2016 CESM WG Meeting: Societal Dimension Working Group

February 8, 2016

PATTERN SCALING: A RECENT DEVELOPMENT AND LARGER PLANS

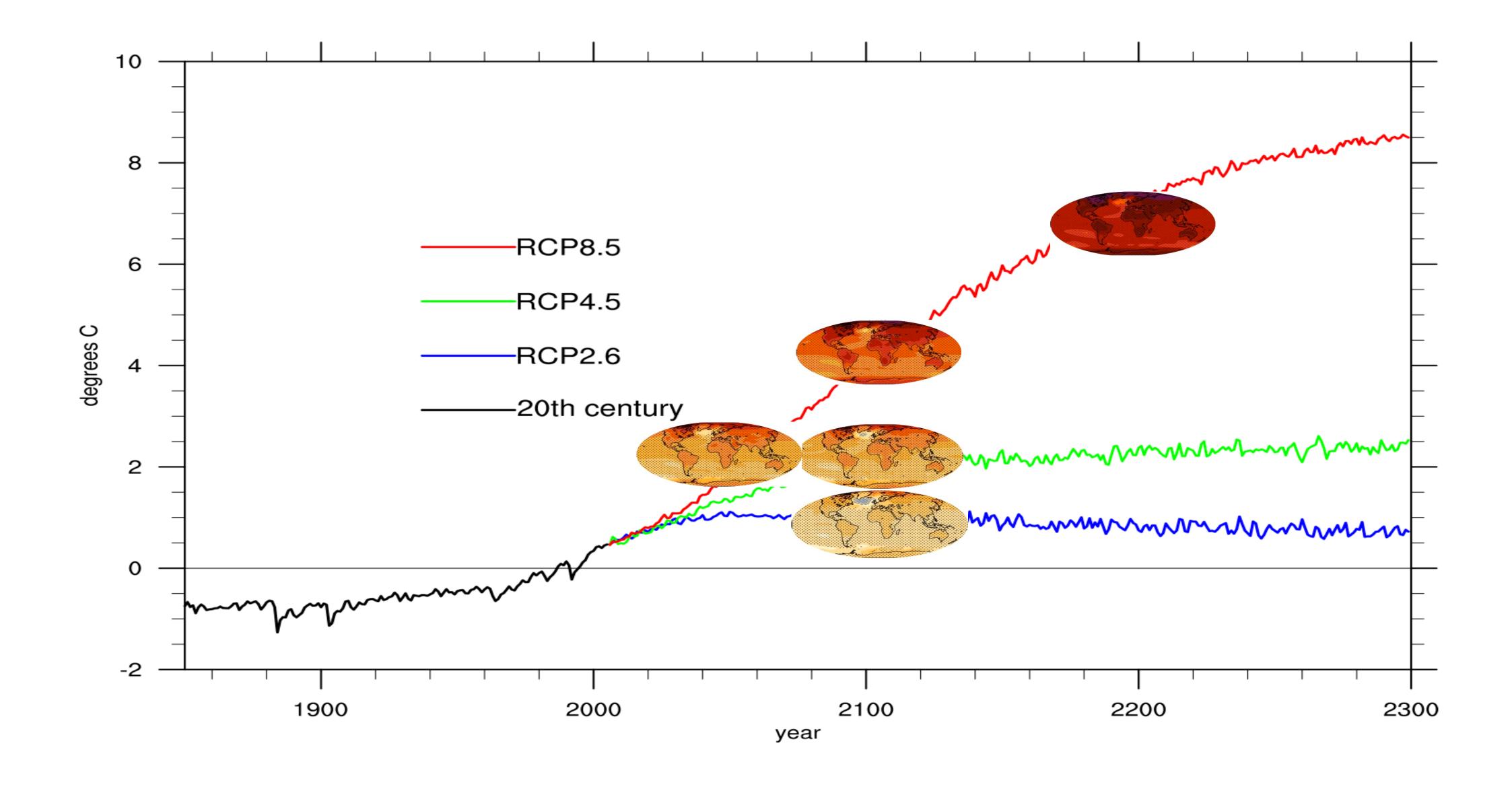
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Pattern Scaling

• Can provide a simplified, computationally cheap representation of the climate system response to anthropogenic forcings.

Has been developed, tested and applied for more than twenty years now (Santer et al., 1990; MAGICC SCENGEN; many other simple or complex emulation methods)

Relies on the notion that a robust geographic pattern of change is constant
through a transient simulation, and the most significant difference as time goes by and GHG atmospheric concentration increase is the intensity of the change, which is to a first approximation proportional to global average temperature increase.



Temperature series plot courtesy of G. Strand

Simple Pattern Scaling

- T_{it} - T_{in} is the map of forced change at a given time t and location i during the simulation of a specific scenario of interest, using a given model.
- g_t - g_0 is the change in global average temperature under that particular scenario and model.
- β_i is the constant (in time) geographic pattern of change per degree of global average warming, independent of scenario and model. Once that is estimated all we need is a **simple model** able to simulate g_t .

$T_{i+} - T_{i} = \beta_i (g_+ - g_0) + \varepsilon_{i+}$

A Better Model

Accounting for variability

At each location i, fit a linear mixed-effects model to RCP 8.5 using Large Ensemble

