## Recent progress with the BISICLES dynamical core in CISM

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## Berkeley-ISICLES (BISICLES)

- DOE ISICLES-funded project to develop a scalable adaptive mesh refinement (AMR) ice sheet model/dycore
  - Local refinement of computational mesh to improve accuracy
- □ Use Chombo AMR framework to support block-structured AMR
  - Support for AMR discretizations
  - Scalable solvers
  - Developed at LBNL
  - DOE ASCR supported (FASTMath)
- Alternate dycore interface to CISM
- □ Collaboration with LANL and Bristol (U.K.)
- □ Continuation in SciDAC-funded PISCEES.













#### "L1L2" Model (Schoof and Hindmarsh, 2010).

- Uses asymptotic structure of full Stokes system to construct a higher-order approximation
  - Expansion in  $\mathcal{E} = \frac{[H]}{[L]}$  and  $\lambda = \frac{[\tau_{shear}]}{[\tau_{normal}]}$  (ratio of shear & normal stresses)
    - Large  $\lambda :$  shear-dominated flow
    - Small  $\lambda:$  sliding-dominated flow
  - Computing velocity to  $O(\varepsilon^2)$  only requires  $\tau$  to  $O(\varepsilon)$
- Computationally much less expensive -- enables fully 2D vertically integrated discretizations. (can reconstruct 3d)
- □ Similar formal accuracy to Blatter-Pattyn  $O(\varepsilon^2)$ 
  - Recovers proper fast- and slow-sliding limits:
    - SIA  $(1 \ll \lambda \leq \varepsilon^{-1/n})$  -- accurate to  $O(\varepsilon^2 \lambda^{n-2})$
    - SSA  $(\varepsilon \le \lambda \le 1)$  accurate to  $O(\varepsilon^2)$







#### "L1L2" Model (Schoof and Hindmarsh, 2010), cont.

- □ Can construct a computationally efficient scheme:
  - 1. Approximate constitutive relation relating grad(u) and stress field  $\tau$  with one relating  $grad(u|_{z=b})$ , vertical shear stresses  $\tau_{xz}$  and  $\tau_{xz}$  given by the SIA / lubrication approximation and other components  $\tau_{xx}(x, y, z)$ ,  $\tau_{xy}(x, y, z)$ , etc
  - 2. leads to an effective viscosity  $\mu(x, y, z)$  which depends only on  $grad(u|_{z=b})$  and  $grad(z_s)$ , ice thickness, etc
  - 3. Momentum equation can then be integrated vertically, giving a nonlinear, 2D, elliptic equation for  $u|_{z=b}(x, y)$
  - 4. u(x, y, z) can be reconstructed from  $u|_{z=b}(x, y)$



### Modified "L1L2" Model (SSA\*)

- □ Can construct a computationally efficient scheme:
  - 1. Approximate constitutive relation relating grad(u) and stress field  $\tau$  with one relating  $grad(u|_{z=b})$ , vertical shear stresses  $\tau_{xz}$  and  $\tau_{xz}$  given by the SIA / lubrication approximation and other components  $\tau_{xx}(x, y, z)$ ,  $\tau_{xy}(x, y, z)$ , etc
  - 2. leads to an effective viscosity  $\mu(x, y, z)$  which depends only on  $grad(u|_{z=b})$  and  $grad(z_s)$ , ice thickness, etc
  - 3. Momentum equation can then be integrated vertically, giving a nonlinear, 2D, elliptic equation for  $u|_{z=b}(x, y)$



4. Use  $u(x, y, z) = u|_{z=b}(x, y)$  (neglect vertical shear in flux velocity)



### **BISICLES Results - MISMIP3D**

#### Experiment P75R: (Pattyn et al (2011)

- Begin with steady-state (equilibrium) grounding line.
- Add Gaussian slippery spot perturbation at center of grounding line
- □ Ice velocity increases, GL advances.
- □ After 100 years, remove perturbation.
- Grounding line should return to original steady state.
- □ Figures show AMR calculation:
  - $\Delta x_0 = 6.5 km$  base mesh,
  - 5 levels of refinement
  - Finest mesh  $\Delta x_4 = 0.195 km$ .
  - t = 0, 1, 50, 101, 120, 200 *yr*
- Boxes show patches of refined mesh.
- GL positions match Elmer (full-Stokes)













### MISMIP3D (cont): L1L2 (SSA\*) Spatial Resolution



• Very fine (~200 m) resolution needed to achieve reversability!

