



Comparing CAM-FV and CAM-SE in a 'perfect model' data assimilation environment

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Background



- ➤ The Data Assimilation Research Testbed has assimilated many kinds of observations into many versions of CAM (eulerian and finite volume 'FV')
- Results are comparable to operational forecasting centers.
- > Extensions into CESM:
 - + POP and CLM
 - + Assimilation into a coupled model: CAM+POP+CLM
 - + WACCM (Pedatella & Liu in WAWG)
 - + CAM-Chem (Barré in CCWG)
- Now extended to spectral element CAM ('SE')

1-slide tangent: WACCM+DART results

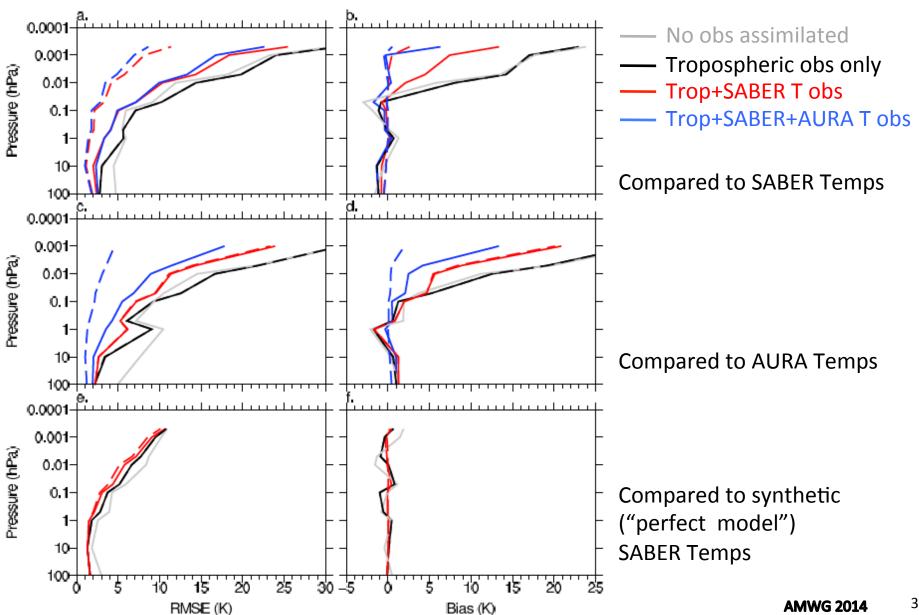
Then compare CAM-SE against CAM-FV in a 'perfect model' context; the first validation step of a data assimilation implementation.



WACCM(FV)+DART: SABER and AURA



Pedatella, et al. "Ensemble Data Assimilation in the Whole Atmosphere Community Climate Model" JGR, in press





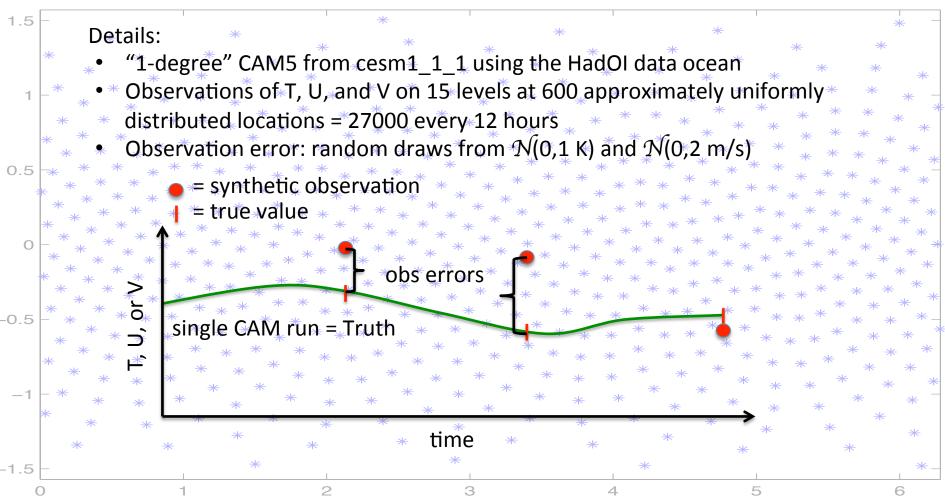
Perfect Model



Free run of the model is used as the Truth.

Observations of the evolving model state are taken periodically.

Observational error is added to the observed values to make them realistic.

