

# Estimation and Propagation of Errors in Ice Sheet Bed Elevation Measurements

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14 February, 2012  
Boulder, CO

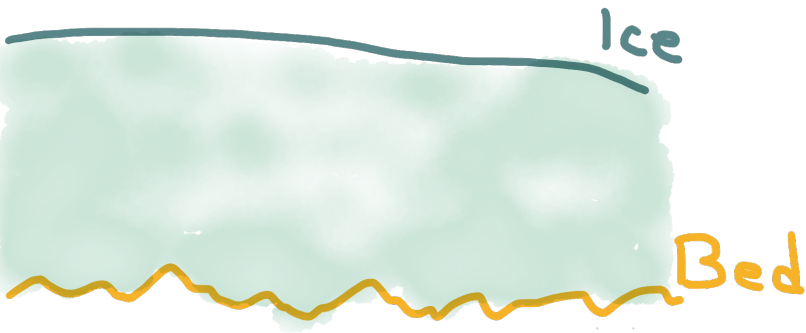
# Problem Statement



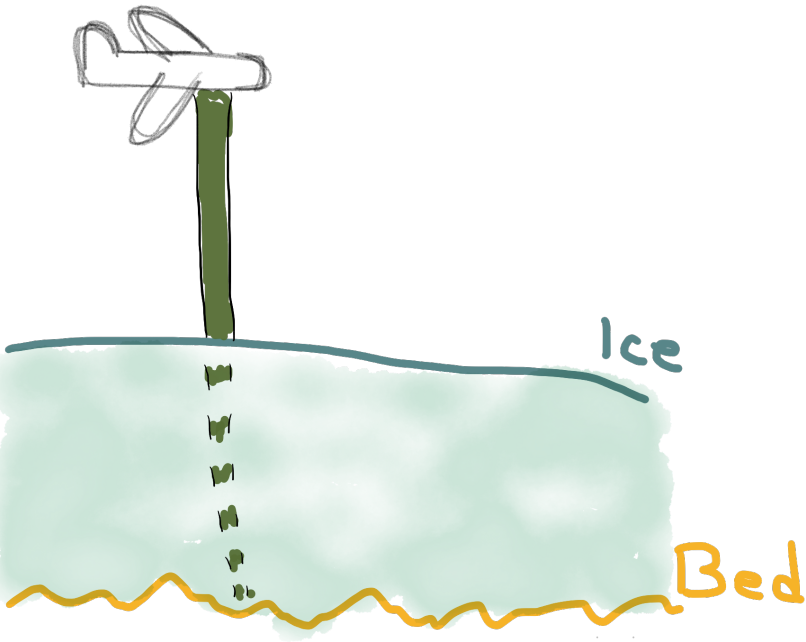
# Problem Statement



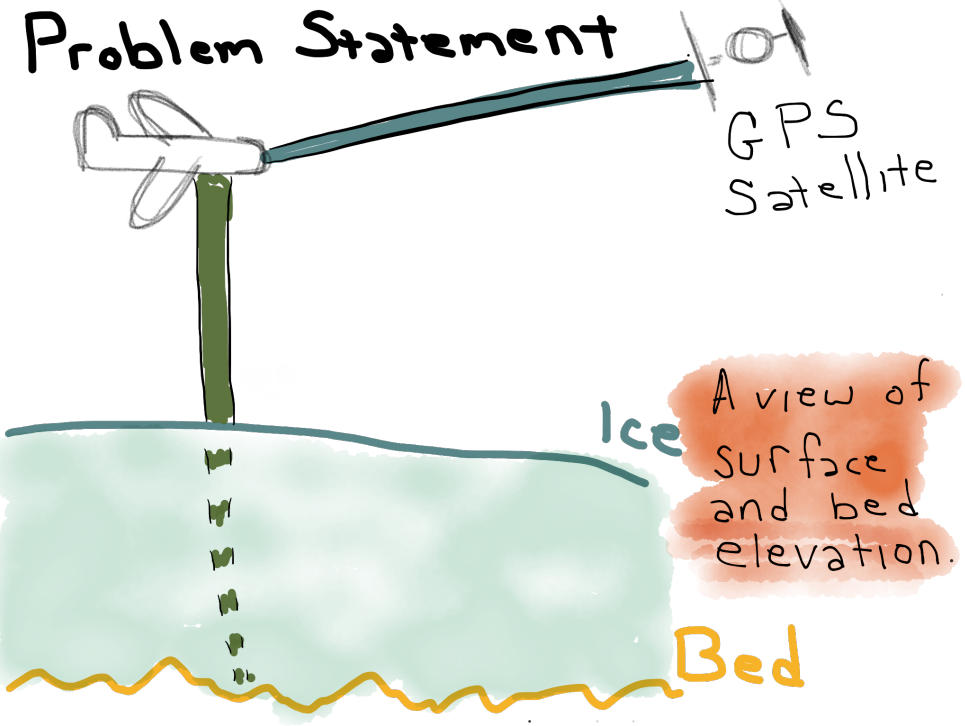
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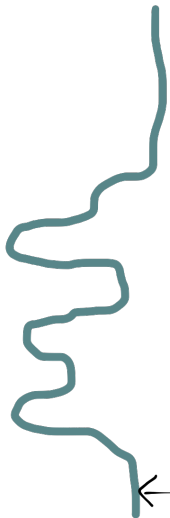


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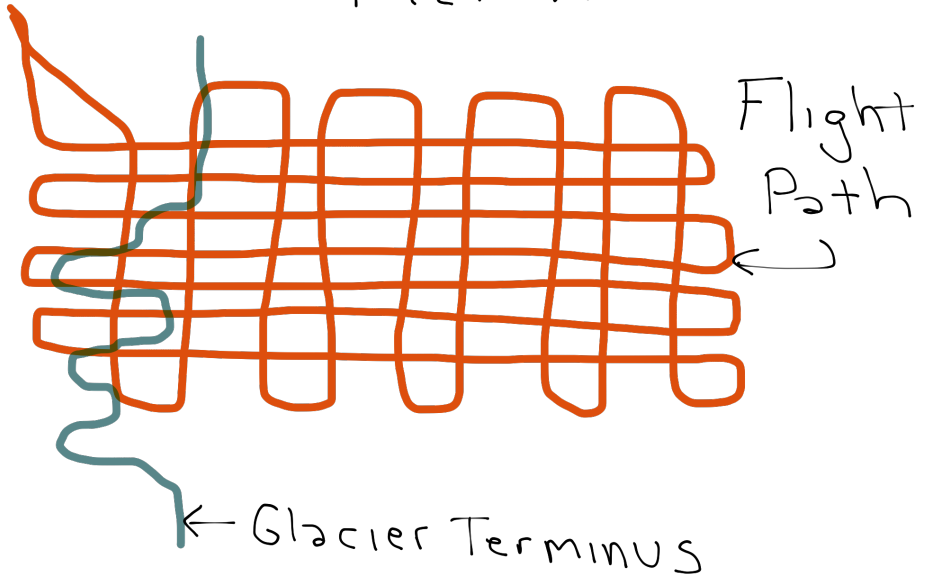
Plan View



