

# Complexity in Sea-Ice Deformation and Morphogenesis — Observations, Analysis and Implications for Modeling

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## Thanks to my collaborators and students ...

**Geomath Team:** Brian McDonald, Phil Chen, Bruce Wallin (now NMTech), Ian Crocker, Maciej Stachura, Alex Weltmann, Lance Bradbury, Alex Yearsley, Griffin Hale, SeanOGrady

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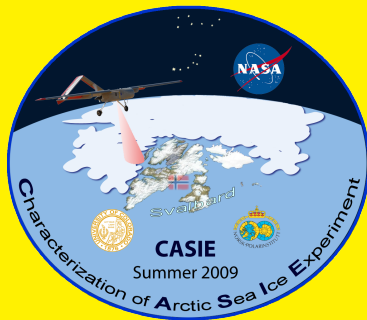
**CASIE and SeaiCEIPY:** James Maslanik (CCAR, CU Boulder), Ron Kwok (JPL), John Heinrichs (Ft. Hays State Univ, KS), David Long (BYU Provo), Matt Fladeland and SIERRA Team at NASA Ames Res Center  
Al Gasiewski (ETL, ECE, CU Boulder), Michael Kuhn (U Innsbruck), David Korn (NSIDC)

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- ▶ NASA Cryospheric Sciences
- ▶ NASA ICESat-2 Project
- ▶ NASA AMES Research Center
- ▶ University of Colorado UROP Program

## Avenues for contributions to improving sea-ice modeling in CESM

- (1) **Statistics and Geomathematics:** Approaches to capture complex spatio-temporal phenomena; scaling; parameterization of (subscale) physical phenomena for model input
- (2) **Observations:** Data and data analysis of sea-ice characteristics from satellite and airborne campaigns



Survey campaigns and satellite missions

→ tiers of observations

SCALE

# Objectives

## Cryospheric science objective:

Detect and quantify different forms of change in the cryosphere and attribute changes to sea-ice-morphogenetic processes

## Remote-sensing objective:

Present and analyze observations from new instruments (GLAS (ICESat), ICESat-2, UA laser profilometer, SAR, microSAR)

## Geomathematical objective:

– Realize new methodological components for spatial structure analysis  
– Identify, characterize and classify forms from hidden information in

- (a) Undersampled situations
- (b) Oversampled situations

# APPROACH

## Using Geomathematics to Connect Science and Engineering

- ← Understanding Environmental Change through Geomathematical Analysis of Remote-Sensing Data
- Applying Spatial Statistics to Design Cryospheric Observations, Instrumentation, Satellite, Airborne and Field Campaigns

# Measurement objective:

Development of instrumentation to survey (Micro-)topography and roughness of ice surfaces

- (1) Glacier Roughness Sensor (GRS)
- (2) UAV Laser Profilometer  
(UAV- Unmanned Aerial Vehicle)

Contribution to new Satellite and Airborne Observation Technology

- (1) ICESat-2
- (2) MABEL
- (3) SIGMA (data analysis)
- (4) CryoSat2





Rubbled Ice (March 2003) (J. Maslanik photo)



Beaufort Sea, Ridge (March 2003) (J. Maslanik photo)

## Objectives of Ice Classification

- (1) Characterization of ice provinces: Establish a unique quantitative description of each ice type
- (2) Classification: Assign a given object to a surface class, using the characterization
- (3) Segmentation: Create a thematic map by applying the classification operator in a moving window

## Transfer to Modeling

- (1) Parameterization of spatial sea-ice properties, based on characterization
- (2) Summarize properties of ice types, based on classification
- (3) Simplify regional ice-type distributions for model input at larger/ regional scale, based on segmentation

## Examples of Applications to Arctic Sea Ice

- (1) CASIE 2009: Passive and active microwave observations from unmanned aircraft to characterize sea ice properties and their changes in the FRAM Strait
- (2) Roughness length and ice types
- (3) Ice provinces as reflected in ICESat Geoscience Laser Altimeter System (GLAS) data and Airborne Topographic Mapper (ATM) data
- (4) Classification of sea-ice provinces