$T_{ikt} - T_{i,0} =$

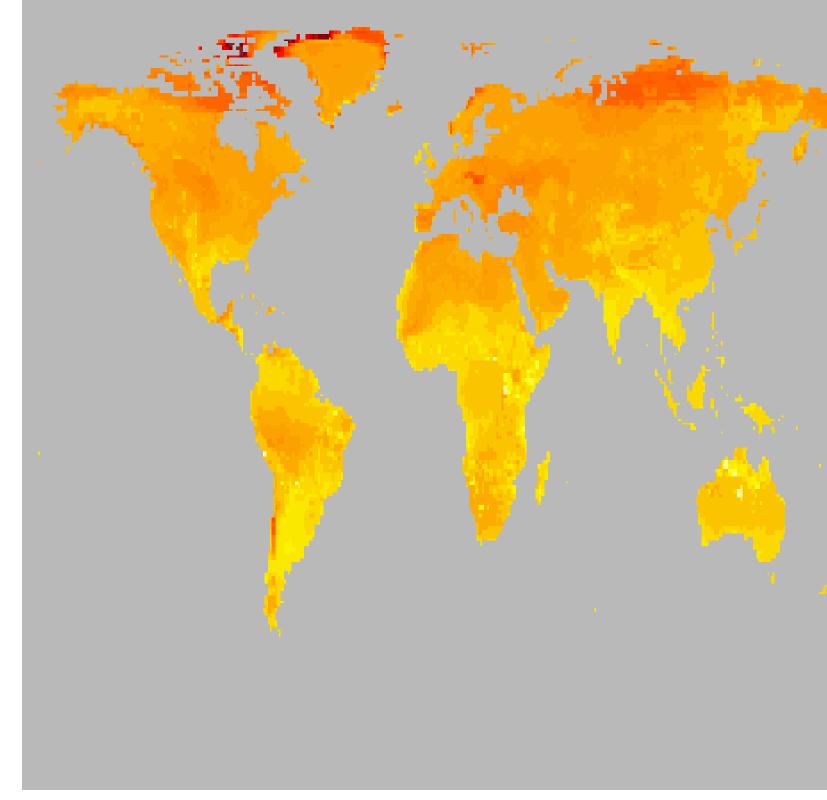
where k is the ensemble member

 $(eta_i) \cdot (g_t - g_0) + \epsilon_{ikt},$ $\epsilon_{ikt} \sim N(0, \sigma_i^2)$

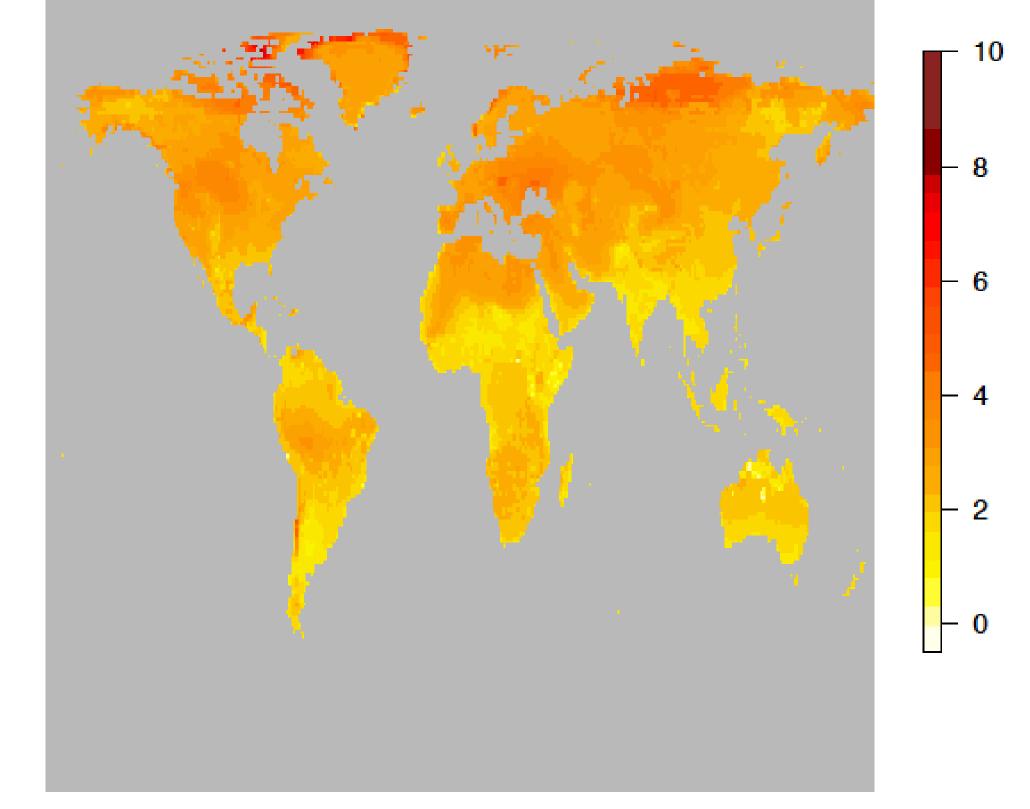
(Alexeeff et al., in review – BRACE special issue)

(As in Simple Pattern Scaling)