← Glacier Terminus

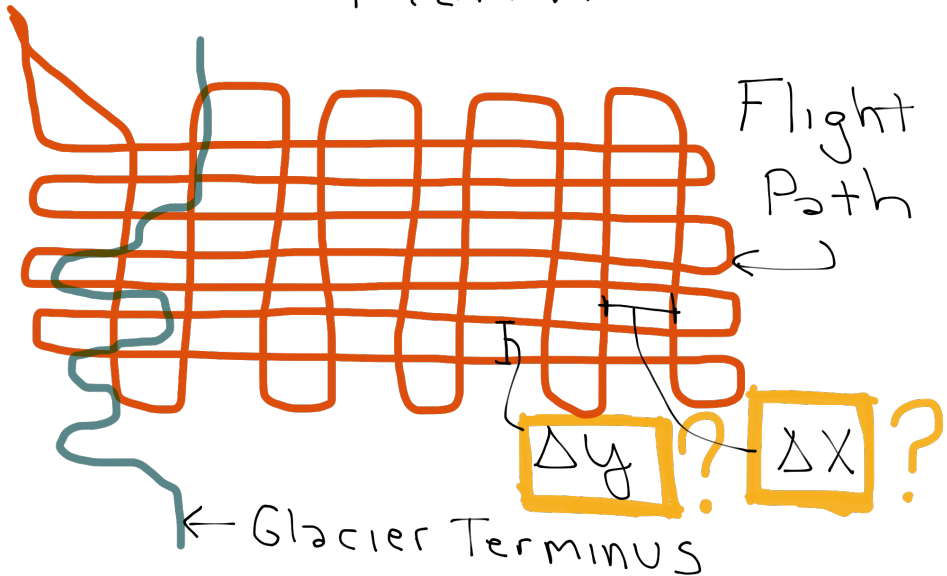
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Plan View

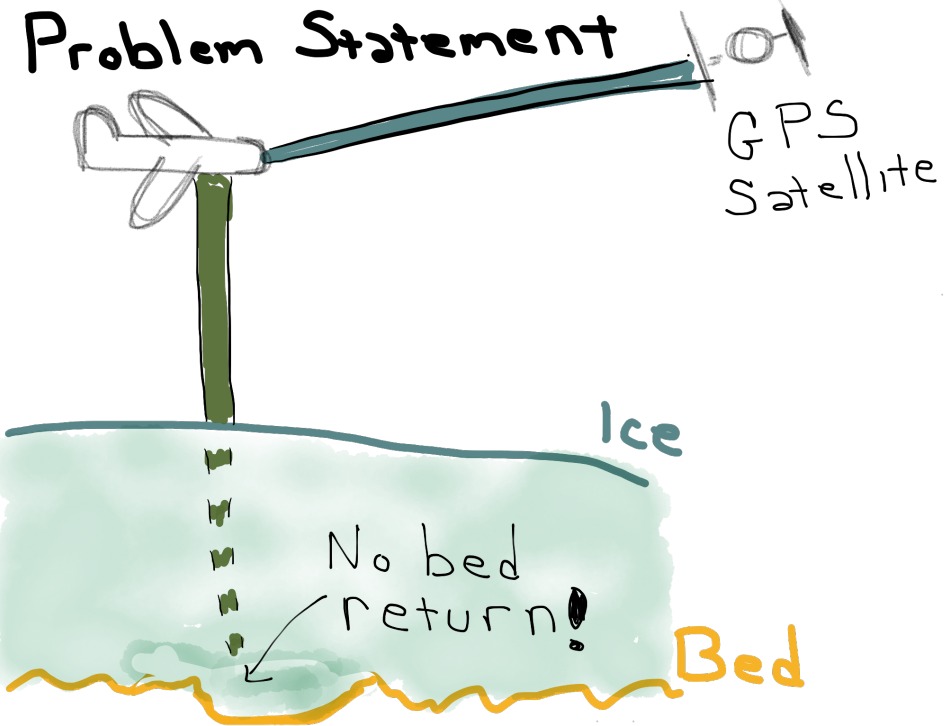


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Plan View



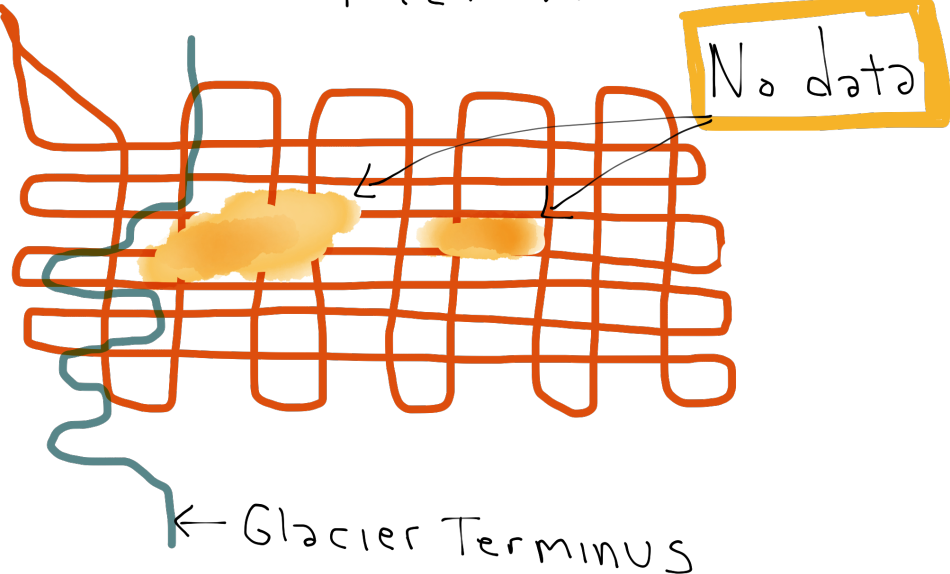
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## Plan View

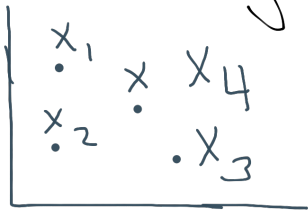


Goal: Estimate values between flightlines and in coverage gaps.