# CASIE Experiment 2009

## Fram Strait

CASIE – Characterization of Arctic Sea Ice Experiment

July/ August 2009 from a base in Nye Alesund, Svalbard

Objective: Collection of high-resolution microtopographic and roughness data

SIERRA UAV, NASA AMES Research Center: Matthew Fladeland and collaborators

Experiment science: Jim Maslanik (P.I.), Ute Herzfeld (Co-I.), David Long (Co-I.), R. Kwok (Co-I.), Ian Crocker, K. Wegrezyn

NASA IPY sea-ice roughness project: J. Maslanik, U. Herzfeld, J. Heinrichs, D. Long, R. Kwok



NASA AMES SIERRA: Cold-Weather System Test with CU-ULS (March 2009)  
photograph by Don Herlth

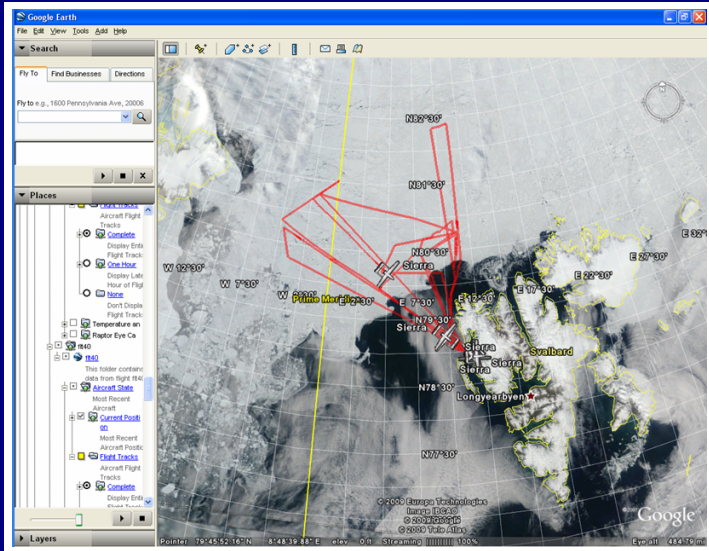


BYU mSAR panels integrated in SIERRA



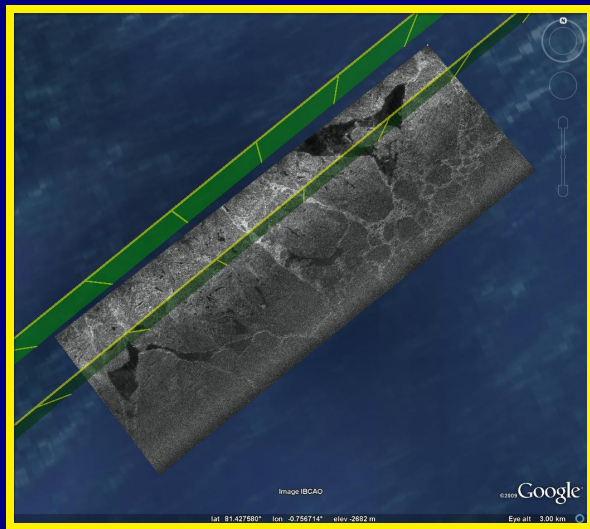
NASA AMES SIERRA: Ny Alesund, Svalbard  
photograph by Ian Crocker





