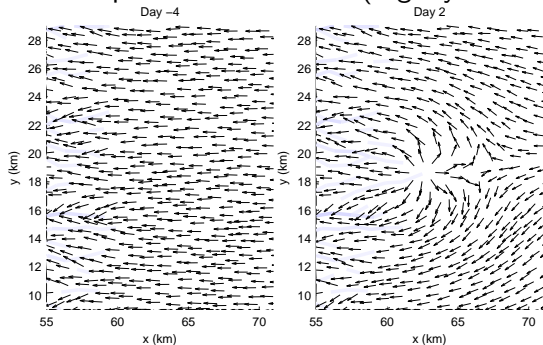
Switching on a moulin

Zoomed plots around moulin (slightly different run):



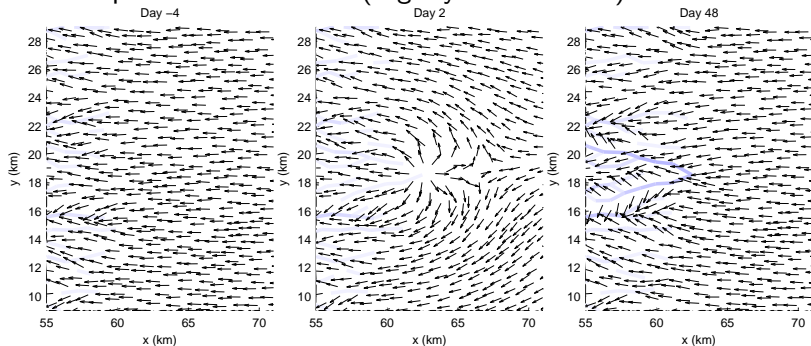
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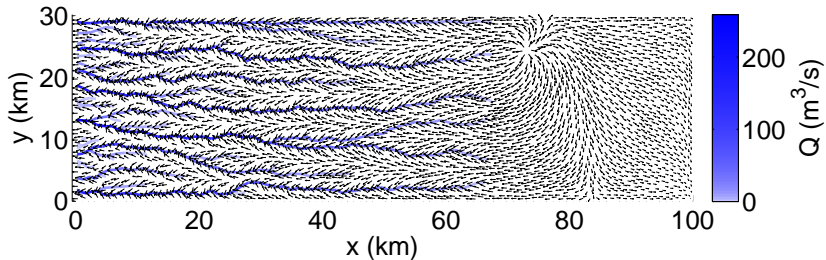


Storage

The “spooky action at a distance” when switching on the moulin is a reason to have storage.

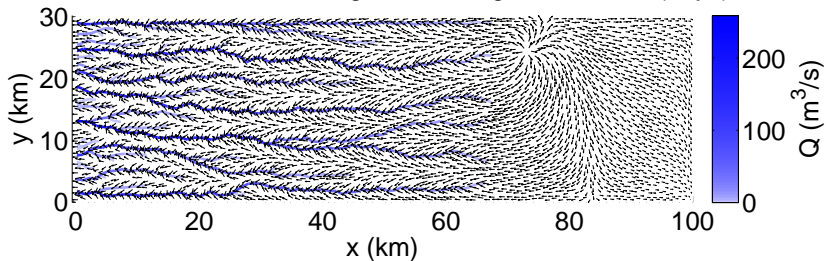
Storage: moulin switch

Sheet and channel discharge. No storage Time: 4.13 (days)

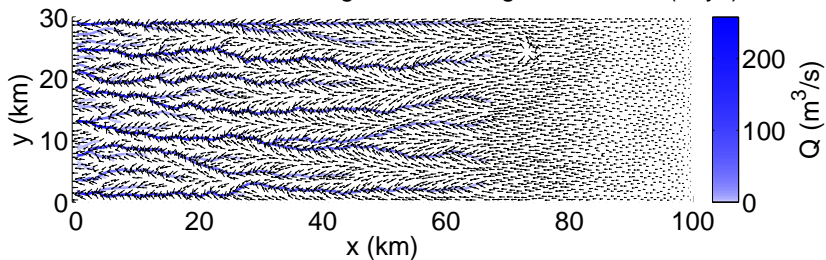


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Sheet and channel discharge. No storage Time: 4.13 (days)



Sheet and channel discharge. With storage Time: 4.25 (days)



Storage: diurnal meltwater forcing

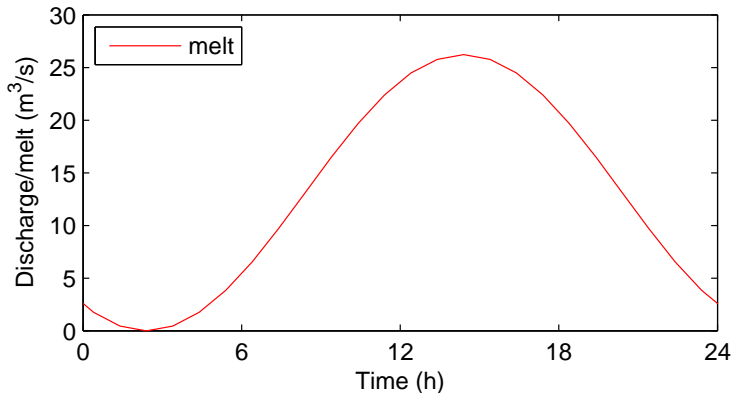
Observations show a **lag** between peak surface **melt** and peak proglacial **discharge**.