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Interpolation:

$$f(x) = \sum_{i \in \text{data}_2} w_i f(x_i)$$

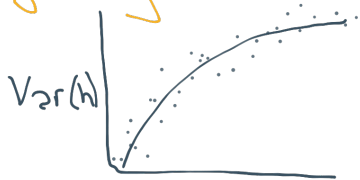


Inverse distance weighting

$$w_i = 1/d_i$$

Kriging

$$w_i \leftarrow \text{VARIogram } h$$



Goal: Estimate values between flightlines and in coverage gaps.

Mass Conserving Bed

Continuity Equation:

$$\frac{\partial H}{\partial t} = -\nabla \cdot (\vec{U}H) + \dot{a}$$

$H$  = thickness

$\vec{U}$  = velocity

$\dot{a}$  = accumulation /  
ablation

Mass Conserving Bed observed

$$\frac{\partial H}{\partial t} = -\nabla \cdot (\bar{u} H) + \dot{a}$$

solved for

What about the flight lines, where  $H$  is known? Call this  $H_0$

Variational Form:

$$I = \int \left[ \frac{1}{2} (\nabla \cdot (\bar{u} H) - \dot{a})^2 + \frac{\rho}{2} (H - H_0)^2 \right] d\Omega$$

$$\rho = \begin{cases} 1 & \text{on flight} \\ 0 & \text{off flight} \end{cases}$$

Mass Conserving Bed observed

$$\frac{\partial H}{\partial t} = -\nabla \cdot (\bar{u} H) + \dot{a}$$

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Minimize  $I$

$$\rho = \begin{cases} 1 & \text{on flight} \\ 0 & \text{off flight} \end{cases}$$

Use 1<sup>st</sup> variation:  $\delta I(H) / \delta H$

Objective:

Find errors in both krigging and mass conserving beds.

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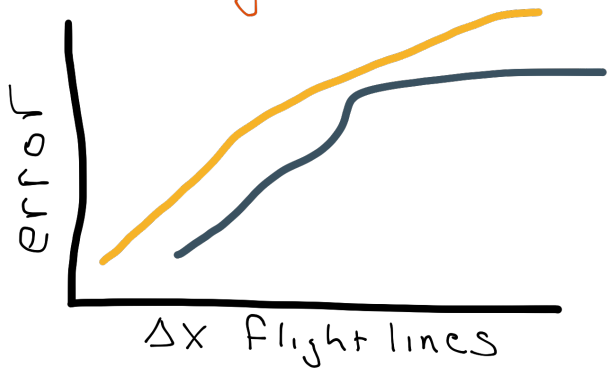
As a function of flight line spacing.



# Objective:

Find errors in both krigging and mass conserving beds.

As a function of flight line spacing.

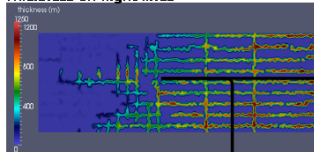


mass cons.

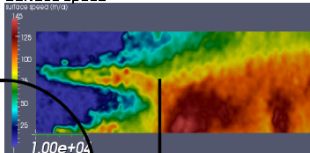
kriged

# Work flow for error analysis

Thickness on flight lines

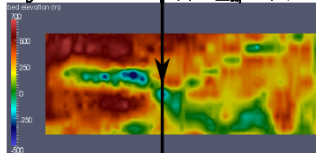


Surface speed



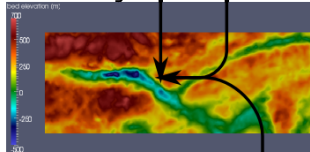
$$\int_{\min} \left( \frac{1}{2} (\nabla \cdot (\bar{u}H) - \dot{a})^2 + \frac{1}{2} (H - H_0)^2 \right) dA$$

Kriged bed

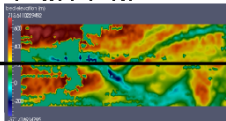


$$b(\mathbf{x}) = \sum_{\alpha_i} w_i b(\mathbf{x}_i)$$

Mass conserving bed



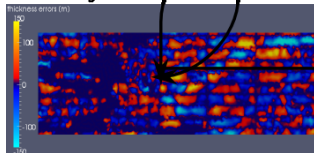
Full resolution bed



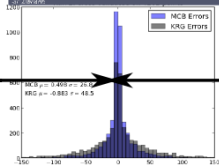
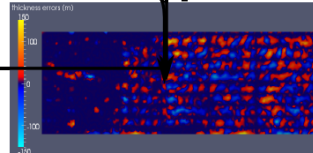
Krg - Full Res

MCB - Full Res

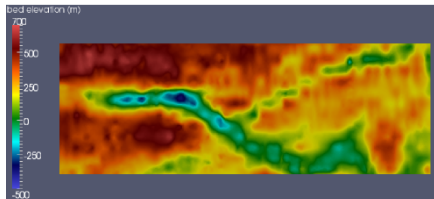
Errors in kriged bed



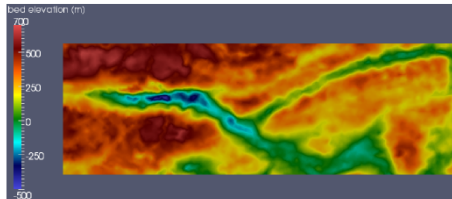
Errors in mass conserving bed



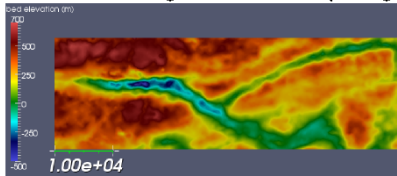
## Kriged bed at 1.0 km spacing



## Mass conserving bed at 1.0 km spacing

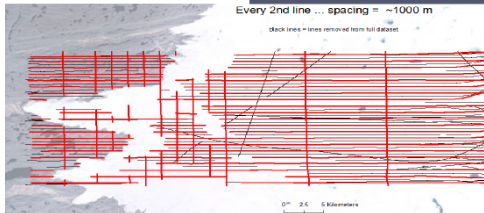


## Mass conserving bed at 500 m spacing

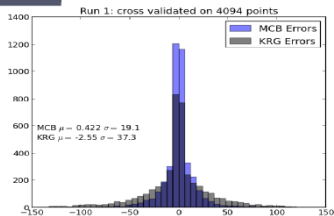


Every 2nd line ... spacing = ~1000 m

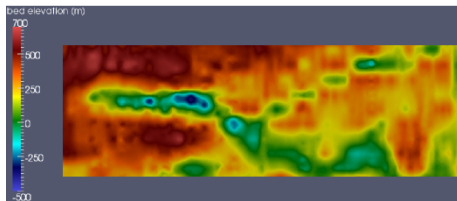
(black lines = lines removed from full dataset)