![](_page_6_Picture_3.jpeg)

![](_page_6_Picture_4.jpeg)

![](_page_6_Picture_5.jpeg)

![](_page_6_Picture_6.jpeg)

#### MISMIP3D: SSA vs. "L1L2" or "SSA\*"

![](_page_7_Figure_1.jpeg)

- Direct comparison of SSA vs. SSA\*
  - (fully resolved spatially, same numerics, etc)
  - Note difference in steady-state GL positions

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![](_page_7_Picture_8.jpeg)

BRISTOL

#### BISICLES Results - Ice2Sea Amundsen Sea

- □ Study of effects of warm-water incursion into Amundsen Sea.
- □ Results from Payne et al, (2012), submitted.
- Modified 1996 BEDMAP geometry (Le Brocq 2010), basal traction and damage coefficients to match Joughin 2010 velocity.
- □ Background SMB and basal melt rate chosen for initial equilibrium.
- □ SMB held fixed.
- Perturbations in the form of additional subshelf melting:
  - derived from FESOM circumpolar deep water
  - ~5 m/a in 21<sup>st</sup> Century,
  - ~25 m/a in 22<sup>nd</sup> Century.

![](_page_8_Picture_10.jpeg)

# **Amundsen Sea Ice Sheet Simulation**

One possible climate scenario (Payne et al.) simulated using SciDAC-funded BISICLES code

![](_page_9_Picture_3.jpeg)

## Ice2Sea Amundsen (cont)

- Need at least 2 km resolution to get any measurable contribution to SLR.
- □ Appears to converge at first-order in ∆x

SLR vs. year, Amundsen Sea Sector

![](_page_10_Figure_4.jpeg)

time (years)

![](_page_10_Picture_6.jpeg)

![](_page_10_Picture_7.jpeg)

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![](_page_10_Picture_9.jpeg)

### Ice2Sea Amundsen (cont) - Thwaites?

- In 400 year run, Thwaites destabilizes as well.
- Same forcing as previous run, subshelf melting held constant past 2200.
- Thwaites is very stable, until it tips.

![](_page_11_Picture_4.jpeg)

![](_page_11_Picture_5.jpeg)

# BISICLES/CISM coupling

# □ FAS multigrid solver

# Embedded boundary for Grounding lines

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## CISM/BISICLES coupling update

- Extension of existing serial coupled code to work in the fully distributed case (no serial bottlenecks)
- □ CISM (F90) to BISICLES (C++)
- General API design for coupling alternate dynamical cores into CISM
- □ Moderately complex build process (working to streamline)
- CISM owns "main", problem setup, coupler to CESM, other physics (like isostasy, hydrology, etc)
- CISM hands control to BISICLES, which evolves the ice sheet
- BISICLES passes fields like thickness, velocity back to CISM

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#### CISM/BISICLES coupling update (cont)

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![](_page_14_Picture_6.jpeg)

## Embedded Boundary (EB) for Grounding Lines

- Embedded Boundary (EBChombo)
  - Currently force GL and ice margins to cell faces
  - "Stair-step" discretization Known to be inadequate from experience with Stefan Problem in other contexts!
  - Use Chombo Embedded-boundary support to improve discretization of GL's and ice margins.
  - Can solve as a Stefan Problem, with appropriate jump conditions enforced at grounding line. (as in Schoof, 2007)

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![](_page_15_Picture_8.jpeg)

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![](_page_15_Picture_12.jpeg)

## New FAS Multigrid nonlinear solver

- □ Full Approximation Storage (FAS) nonlinear multigrid
- □ Picard, JFNK:
  - Iinear solver nested inside of nonlinear one
  - Linear Multigrid solvers (residual-correction form) work well.
- □ FAS Multigrid fully nonlinear solver (no outer solver)
  - Can outperform JFNK/MG
  - More robust (don't need good initial guess)
  - Simpler to implement and maintain
  - Nonlinear convergence similar to MG linear convergence

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## Antarctica (Ice2Sea)

- Refinement based on Laplacian(velocity), grounding lines
- 5 km base mesh with 3 levels of refinement
  - base level (5 km): 409,600 cells (100% of domain)
  - level 1 (2.5 km): 370,112 cells (22.5% of domain)
  - Level 2 (1.25 km): 955,072 cells (14.6% of domain)
  - Level 3 (625 m): 2,065,536 cells (7.88% of domain)

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#### Next Steps

- □ Continue work with CISM/BISICLES hybrid code
  - Fully 2-way coupling
  - Eventual coupling to CESM
- Embedded boundary approach is promising
- □ More solver improvements
- Full-Stokes dynamical core

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- US Department of Energy Office of Science (ASCR) funded BISICLES project
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- □ Mark Adams (Columbia University)

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#### **Extras**

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#### Linear Solvers - GAMG vs. Geometric MG

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