Storage: diurnal meltwater forcing

The model can reproduce this lag between melt and proglacial discharge **with the storage term**

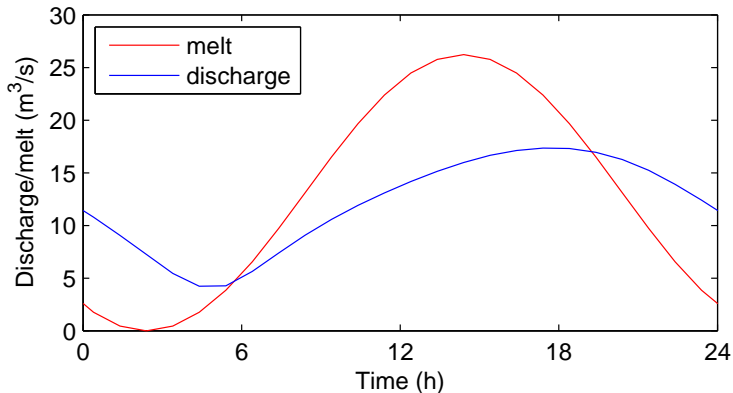
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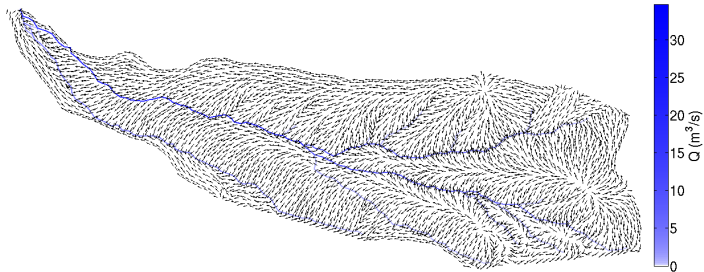
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Storage: diurnal meltwater forcing

Animation of what the hydraulic potential does:

Hydraulic potential and channel discharge. Time: 0.00 (days)



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Outlook

- Test it thoroughly: convergence, statistics of channels
- Explore parameters
- Add external model components: melt model, supraglacial water routing, etc.
- Rewrite of model in faster language
- Inclusion of subglacial lakes
- Model validation with Gornergletscher observations
- Application to ice sheet catchments
- Coupling to ice flow model: CISM

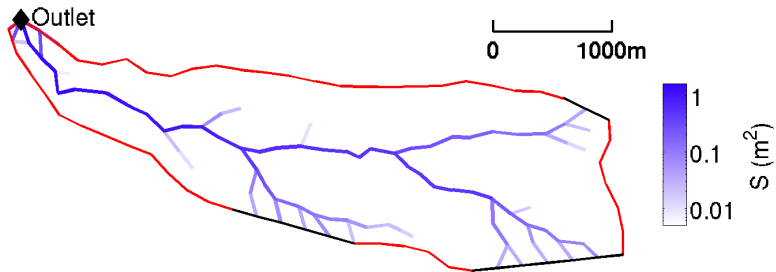
Does the model converge

Question:

Does the predicted location of channels converge when the mesh is refined?

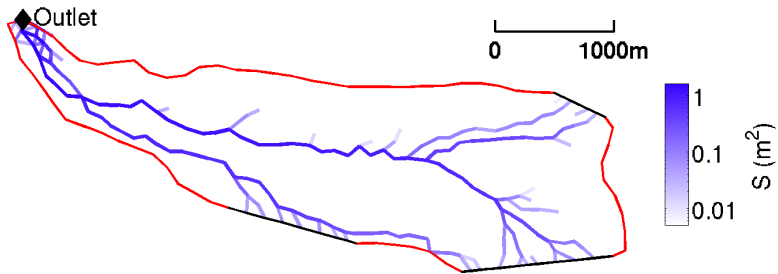
(Other types of convergence of course also interesting.)