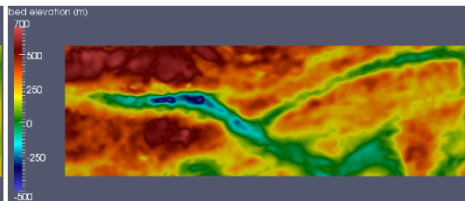
## Error Structure



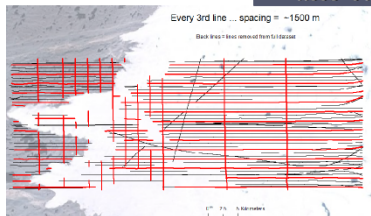
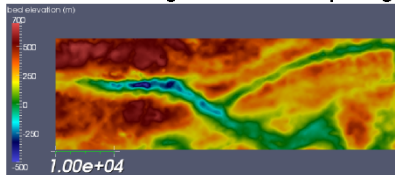
### Kriged bed at 1.5 km spacing



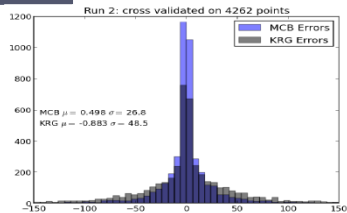
### Mass conserving bed at 1.5 km spacing



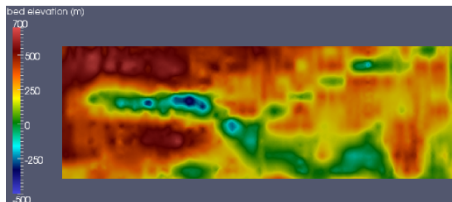
### Mass conserving bed at 500 m spacing



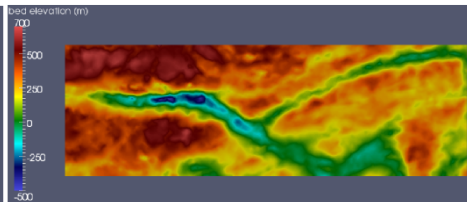
### Error Structure



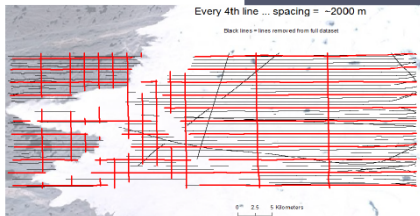
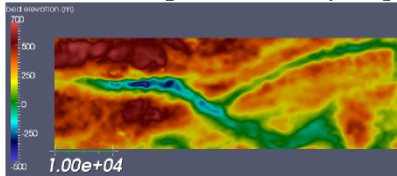
## Kriged bed at 2.0 km spacing



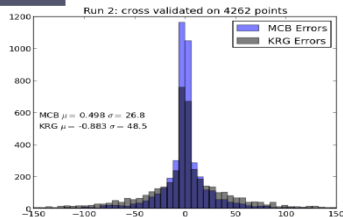
## Mass conserving bed at 2.0 km spacing



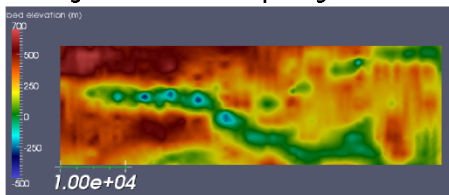
## Mass conserving bed at 500 m spacing



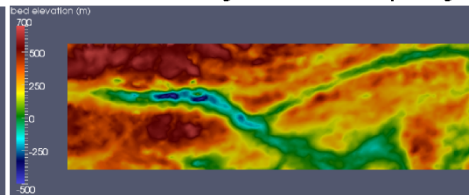
## Error Structure



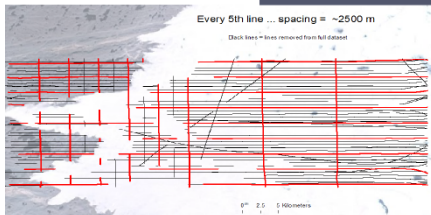
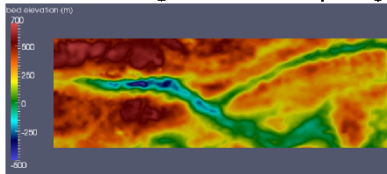
## Kriged bed at 2.5 km spacing



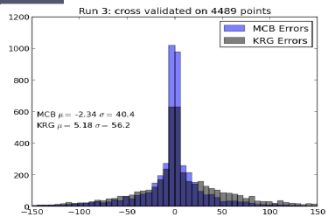
## Mass conserving bed at 2.5 km spacing



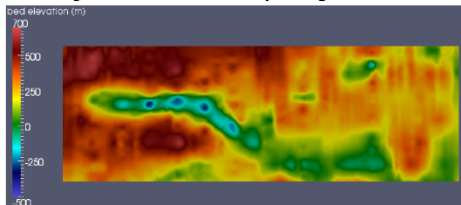
## Mass conserving bed at 500 m spacing



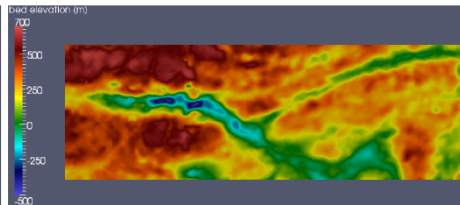
## Error Structure



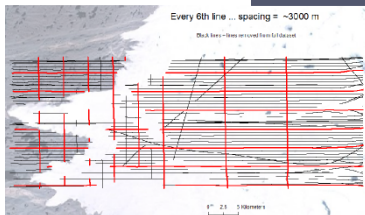
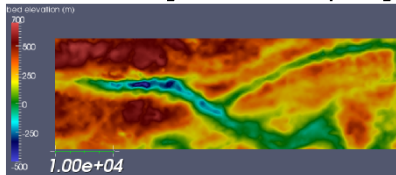
## Kriged bed at 3.0 km spacing



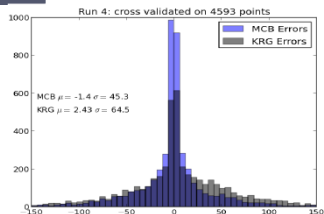
## Mass conserving bed at 3.0 km spacing