RCP4.5, 2060-2069, JJA

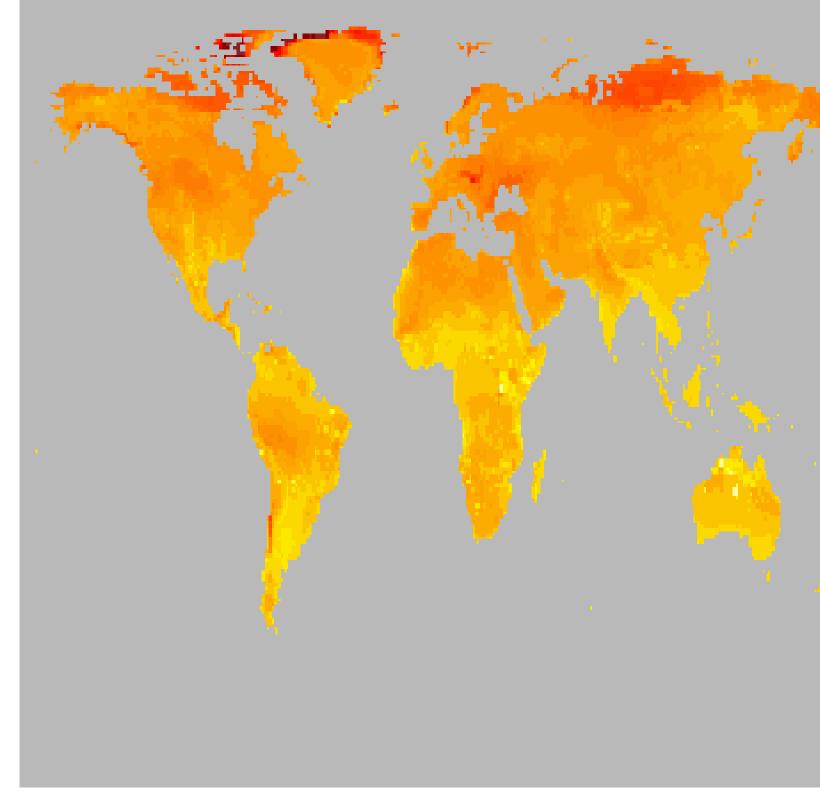


Emulated Mean, 2060–2069, JJA

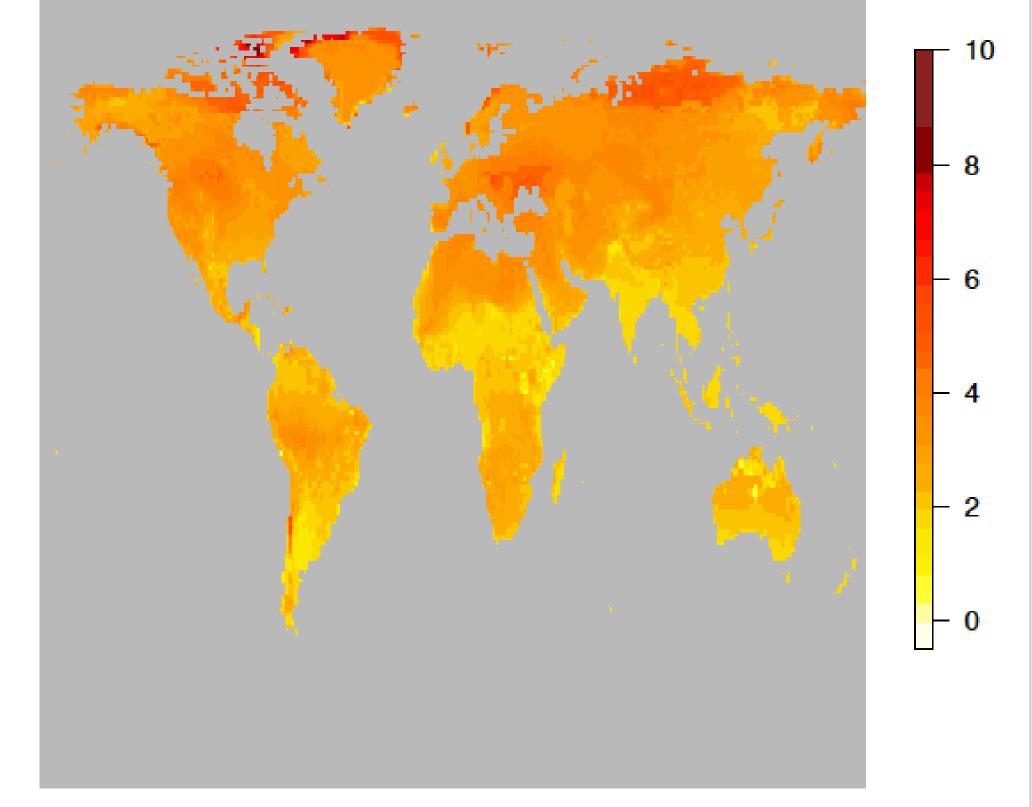


(As in Simple Pattern Scaling)

RCP4.5, 2070-2079, JJA

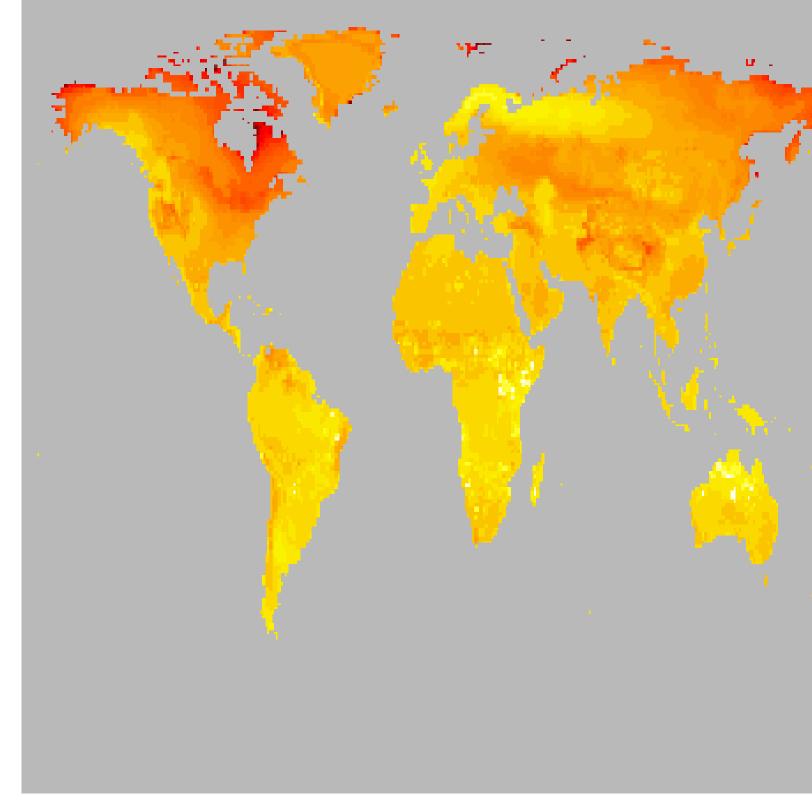


Emulated Mean, 2070–2079, JJA

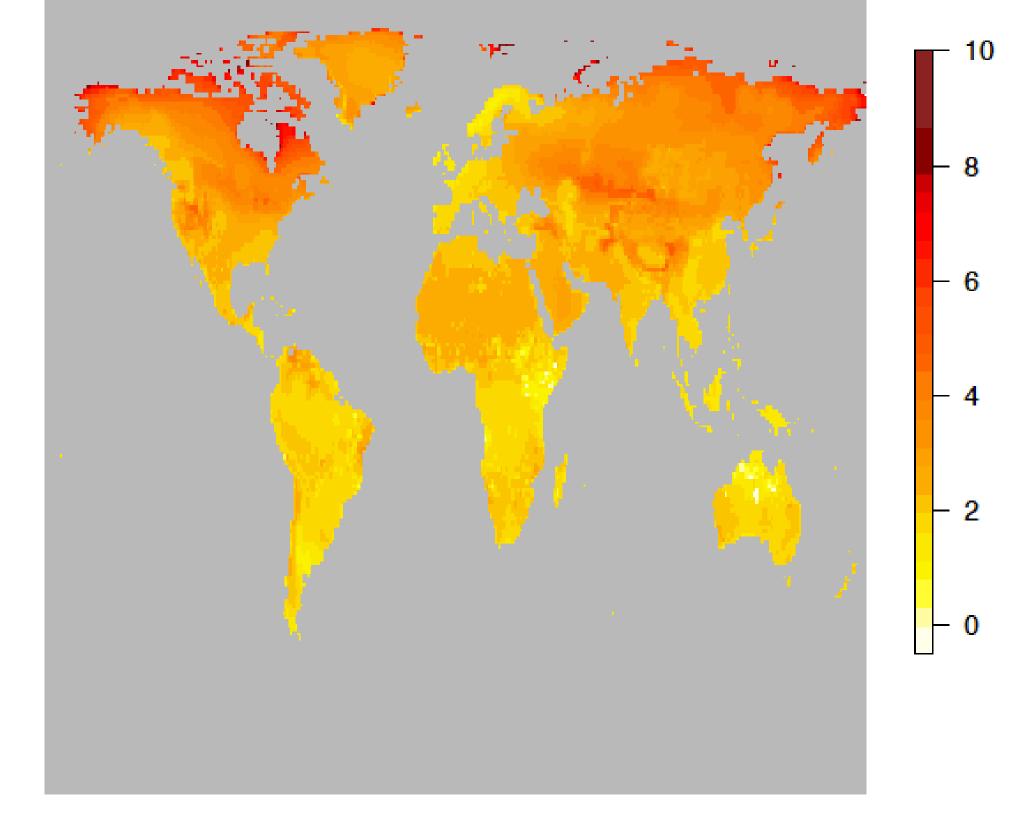


(As in Simple Pattern Scaling)