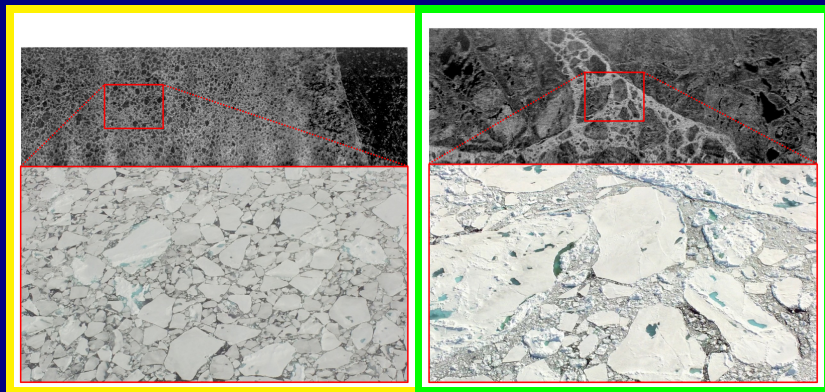
flight tracks

# Data Acquisition CASIE (Fram Strait): ULS and MicroSAR (July 2009)



## (2) Roughness length and ice types

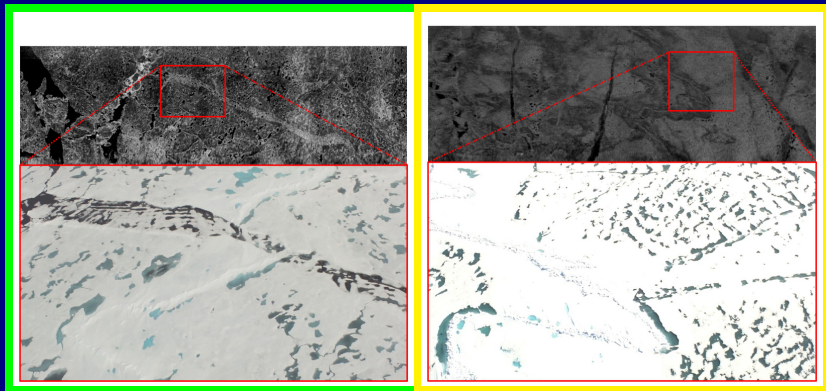
# Sea Ice Types — Fram Strait, from CASIE 2009



(a) near ice edge

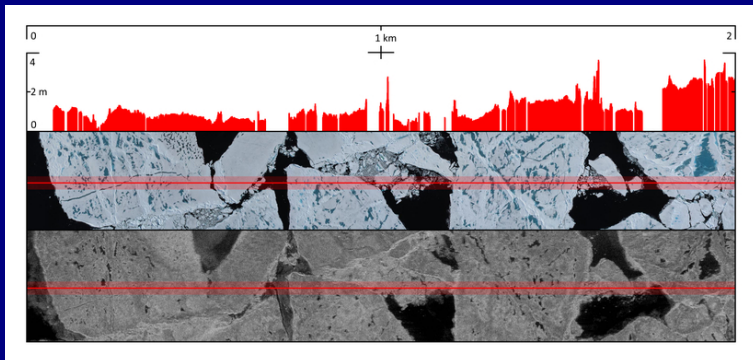
(b) rubble – lead – floes

# Sea Ice Types — Fram Strait, from CASIE 2009



(c) refrozen lead

(d) flooded floes - ridging



Laser altimeter data, videographic data and microASAR data from CASIE

# Analysis approach: Spatial surface roughness

## (1.) What is spatial surface roughness?

- ▶ a derivative of (micro)topography
- characterization of spatial behavior

## (2.) Why do we need surface roughness?

- ▶ morphologic characteristics are captured in surface roughness (**not** in absolute elevation)
- ▶ subscale information for satellite data

## (3.) How do we measure surface roughness?

- ▶ Glacier Roughness Sensor (land ice)
- ▶ A UAV with laser profilometer

## (4.) How do we analyze surface roughness?

The analytically defined spatial derivative needs to be calculated numerically from a data set.

One way to do this:

$$\lim_{x \rightarrow x_0} \frac{z(x_0) - z(x)}{x_0 - x}$$

surface slope in a given location  $x_0$

To characterize morphology, better use averages...