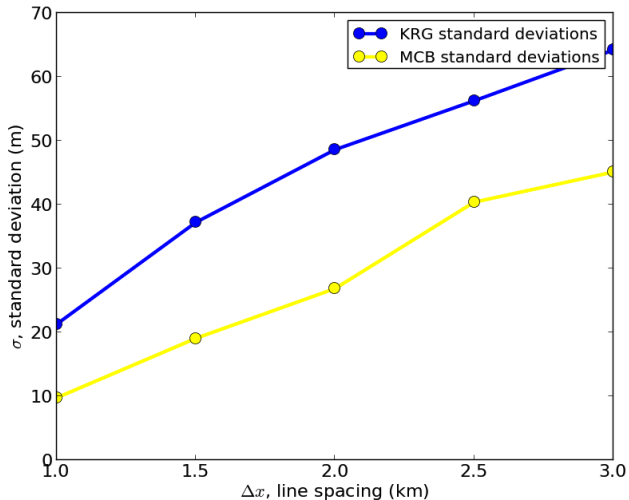
## Mass conserving bed at 500 m spacing



## Error Structure

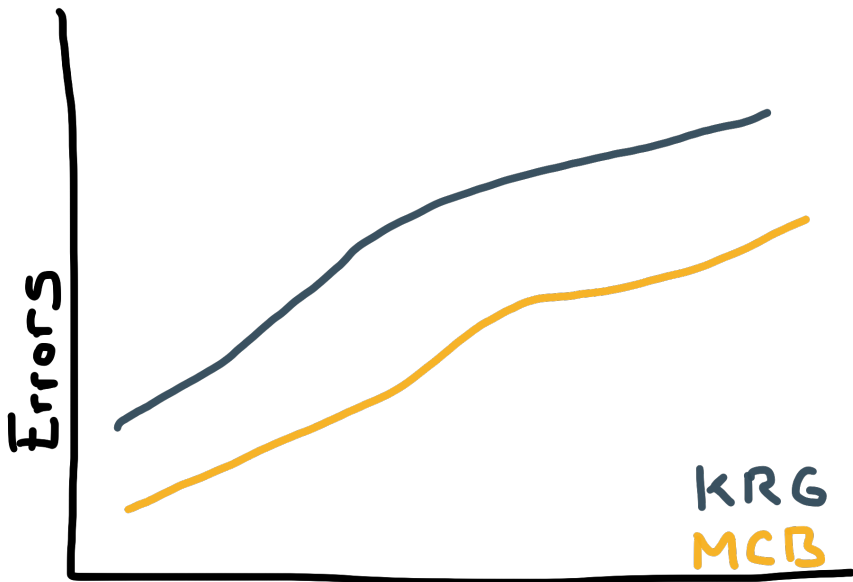


## Errors in the bed vs. flight spacing





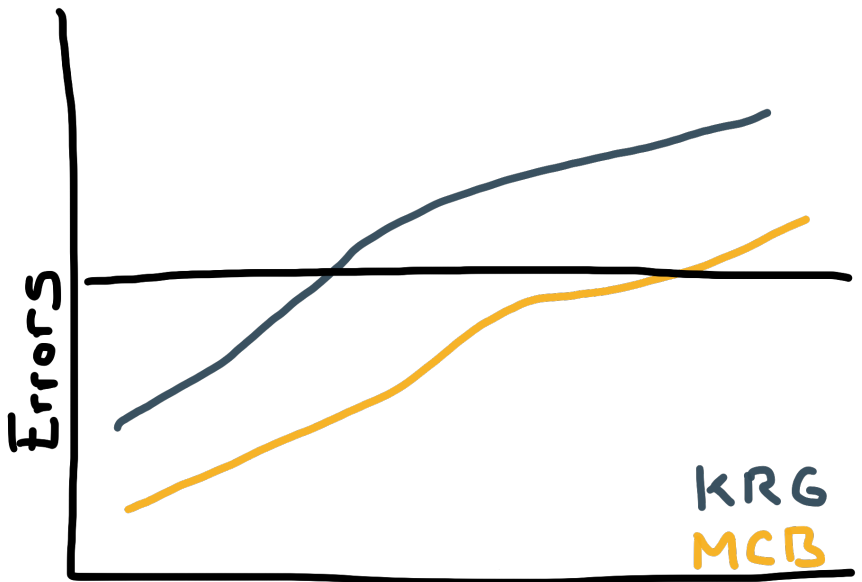
How much do bed errors matter?



ΔX flight lines

KRG  
MCB

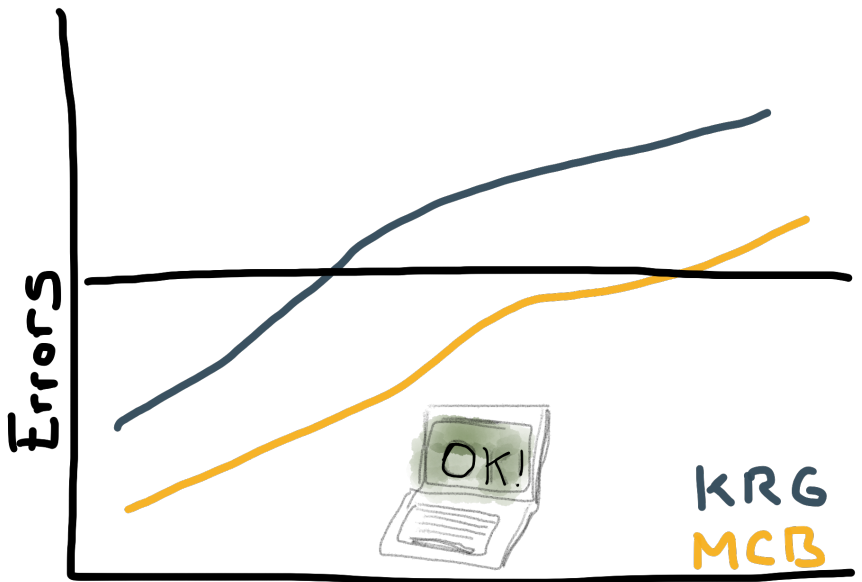
How much do bed errors matter?