RCP4.5, 2060-2069, DJF

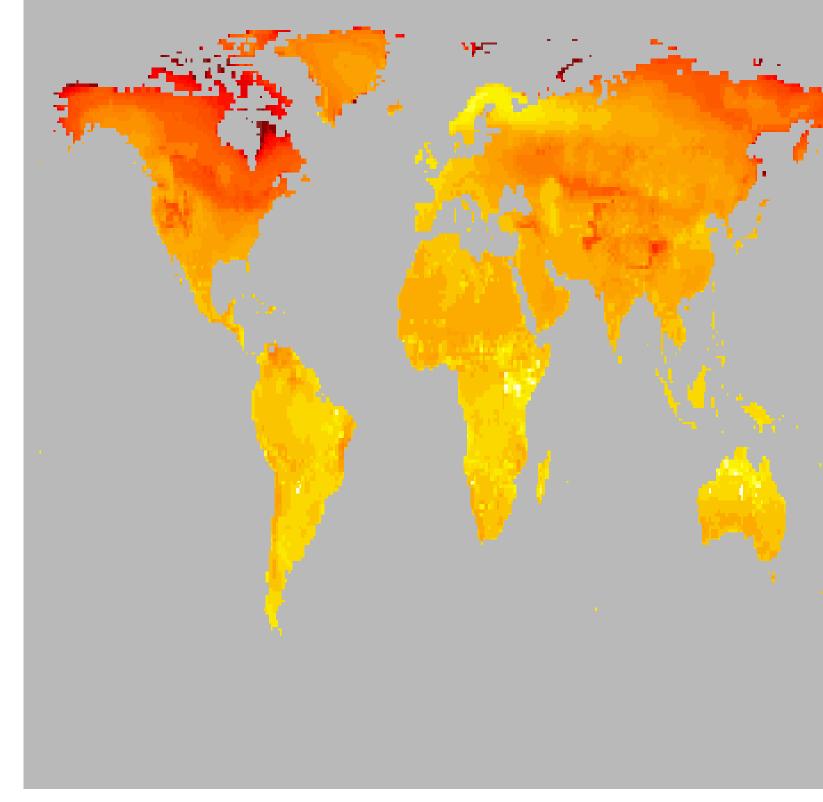


Emulated Mean, 2060–2069, DJF



(As in Simple Pattern Scaling)

RCP4.5, 2070-2079, DJF



Emulated Mean, 2070–2079, DJF

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A Better Model

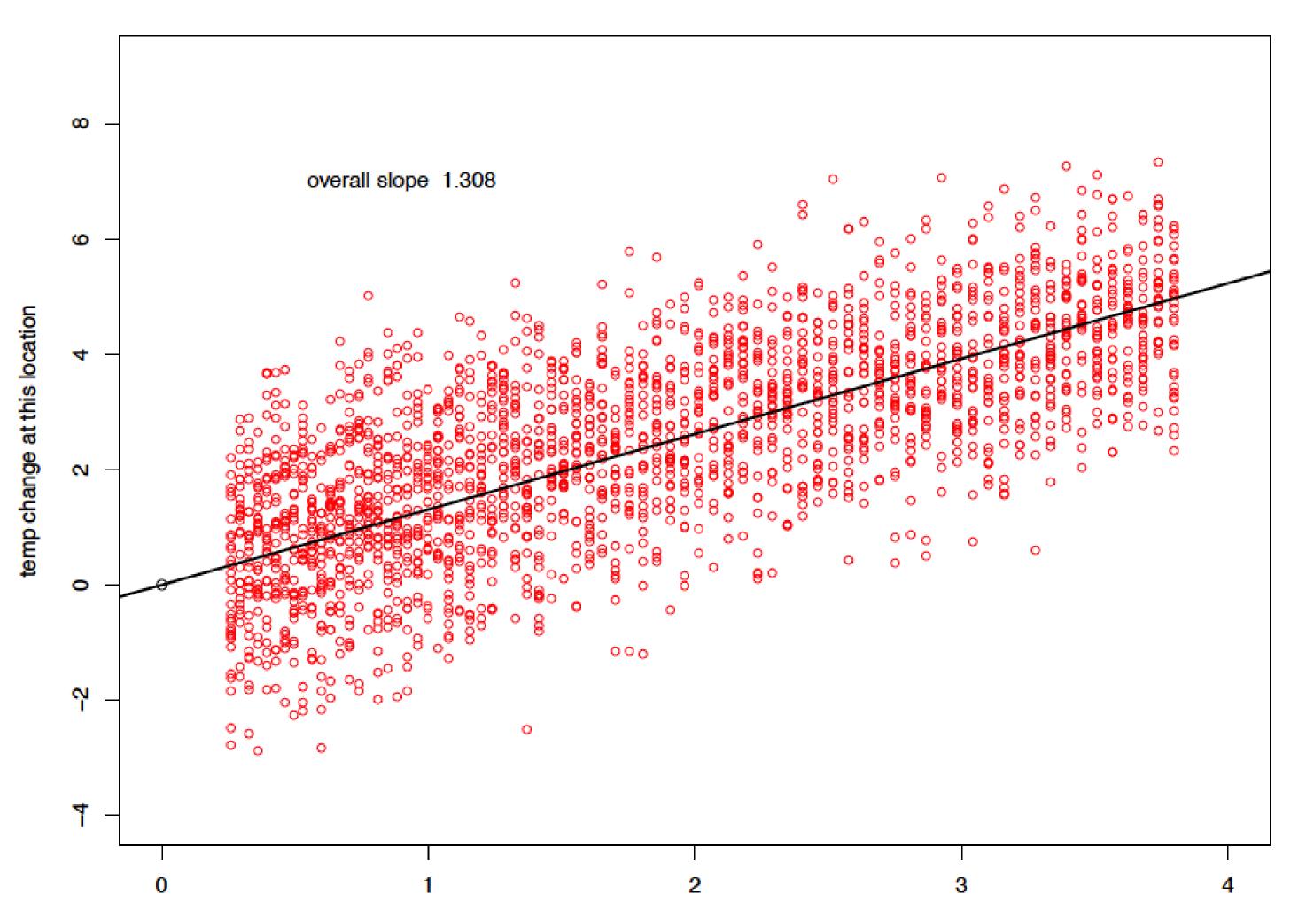
Accounting for variability

At each location i, fit a linear mixed-effects model to RCP 8.5 using Large Ensemble