# Definition of Vario Functions

$$V = \{(x, z) \text{ with } x = (x_1, x_2) \in \mathcal{D} \text{ and } z = z(x)\} \subseteq \mathcal{R}^3$$

discrete-surface case or

$$V = \{(x, z) \text{ with } x \in \mathcal{D} \text{ and } z = z(x)\} \subseteq \mathcal{R}^2$$

discrete-profile case

Define the **first-order vario function**  $v_1$

$$v_1(h) = \frac{1}{2n} \sum_{i=1}^n [z(x_i) - z(x_i + h)]^2$$

with  $(x_i, z(x_i)), (x_i + h, z(x_i + h)) \in \mathcal{D}$  and  $n$  the number of pairs separated by  $h$ .

# Higher-Order Vario Functions

The **first-order vario-function set** is

$$V_1 = \{(h, v_1(h))\} = \underline{v}(V_0)$$

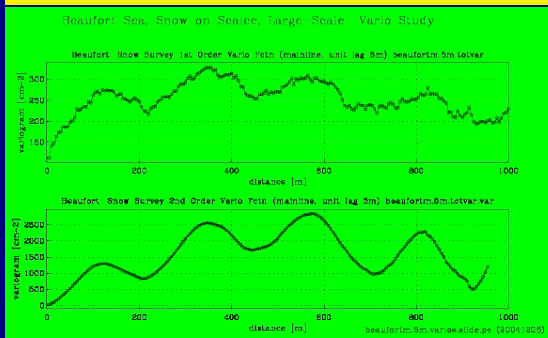
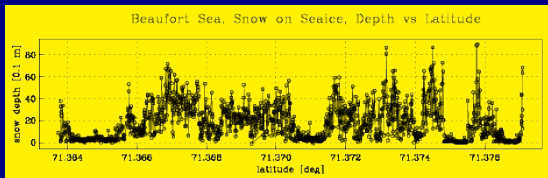
Then: get  $V_2$  from  $V_1$  in the same way you get  $V_1$  from  $V_0$ . The second-order vario function is also called **varvar function**.

Recursively, the **vario function set of order  $i + 1$**  is defined by

$$V_{i+1} = \underline{v}(V_i)$$

for  $i \in \mathcal{N}_0$ .

# Beaufort Sea



# Geostatistical Classification Parameters

significance parameters:

slope parameter:

$$p1 = \frac{\gamma_{max_1} - \gamma_{min_1}}{h_{min_1} - h_{max_1}}$$

relative significance parameter:

$$p2 = \frac{\gamma_{max_1} - \gamma_{min_1}}{\gamma_{max_1}}$$

pond – maximum vario value

mindist – distance to first min after first max

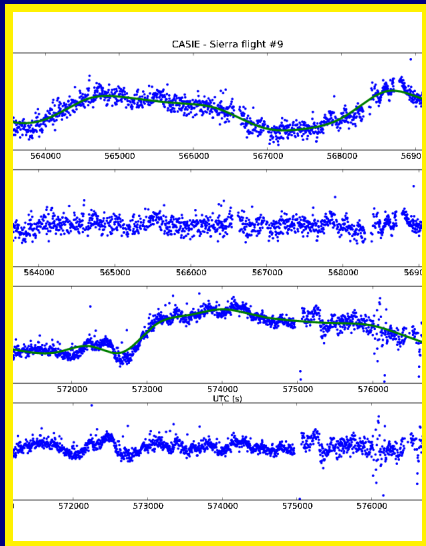
$$avgspac = \frac{1}{n} \sum_{i=1}^n \frac{1}{i} h_{min_i}$$

typically for  $n = 3$  or  $n = 4$

Roughness length approximation:

$$arl = \frac{1}{2} \sqrt{2pond}$$

## Laser altimeter data — correction method



### Correction ingredients

- (1) 1 Hz GPS data, collected on-board SIERRA
- (2) cubic splines to correct for longer range aircraft motion
- (3) altimetry / geolocation residuals wrt to fitted splines