ΔX flight lines

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MCB

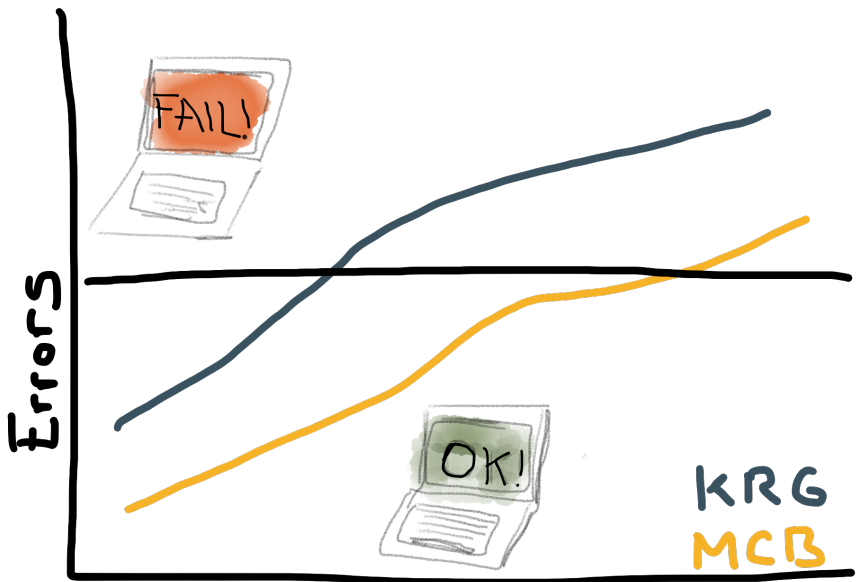
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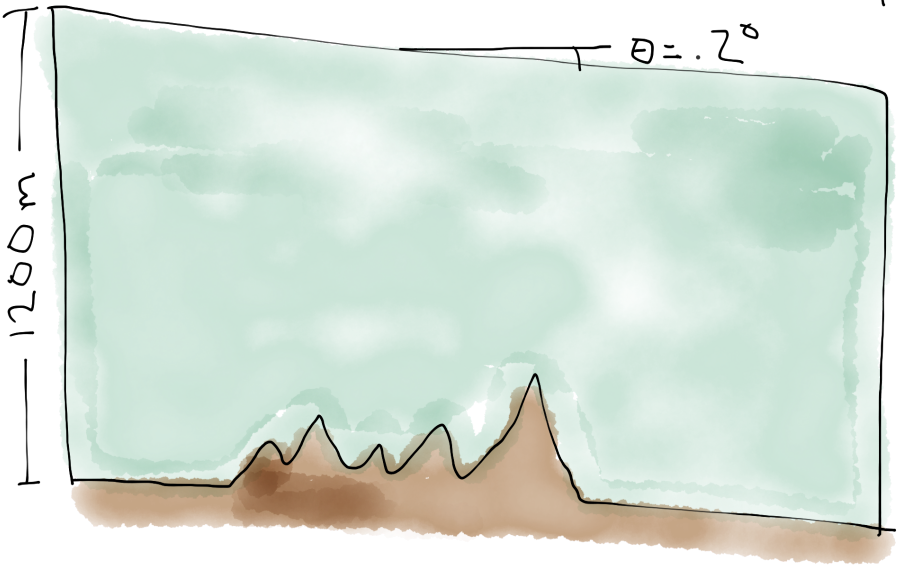
# Numerical Experiment

# Numerical Experiment

50km

$\theta = .2^\circ$

1200m



# Numerical Experiment

50 km

$$\sigma \cdot \hat{n} = 0$$

$$\theta = .2^\circ$$

$$\nabla \cdot \sigma = \rho g$$

$$\sigma = \eta \dot{\epsilon}$$

$$\eta = A(T) \dot{\epsilon}_{II}^{\frac{n-1}{2}}$$

$$\tau_b = \beta u_b^2$$

1200 m

1200 m

1200 m

# Numerical Experiment

50 km

$$\sigma \cdot \hat{n} = 0$$

$$\theta = .2^\circ$$

$$\nabla \cdot \sigma = \rho g$$

$$\sigma = \eta \dot{\epsilon}$$

$$\eta = A(T) \dot{\epsilon}_{II}^{\frac{n-1}{2}}$$

$$\tau_b = \beta u_b$$

$$\beta = \beta_0$$

$$\beta = \beta_0 / 2$$

1200 m



# Numerical Experiment

$$\nabla \cdot \sigma = \rho g$$

$$\sigma = \eta \dot{\epsilon}$$

$$\eta = A(T) \dot{\epsilon}_{II}^{\frac{n-1}{2}}$$

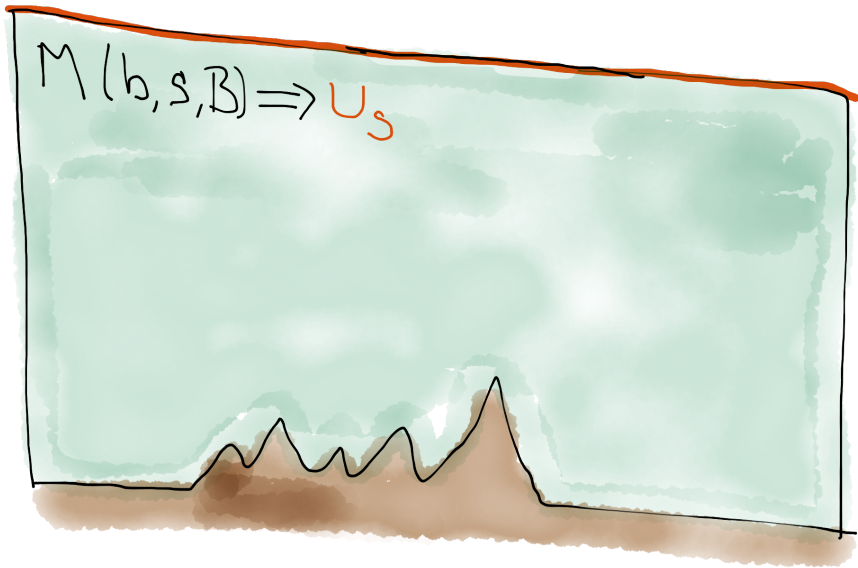
$$\left. \begin{array}{l} \nabla \cdot \sigma = \rho g \\ \sigma = \eta \dot{\epsilon} \\ \eta = A(T) \dot{\epsilon}_{II}^{\frac{n-1}{2}} \end{array} \right\} M(b, s, B)$$