Steady state channels



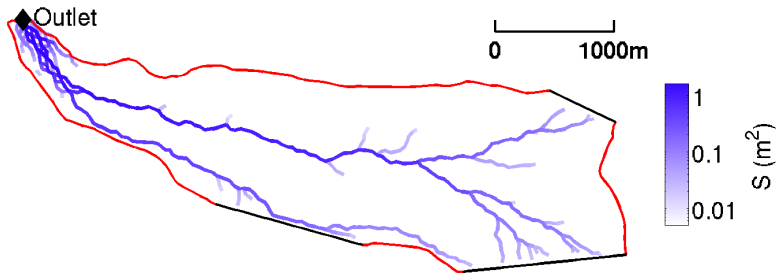
Mesh: 444 elements, 700 edges

Steady state channels



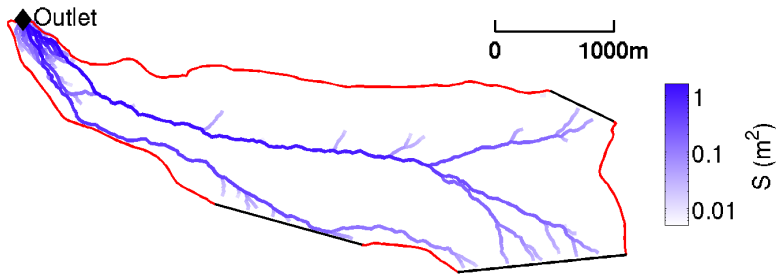
Mesh: 935 elements, 1458 edges

Steady state channels



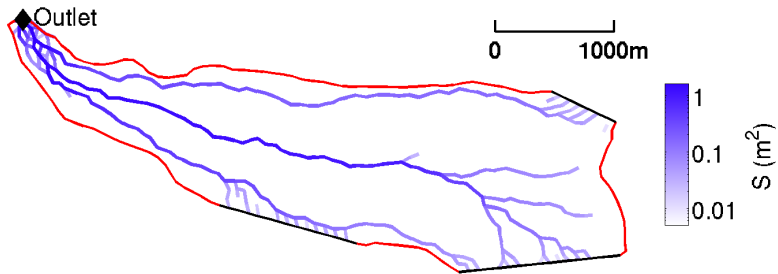
Mesh: 4502 elements, 6878 edges

Steady state channels



Mesh: 8933 elements, 13574 edges

Steady state channels



Mesh: 2203 elements, 3382 edges Northern channel different!

Summary of equations

Standard equations describing linked cavity sheet and R-channels:

	Sheet	R-channels
Mass conserv.	$\frac{\partial h}{\partial t} + \nabla \cdot \mathbf{q} = m$	$\frac{\partial S}{\partial t} + \frac{\partial Q}{\partial s} = \frac{\Xi}{\rho_w L} + m_C$
Turbulent flow	$\mathbf{q} = -k_s h^\alpha \nabla \phi ^{\beta-2} \nabla \phi$	$Q = -k_C S^\alpha \left \frac{\partial \phi}{\partial s} \right ^{\beta-2} \frac{\partial \phi}{\partial s}$
Time evolution	$\frac{\partial h}{\partial t} = v_{os} - v_{cs}$	$\frac{\partial S}{\partial t} = \frac{\Xi}{\rho_i L} - v_{cC}$
Opening	$v_{os}(u_b, h) \propto u_b(h_r - h)$	$\Xi(\nabla \phi, S) = \left Q \frac{\partial \phi}{\partial s} \right + l_r \mathbf{q} \cdot \nabla \phi $
Closure	$v_{cs}(N, h) \propto h N ^{n-1}N$	$v_{cC}(N, S) \propto S N ^{n-1}N$

Steady state for different meshes

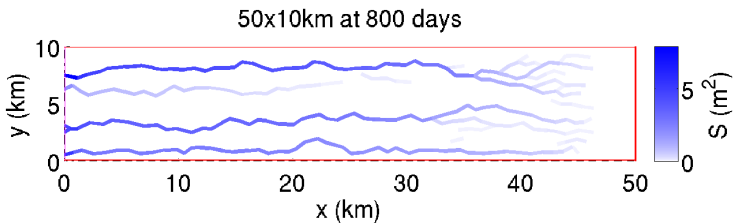
Does the model reach a comparable steady state for different meshes?

Steady state for different meshes

Does the model reach a comparable steady state for different meshes?

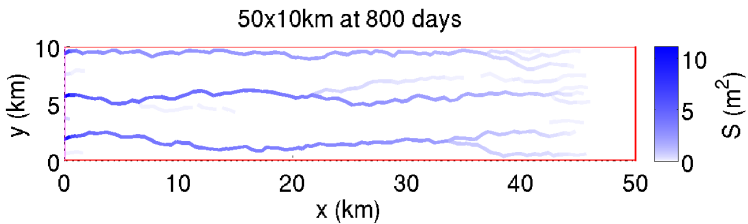
In particular for the channels?

Steady state for different meshes



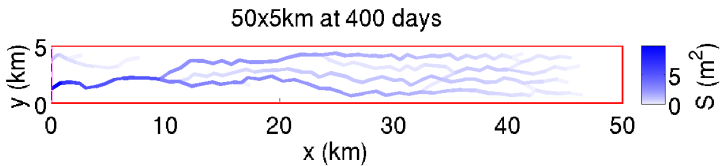
Mesh: 1269 elements, 1969 edges

Steady state for different meshes



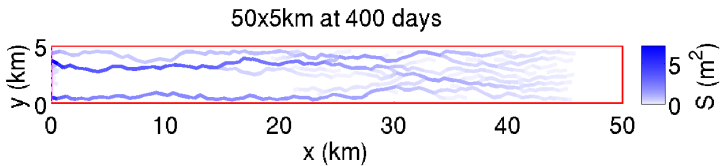
Mesh: 3189 elements, 4889 edges

Steady state for different meshes



Mesh: 635 elements, 1014 edges

Steady state for different meshes



Mesh: 1639 elements, 2557 edges

Steady state for different meshes

Looks ok: all have ~ 1 channel per 3km width.