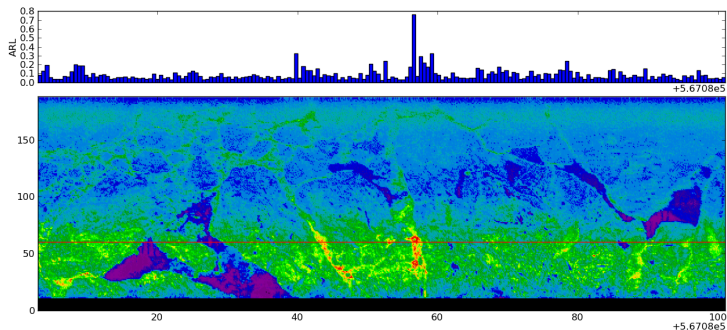
Shown at left: 2 segments with double tracks, altimetry over microASAR

Top: Segment 1, Flight 9

Bottom: Segment 2, Flight 9

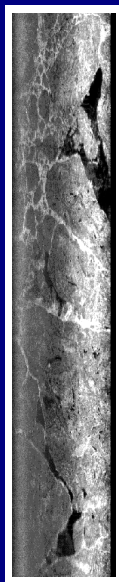
2009-07-25

# ARL from altimetry and matching microASAR data

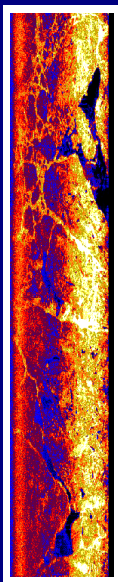


Segment 1 (msar104), Flight 9, 2009-07-25, CASIE 2009

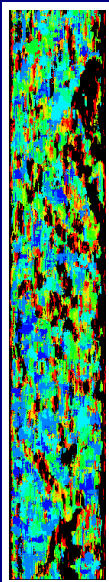
# BYU MicroSAR data and roughness parameters



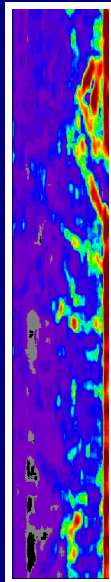
mSAR



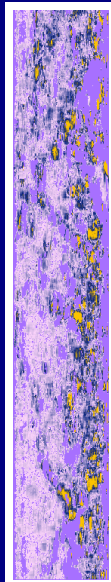
mSAR



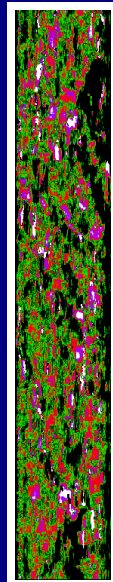
mindist



pond



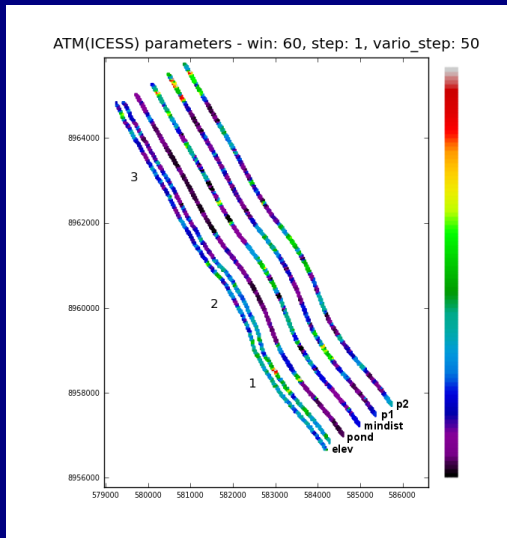
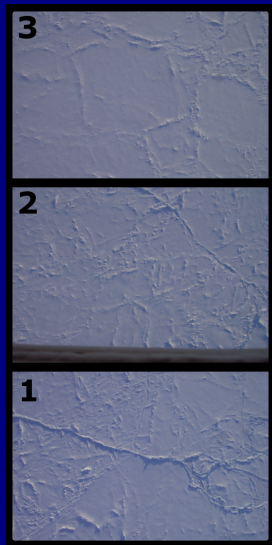
p1