$$\Rightarrow u, p$$

$$\tau_b = \beta u_b$$

# Numerical Experiment

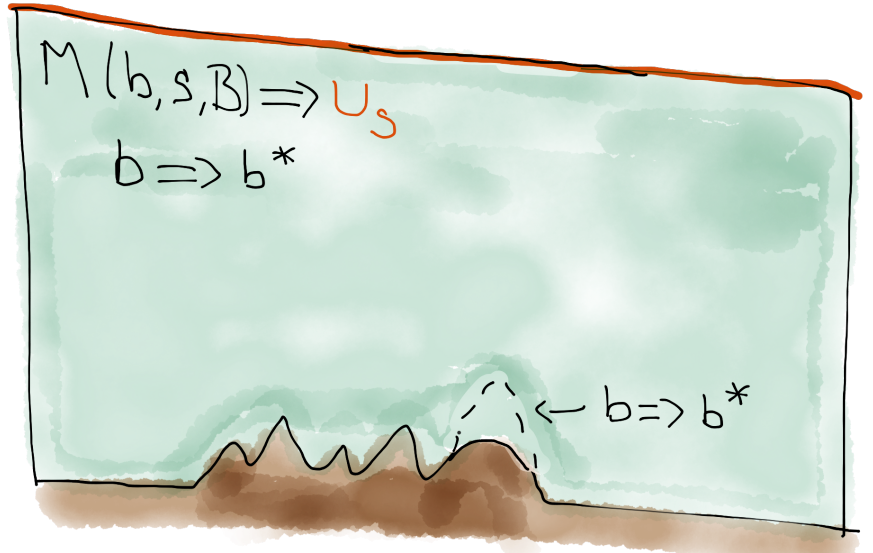
$$M(b, s, B) \Rightarrow U_s$$



# Numerical Experiment

$$M(b, s, B) \Rightarrow U_s$$

$$b \Rightarrow b^*$$

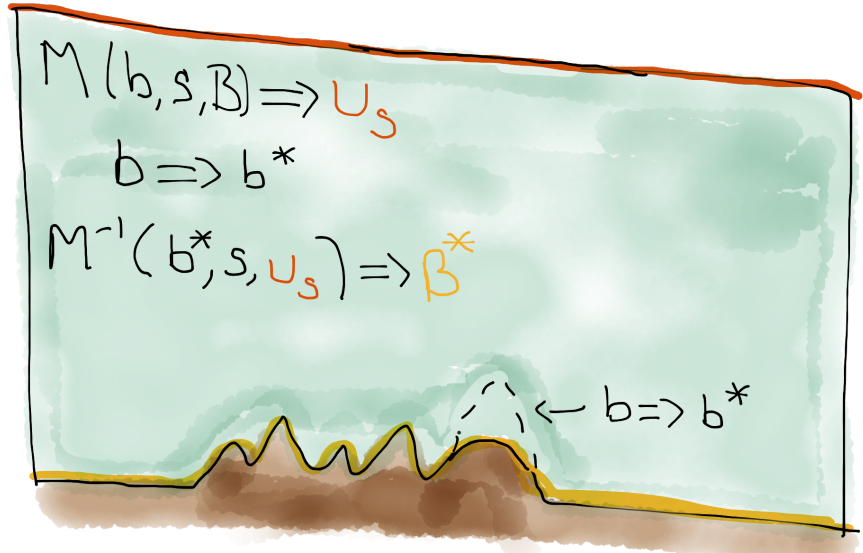

$$\leftarrow b \Rightarrow b^*$$

# Numerical Experiment

$$M(b, s, \beta) \Rightarrow U_s$$

$$b \Rightarrow b^*$$

$$M^{-1}(b^*, s, U_s) \Rightarrow \beta^*$$



$\leftarrow b \Rightarrow b^*$

# Numerical Experiment

$$M(b, s, \beta) \Rightarrow U_s$$

$$b \Rightarrow b^*$$

$$M^{-1}(b^*, s, U_s) \Rightarrow \beta^*$$

$$M(b^*, s, \beta^*) \Rightarrow U_s^*$$

$$\leftarrow b \Rightarrow b^*$$

# Numerical Experiment

$$\frac{ds}{dt} = -U \frac{ds}{dx} + W$$

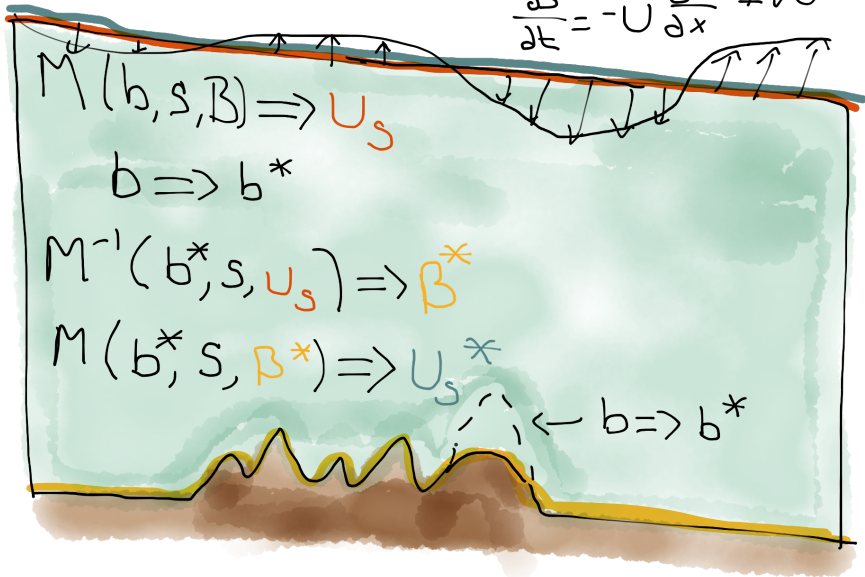
$$M(b, s, \beta) \Rightarrow U_s$$

$$b \Rightarrow b^*$$

$$M^{-1}(b^*, s, U_s) \Rightarrow \beta^*$$

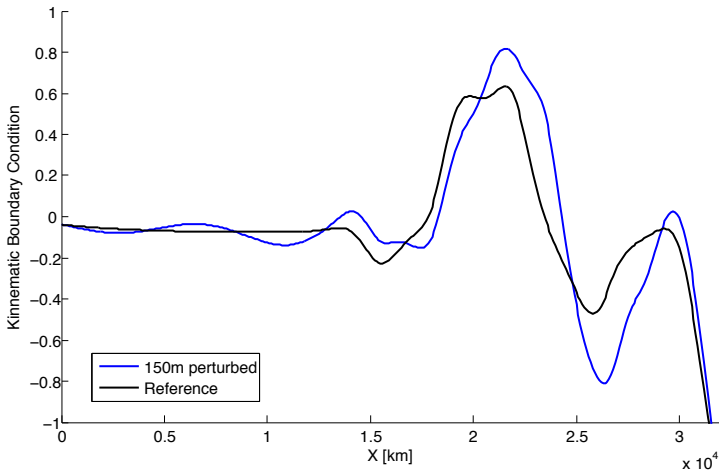
$$M(b^*, s, \beta^*) \Rightarrow U_s^*$$

$$\leftarrow b \Rightarrow b^*$$



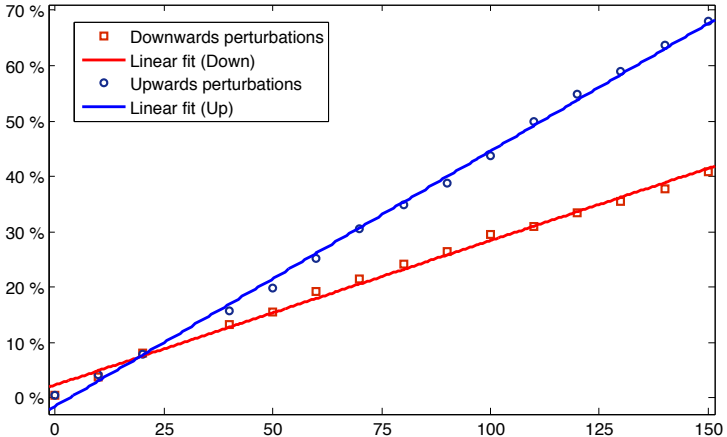
## Errors in the kinematic boundary condition