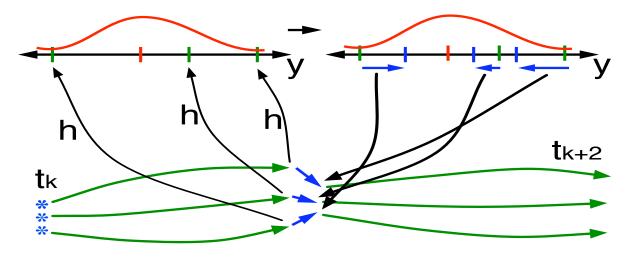




DART



Ensemble Kalman filter algorithm requires running an ensemble of equally likely forecasts, then using statistics of the ensemble and observations to allow the observations to guide the ensemble to a better description of the atmosphere.



Ensemble spread = uncertainty of the model state. It grows during forecast, shrinks as information is added during assimilation.

Neglected errors -> ensemble spread is too small (over confident). This can be fixed with "adaptive inflation", which increases ensemble spread but retains the mean.

Observations more than 3×spread away from ensemble mean are ignored as being erroneous.



"Identical Twin" Experiments



Will the ensemble track the observations (Truth + obs error) if the Truth model = the DA model = CAM-SE?

Initial ensemble has a tiny spread (O(round-off) in T) centered around the True State.

No inflation (shouldn't be needed).



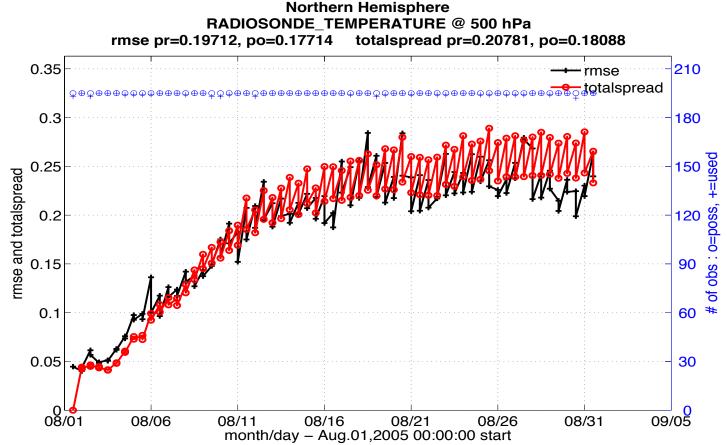
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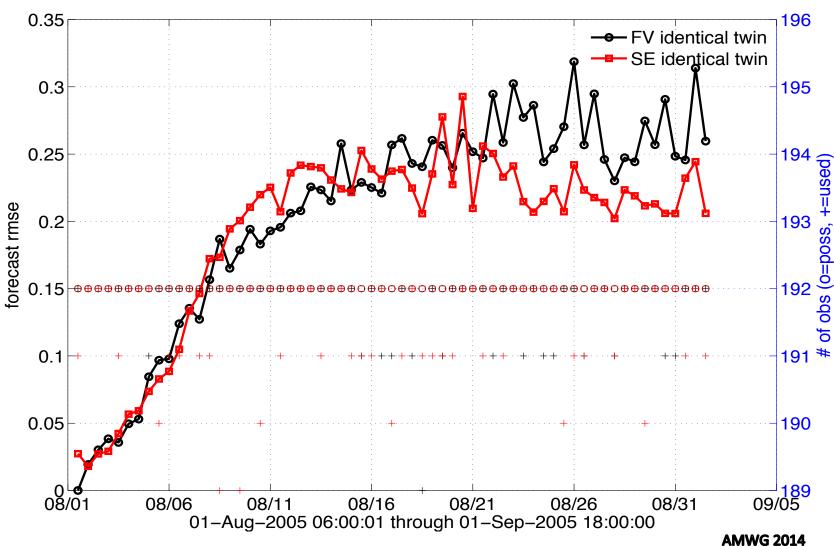


"Identical Twin" Experiments



How does the CAM-SE assimilation compare to corresponding CAM-FV assimilation?

Southern Hemisphere RADIOSONDE_TEMPERATURE @ 500 hPa







Will the ensemble of CAM-SE track the observations of CAM-FV? And vice versa.