$T_{ikt} - T_{i,0} =$

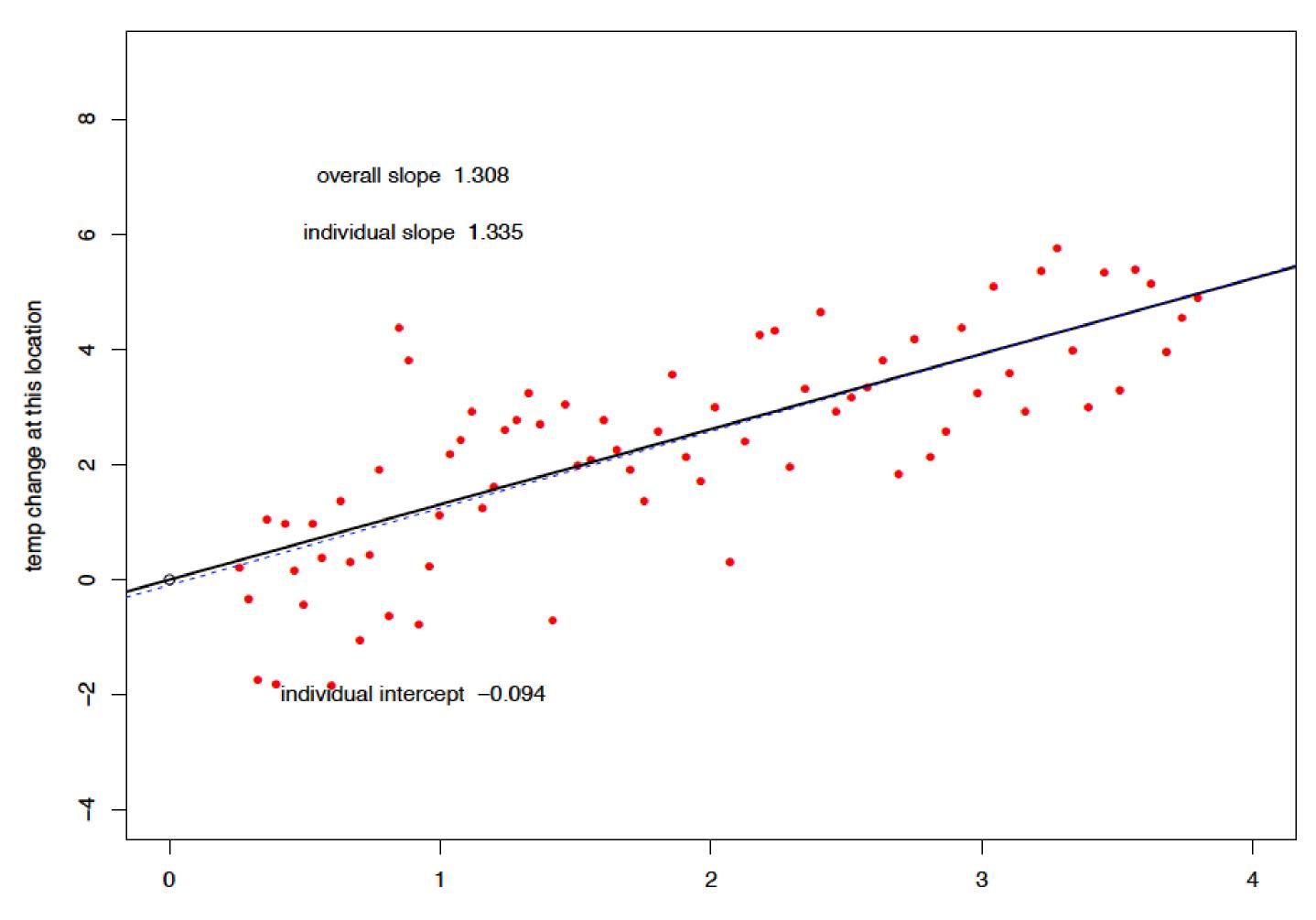
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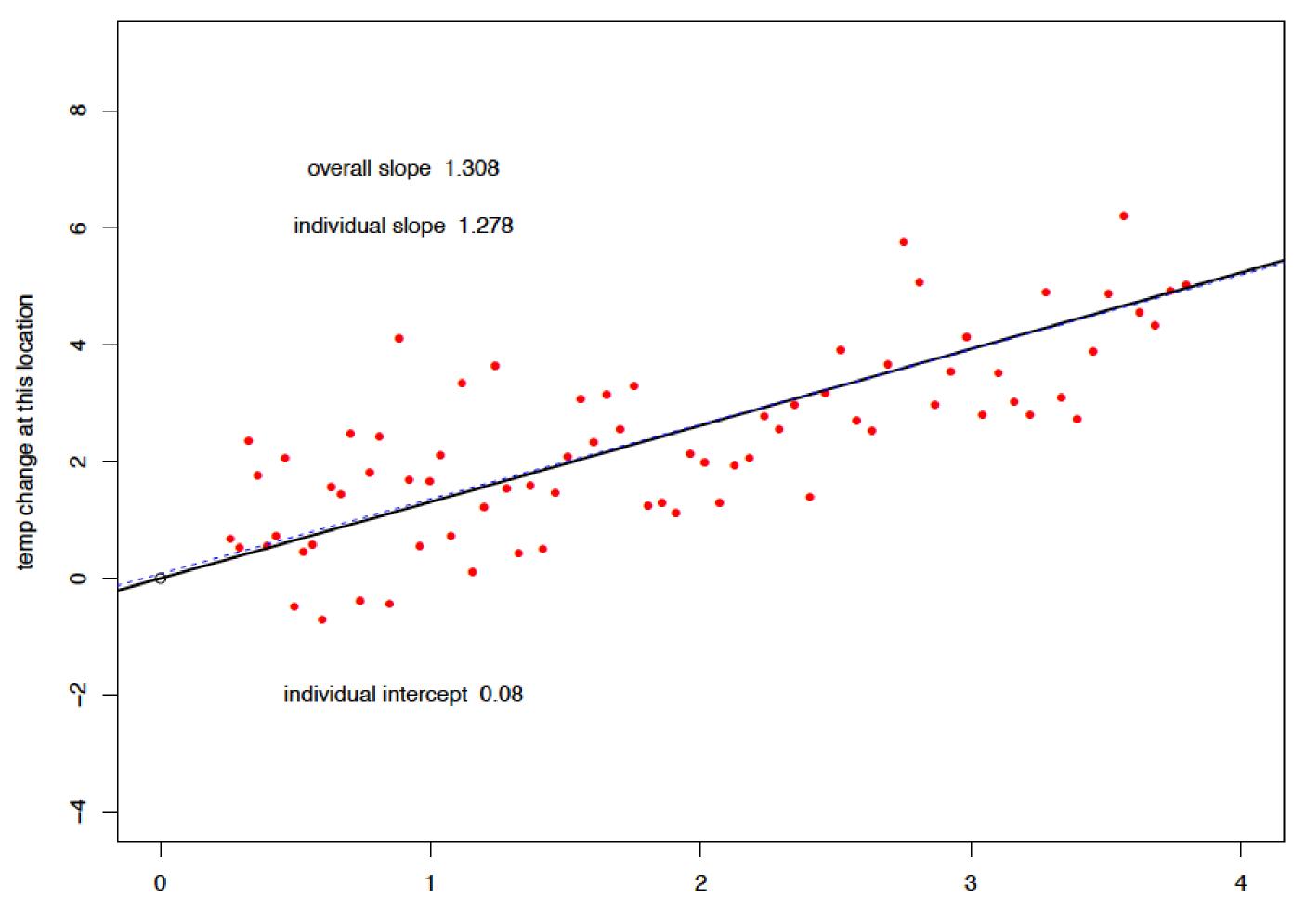


