







## CAM-SE Dynamics Update: Separating Physics-Dynamics Grids, Tracers, ...

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### CAM -SE: NCAR-DOE Community Atmosphere CAM-SE: NCAR-DOE Community Atmosphere Model with Spectral Elements dynamical core

Continuous Galerkin finite-element method (Taylor et al., 1997) on a cubed-sphere:



Discretization is mimetic => mass-conservation & total energy conservation

Conserves axial angular momentum very well (Lauritzen et al., 2014)

- Support static mesh-refinement and retains formal order of accuracy!
- Highly scalable to at least O(100K) processors (Dennis et al., 2012)
- AMIP-climate competitive with CAM-FV (Evans et al., 2012)
- Low computational throughput for 1 degree horizontal resolution at "low" processor counts compared to CAM-FV

Lower computational throughput for many-tracer applications

abla Issues with spinning up coupled simulations (can we blame the dynamical core?)



## **CAM-SE: NCAR-DOE Community Atmosphere Model with Spectral Elements dynamical core**

Continuous Galerkin finite-element method (Taylor et al., 1997) on a cubed-sphere:

- On Yellowstone, CAM-SE is faster than CAM-FV when more than approximately 2100 processors are used
- Users do not necessarily use many processors & it may be hard to get large jobs through the queue on high performance computing systems ("cultural" change needed?)



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Finite-volume Lagrangian form of continuity equation for  $\psi = \rho, \rho \phi$ :

$$\int_{A_k} \psi_k^{n+1} dx dy = \int_{a_k} \psi_k^n dx dy = \sum_{\ell=1}^{L_k} \left[ \sum_{i+j \leq 2} c_\ell^{(i,j)} w_{k\ell}^{(i,j)} \right],$$

where weights  $w_{k\ell}^{(i,j)}$  are functions of the coordinates of the vertices of  $a_{k\ell}$ .

 $w_{k\ell}^{(i,j)}$  can be re-used for each additional tracer (Dukowicz and Baumgardner, 2000) computational cost for each additional tracer is the reconstruction and limiting/filtering. CSLAM is stable for long time-steps (CFL>1)

Lauritzen, Nair and Ullrich (*J. Comput. Phys.*, 2010)

## A way to accelerate tracer transport:

#### **CSLaM** scheme (Conservative Semi-Lagrangian Multi-tracer)

- Highly scalable (Erath et al., 2012)
- Inherently mass-conservative
- Fully two-dimensional



SciDAC Scientific Discovery through Advanced Computing

-> accurate treatment of weak singularities, e.g., cube corners

-> can be implemented on various spherical grids (cubed-sphere, icosahedral, ...)

Shape-preserving (no negatives, no spurious grid-scale oscillations)

Preserves linear correlations (even with shape-preservation) – see next slide!

- Current version is 3<sup>rd</sup>-order accurate for smooth problems
- Allows for long time-steps (limited by flow deformation not Courant number)
- Multi-tracer efficient (high start-up cost but "cheaper" for each additional tracer):





CSLAM implemented in NCAR-DOE HOMME (High-Order Methods Modeling Environment) by Erath et al., (2012); CAM-SE "pulls" SE dynamical core from HOMME

# The terminator 'toy'-chemistry test: A simple tool to assess errors in transport schemes

(Lauritzen et al, 2015, GMDD)

See: http://www.cgd.ucar.edu/cms/pel/terminator.html



THE TERMIN

TEST

caused by the limiter and/or physics-dynamics coupling!

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Multi-tracer efficient (high start-up cost but "cheap" for each additional tracer)
CSLAM uses a "finite-volume"-type grid and SE uses a quadrature grid









## **Current physics-dynamics coupling**

Atmospheric state passed to physics is at quadrature points:

- Leads to an-isotropic "sampling" of atmospheric state
- High-order basis functions can be oscillatory and are least smooth near element boundaries:









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#### Held-Suarez with topography









# "Equal-area" physics grid

Atmospheric state passed to physics is at quadrature points:

- Leads to an-isotropic "sampling" of atmospheric state
- High-order basis least smooth nea
  Note that physics grid averages/moves fields away from boundary of element where the solution is least smooth

(in element interior the polynomials are  $C^{\infty}$ )











### Mapping variables from dynamics to physics:

Integrate atmospheric state (basis functions) over control volumes: **Conservation** and **consistency** (=preservation of a constant) is enforced via a least squares projection onto the space of conservative and consistent maps. <u>Ullrich and Taylor (2015)</u>

Interpolation matrix can be pre-computed



Lauritzen modification: optimally blend linear map (shape-preserving) with high-order map to provide less diffusive map









### Mapping tendencies from physics to dynamics

Similar method: first-order map that is **shape-preserving**, **conservative** and **consistent**. <u>Ullrich and Taylor</u> (2015)





## **CAM-SE-CSLAM**



#### combining the best of two worlds: high-order spectral dynamics & finite-volume transport







# **CAM-SE-physgrid**







Dry dynamics test case: physics package replaced with simple boundary friction and relaxation of T towards zonally symmetric profile







Idealized surface: no land (or mountains) + specified zonally symmetric sea surface temperatures => free motions, no forced component







Last step(s) towards CAM-SE-CSLAM: coupling mass

In this presentation I am excluding the massive rewrite of CAM history to allow for the separation of physics and dynamics grids as well as other software engineering tasks needed for adding new capability to the CAM code base

(done by Steve Goldhaber, NCAR)





We are trying to couple to distinct numerical methods (has not been done before!) under the following constraints:

- Mass-conservation and shape-preservation
- Consistency: when mixing ratio is =1 the tracer mass must reduce to the SE mass

Coupling the same method on the same grid but with different time-steps for air mass and tracer mass is widely used (e.g., CAM-FV, CAM-SE, ...):







Flux-coupling with CAM-SE-CSLAM: STEP 1: flux-form version of CSLAM (Harris et al., 2011) – DONE but being rewritten for efficiency and code clarity STEP 2: implied fluxes through CSLAM control volumes from SE Received code from Sandia O(week) ago (thanks to Overfelt and Taylor (9)

For CAM-SE it can be shown that the change in mass within each element is given by a natural flux at each element edge (Taylor and Fournier, 2010). Taylor, Ullrich and Overfelt have recently extended this result to hold for CSLAM control volumes.



#### Unforeseen issue:

STEP 1 & 2 yields mass-conservation and consistency or consistency and shape-preservation. We need all three! What is the problem? Swept areas implied by CSLAM and SE may have different signs (when u,v are small)







STEP 3: replace trajectory algorithm based on (u,v) with trajectories based on swept areas implied by SE <u>"CSLAM mass completely slave to SE"!</u>

Straight forward for dimensionally split schemes but not for fully 2D schemes such as CSLAM.



#### **Problem:**

Given SE mass flux through each cell wall, find swept areas so that air mass integrated over swept areas equals SE flux while union of the swept areas span the sphere.



Equivalent perpendicular y-flux Departure grid based on fluxes











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