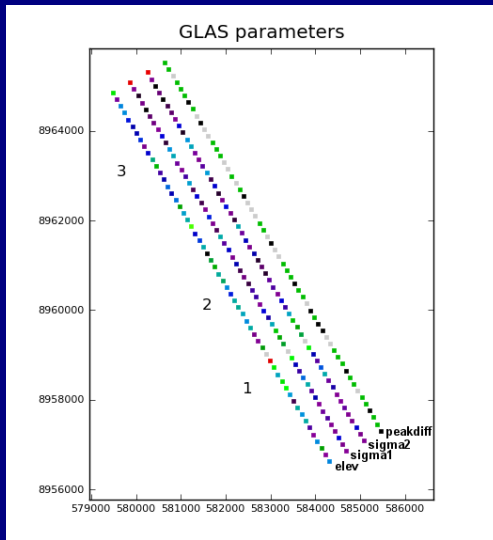
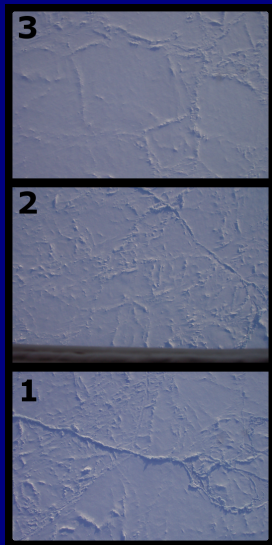
p2



# Surface characterizations derived from March 2006 ATM - ICESat underflight over Arctic sea ice



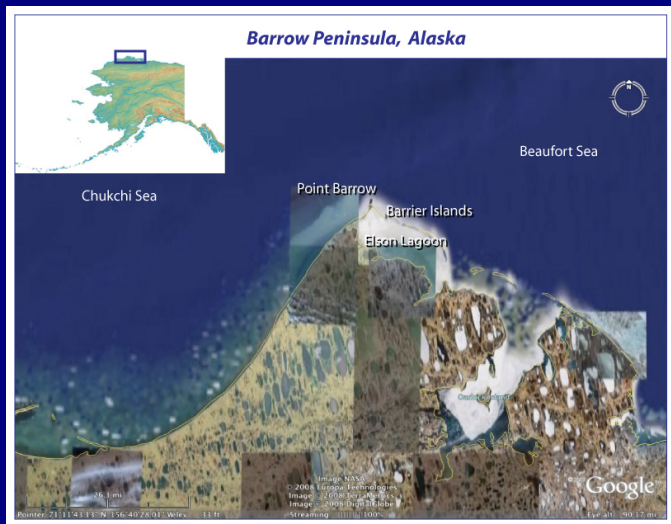
# Surface characterizations derived from March 2006 ATM - ICESat underflight over Arctic sea ice



Example (4): Classification of sea-ice provinces

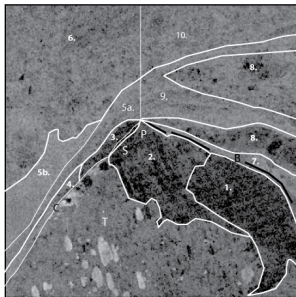
Mapping of spatial properties of sea ice and sea-ice classification  
for larger areas