Mathematically, this is the surface rate of change, given by  $\frac{\partial S}{\partial t} = -u \frac{\partial S}{\partial x} + w$



## Total error in volume rate of change:

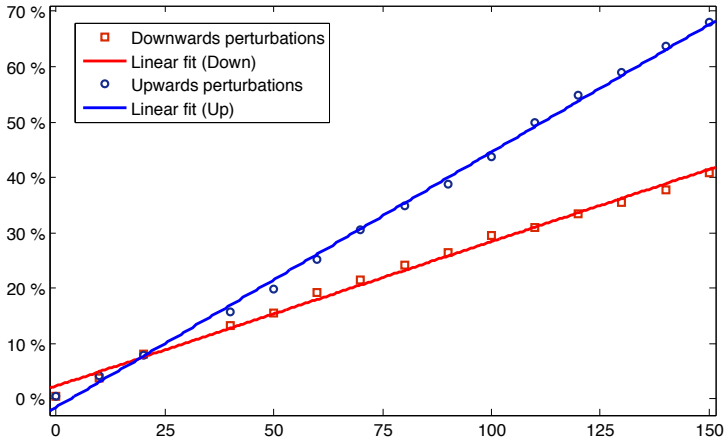
$$\text{Or, } \frac{\partial \Delta V}{\delta t} = \int \left| \frac{\partial S}{\partial t} - \frac{\partial S^*}{\partial t} \right| dx / \int \frac{\partial S}{\partial t} dx$$





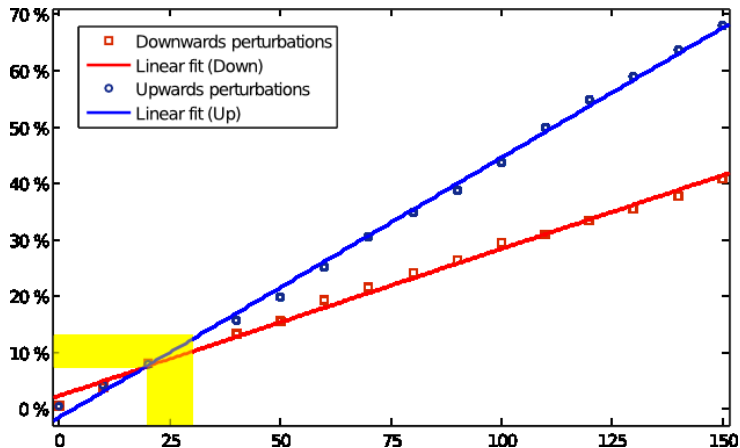
# Limit volume change errors to 10%

Perturbations can be about 25 m



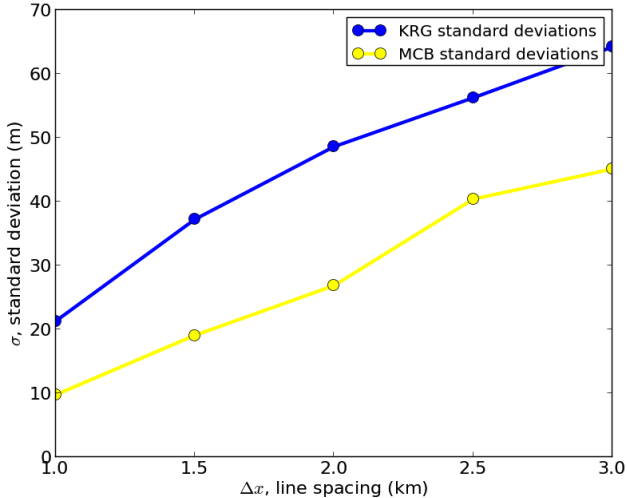
# Limit volume change errors to 10%

Perturbations can be about 25 m



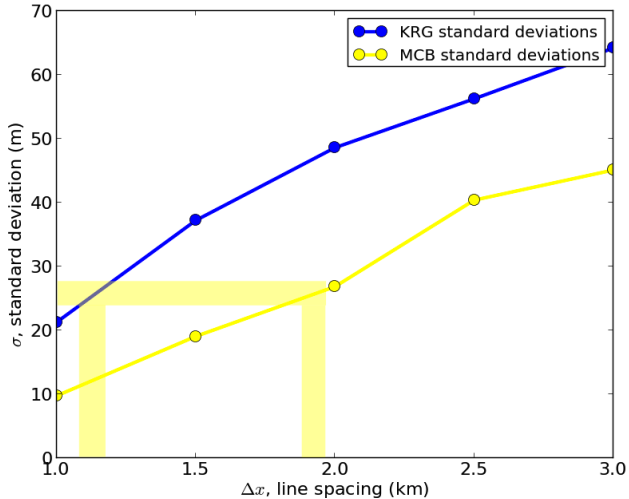
# 25 m errors in bed can be related to flight line spacing

Although  $1\sigma$  only contains  $\sim 2/3$  of errors.



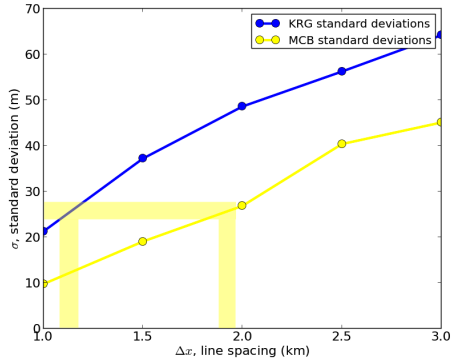
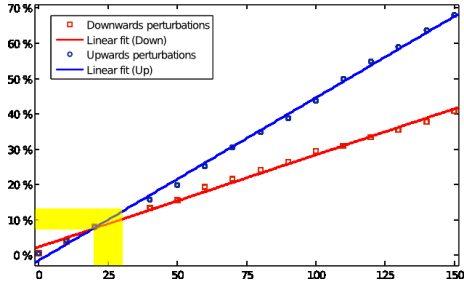
# 25 m errors in bed can be related to flight line spacing

Although  $1\sigma$  only contains  $\sim 2/3$  of errors.



# Conclusions

Flight line spacing should be  $\sim 1.8$  km if MCB is used.



## Conclusions

This is the first example in a general framework for “*physics based interpolation*”

### Our variational problem

$$\mathcal{L}(H, \bar{\mathbf{u}}, \dot{\mathbf{a}}) = \int \frac{1}{2} \underbrace{\rho(H - H_o)^2}_{\text{the data}} + \frac{\gamma}{2} \underbrace{(\nabla \cdot (\bar{\mathbf{u}}H) - \dot{\mathbf{a}})^2}_{\text{PDE involving data}} d\Omega$$

$$\delta\mathcal{L}(\delta H, \bar{\mathbf{u}}, \dot{\mathbf{a}}) = 0$$