global temp change

Boston, MA in winter (DJF)



Boston, MA in winter (DJF)



Boston, MA in winter (DJF)

Emulating a different RCP

To generate pseudo-ensemble m

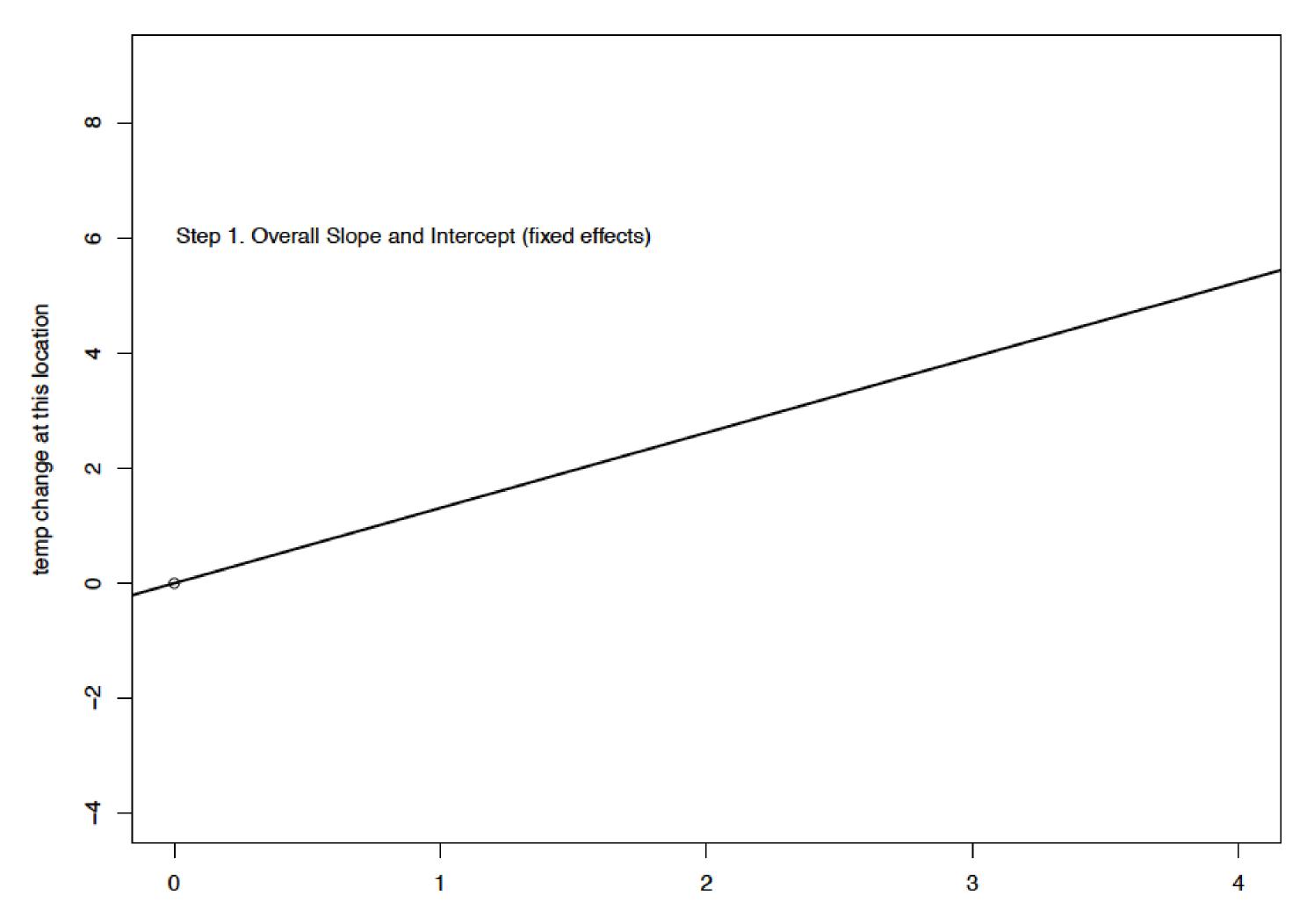
$$\tilde{T}_{it}^{(k)} = T_{i,0} + (\hat{\alpha}_i + \tilde{a}_i^{(k)}) + (\hat{\beta}_i + \tilde{b}_i^{(k)}) \cdot (g_t - g_0) + \tilde{\epsilon}_{it}^{(k)}$$