# Study areas near Point Barrow, Alaska: Chukchi Sea, Beaufort Sea and Elson Lagoon



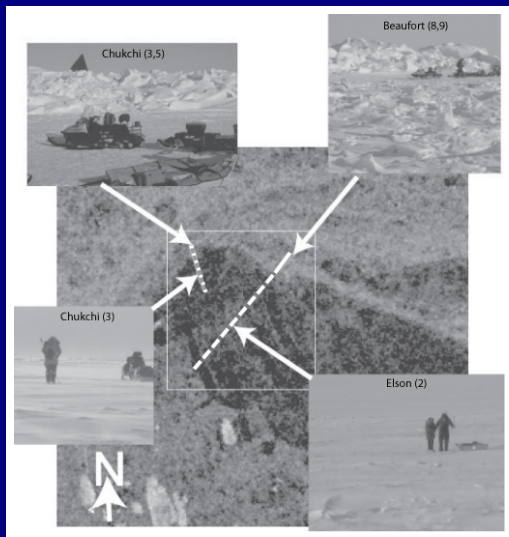
# Sea Ice Types Near Point Barrow, Alaska: SAR Data

Sea Ice Types Near Point Barrow, Alaska

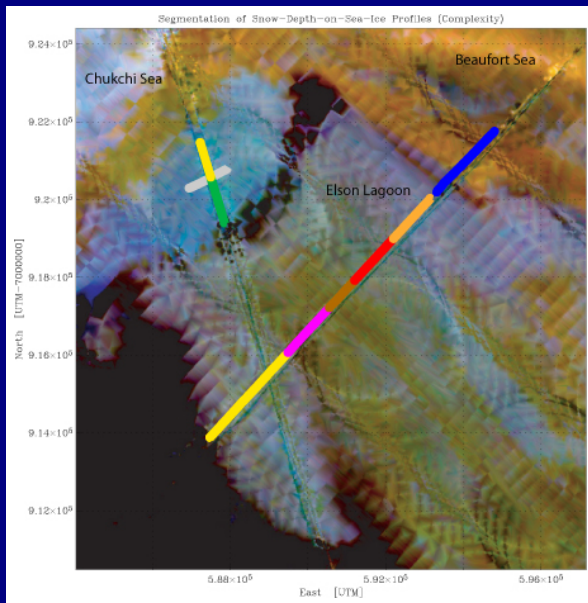


- 5. Barrow Spit
  - C. Coast
  - T. Tundra with Lakes
  - B. Barrier Islands
  - 1. Elson Lagoon, smooth ice
  - 2. Elson Lagoon, smooth ice with small structures
  - 3. Chukchi Sea, near-shore very smooth ice
  - 4. Chukchi Sea, near-shore smooth ice
  - 5. Chukchi Sea, stamukhi zone (grounded ice), a. large ridge bordering very smooth near-shore zone, b. uniformly ridged ice
  - 6. Chukchi Sea, mixed structures, mostly older ice in drifting ice pack
  - 7. Beaufort Sea, zone of large ridges bordering Barrier Islands
  - 8. Beaufort Sea, small-scale rubbled ice
  - 9. Beaufort Sea, striated flows of ridged ice shearing off of Pt. Barrow drifting east
  - 10. Beaufort Sea, mixed structures, mostly older ice in drifting ice pack
- Field observations in areas 1, 2, 3, and 7