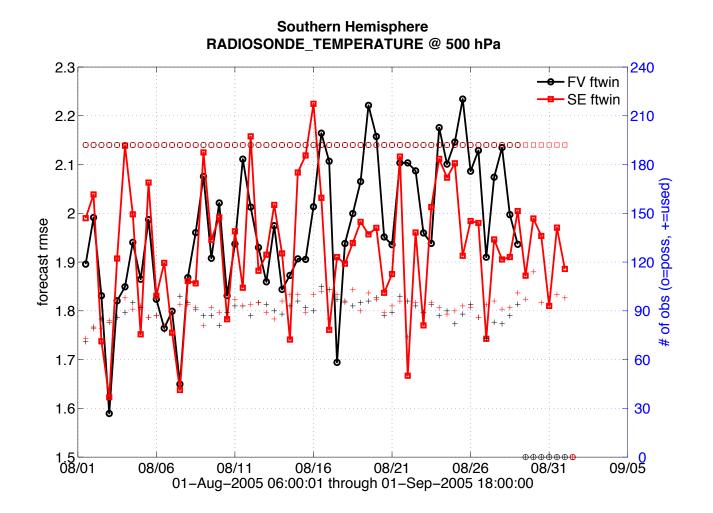
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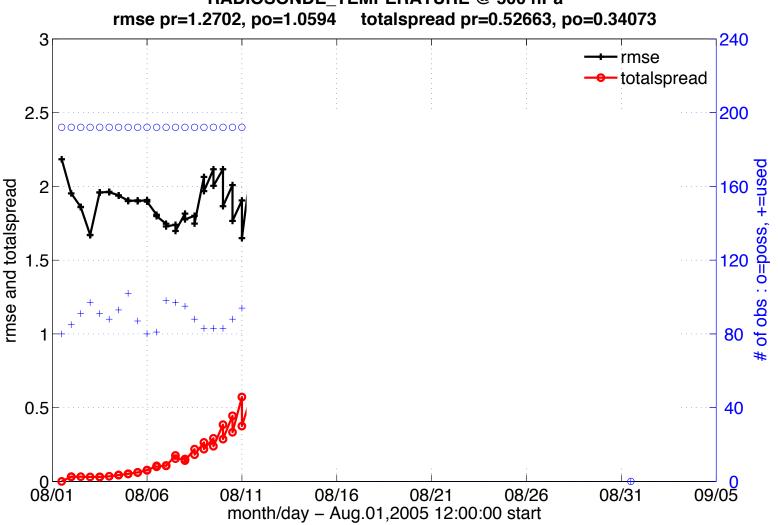
What if we give the assimilation a fighting chance by turning on the adaptive inflation? That may allow the spread to increase, which will allow more observations to be assimilated.





Obs from CAM-FV. Assimilating model is CAM-SE.



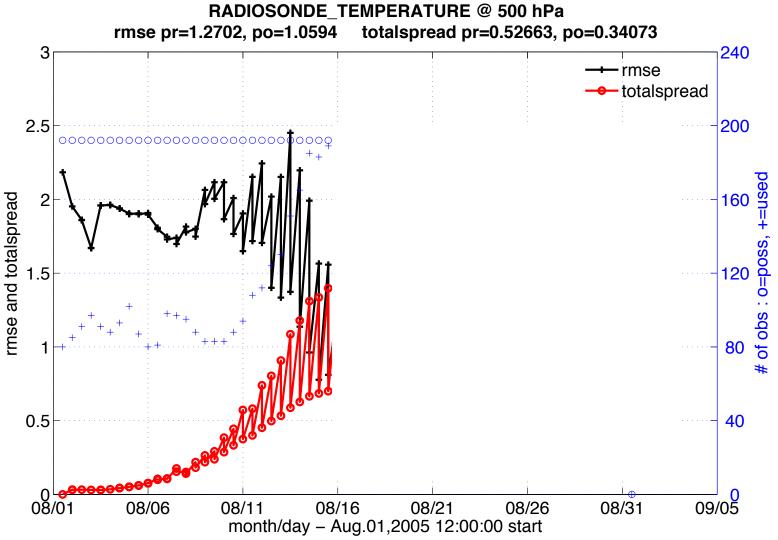






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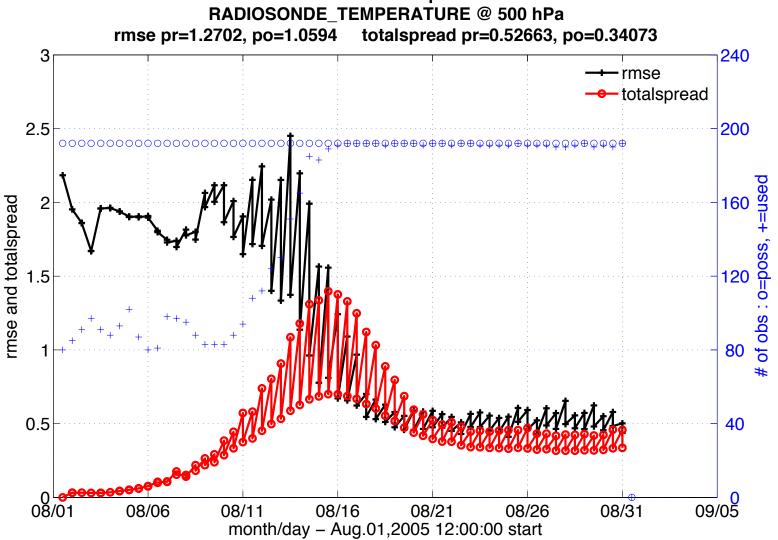