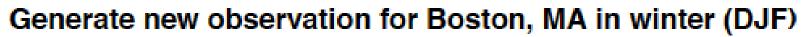
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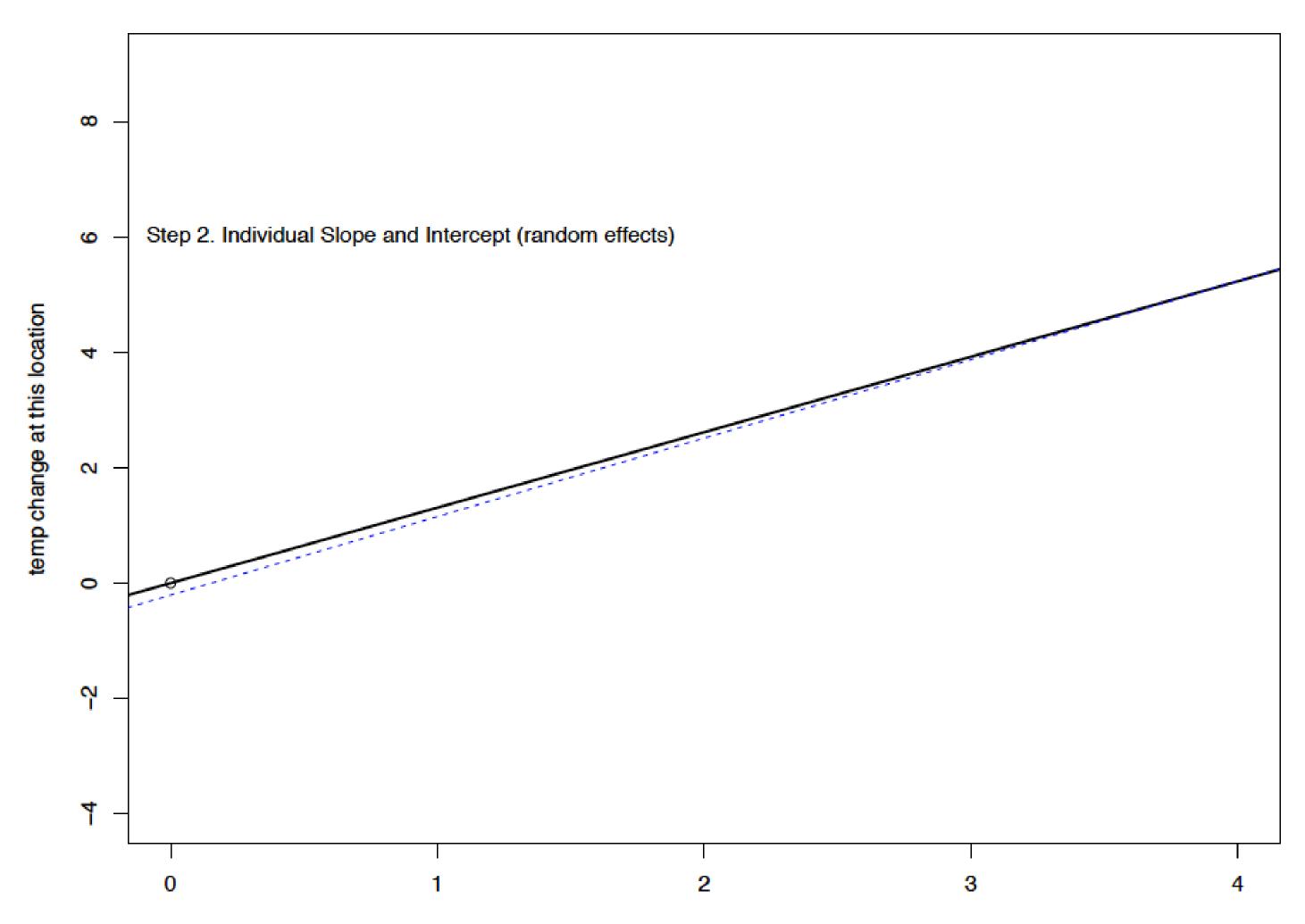
 g_t is the global average temperature change under the different RCP Where and $\tilde{a}_i^{(k)} \sim N(0, \hat{\tau}_{a,i}^2)$ $\hat{\alpha}_{i}, \hat{\beta}_{i}, \hat{\tau}_{a,i}^{2}, \hat{\tau}_{b,i}^{2}$ are estimated from the model fit $\tilde{\epsilon}_{it}^{(k)}$ we generate by resampling the residuals