# Sea Ice Types Near Point Barrow, SAR Data and Photos

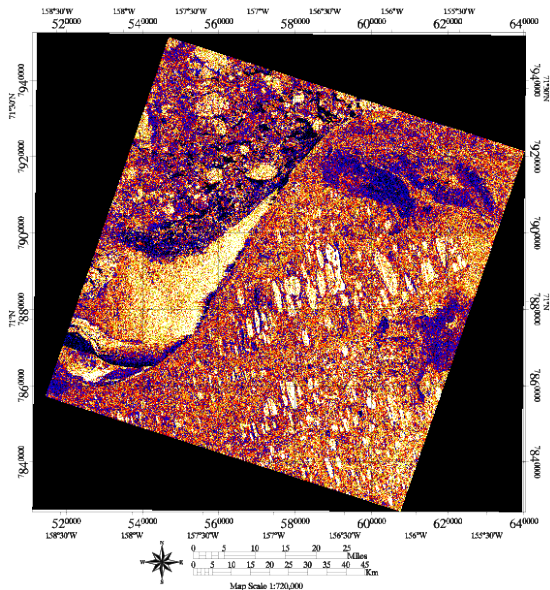


# Sea Ice Classification: PSR and Field Data (Snow Depth)



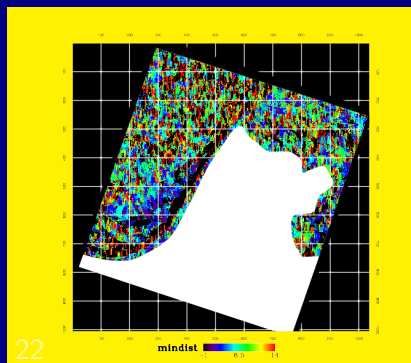
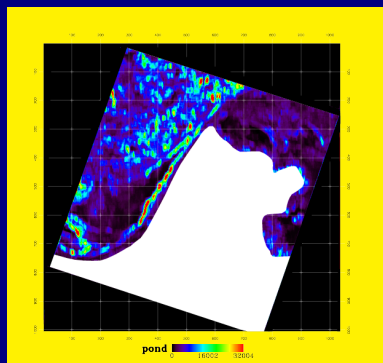
from  
Herzfeld, Maslanik  
and Sturm,  
IEEE TGRS 2006

# Sea Ice Classification: SAR Data



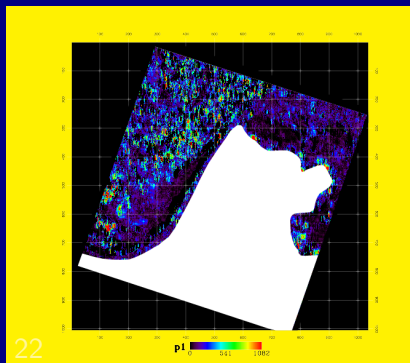
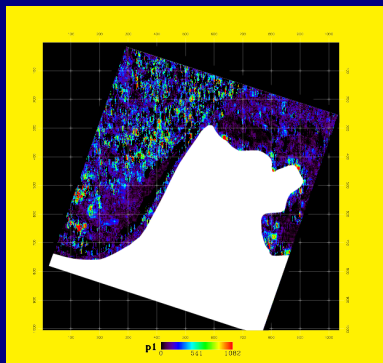


# parameter maps: pond and mindist

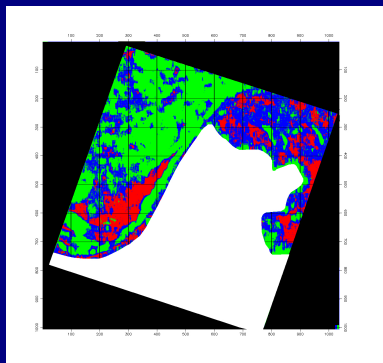


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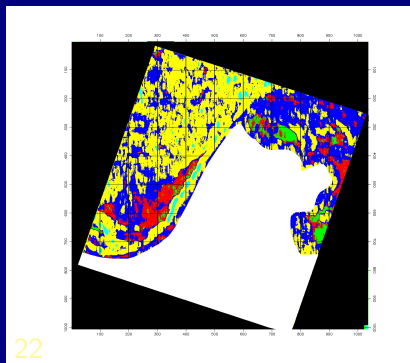
# parameter maps: p1 and p2



# statistical-geostatistical supervised classification: maximum-likelihood criterion



3 classes



22

5 classes

Herzfeld, Williams, Heinrichs, Maslanik, Sucht, JMG, in press 2010

## New Project:

Realization of transfer between

(A) Earth observation and data analysis

(B) modeling: CICE

through parameterization of ridges in sea ice

— collaboration with Elizabeth Hunke, LANL

# Questions?