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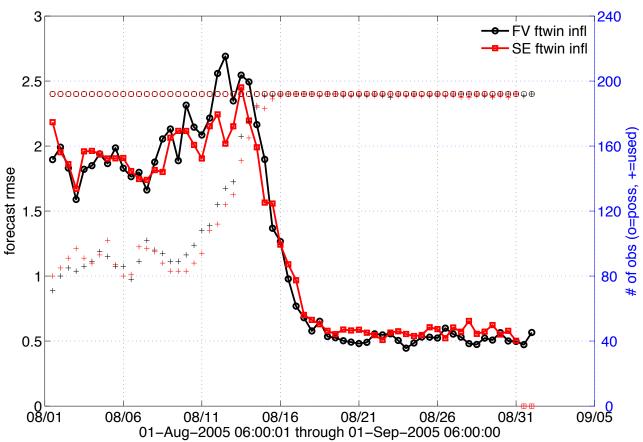




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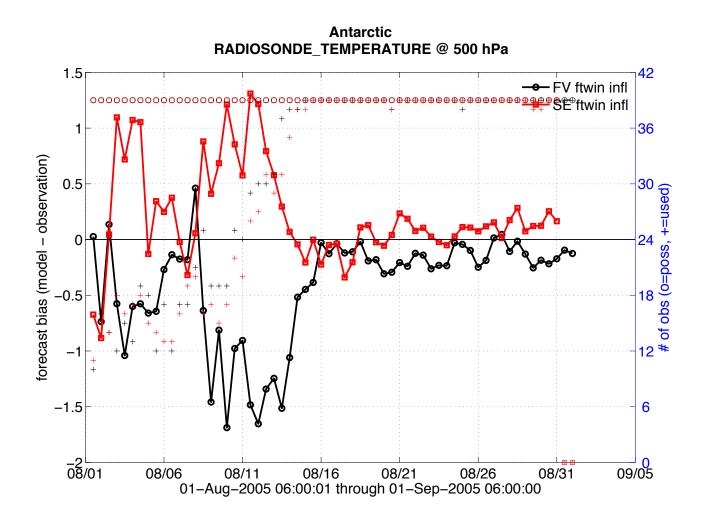








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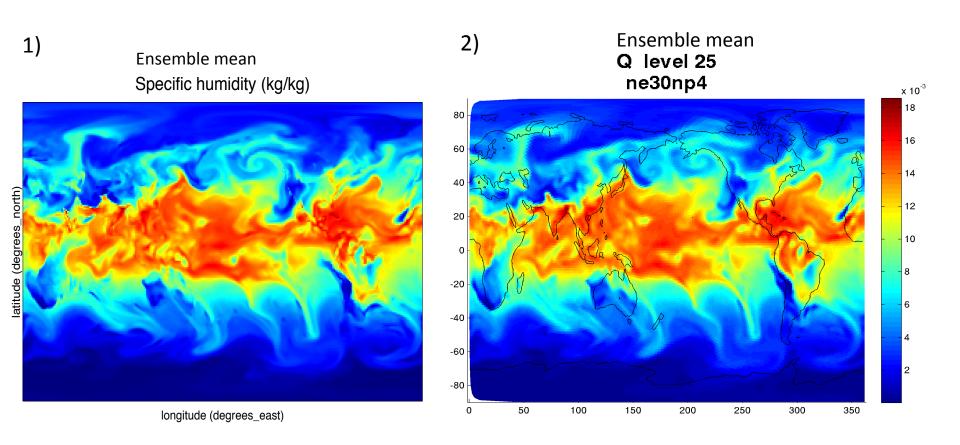


State Space Confirmation



Compare 2 assimilations which use the same set of observations:

- 1) Identical twin using CAM-FV for obs and assimilation
- 2) Fraternal twin using CAM-FV for obs, but CAM-SE for assimilation



Q is not an observed variable, but has been brought to the observed model state.



Conclusions



- Data Assimilation with DART and CAM-SE passes the 'perfect model' tests.
- ➤ The adaptive inflation algorithm effectively permits even ensembles with small spread and wrong mean to be shifted to the correct model state.
- Assimilations with CAM-SE appear comparable to those with CAM-FV, although much more analysis could be done. Collaboration?
- This tool can identify some biases in a new model by comparison with known biases in an old model, without a long run of the new model.
- ➤ A new model can be searched for problem areas by direct comparison to observations.
- We're ready for a real observation test of CAM-SE+DART, including obervations that are not model variables.

For more information:

http://www.image.ucar.edu/DAReS/DART/

(no facebook, no twitter)





Resources



5 nodes/instance (ensemble member) (usually 3, but sporadic memory problems) ~2200 core hours/ 12 hour advance and assimilate 27000 obs.

Wall clock; < 30 min/(forecast+assim cycle)

+ waiting between jobs

~200 Gb/ensemble restart set. Save infrequently

Up to 10 Gb/assimilation of DART output. So up to 0.5 Tb/month, user selectable.