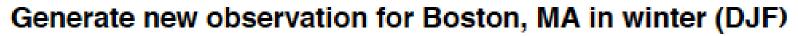
embers
$$\tilde{T}_{it}^{(k)}$$

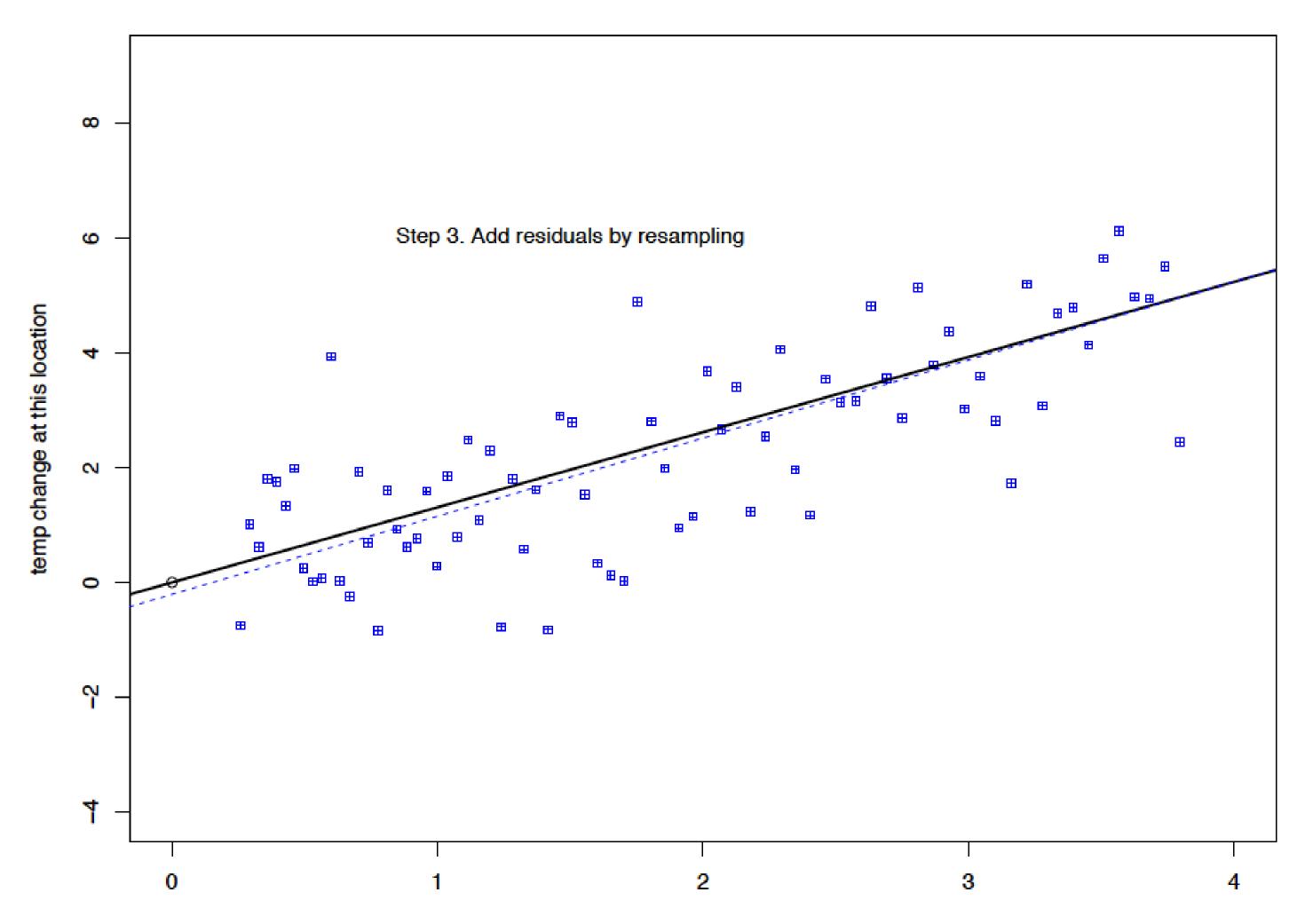
),
$$\tilde{b}_i^{(k)} \sim N(0, \hat{\tau}_{b,i}^2)$$

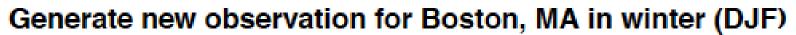


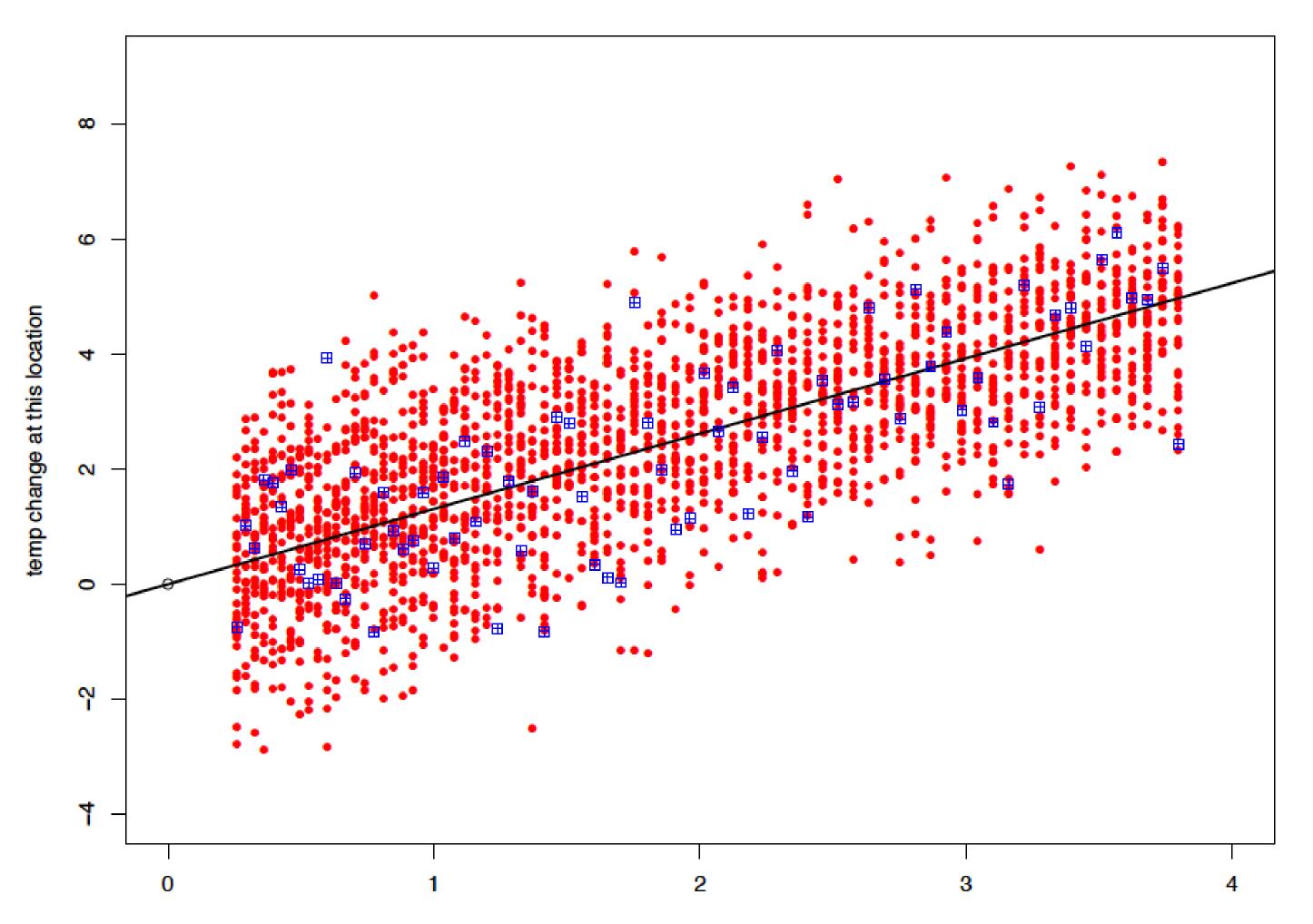












Generate new observation for Boston, MA in winter (DJF)

Resampling of the Residuals

What to consider

entire spatial field of residuals

Temporal autocorrelation: we preserve it by sampling a – short – time window

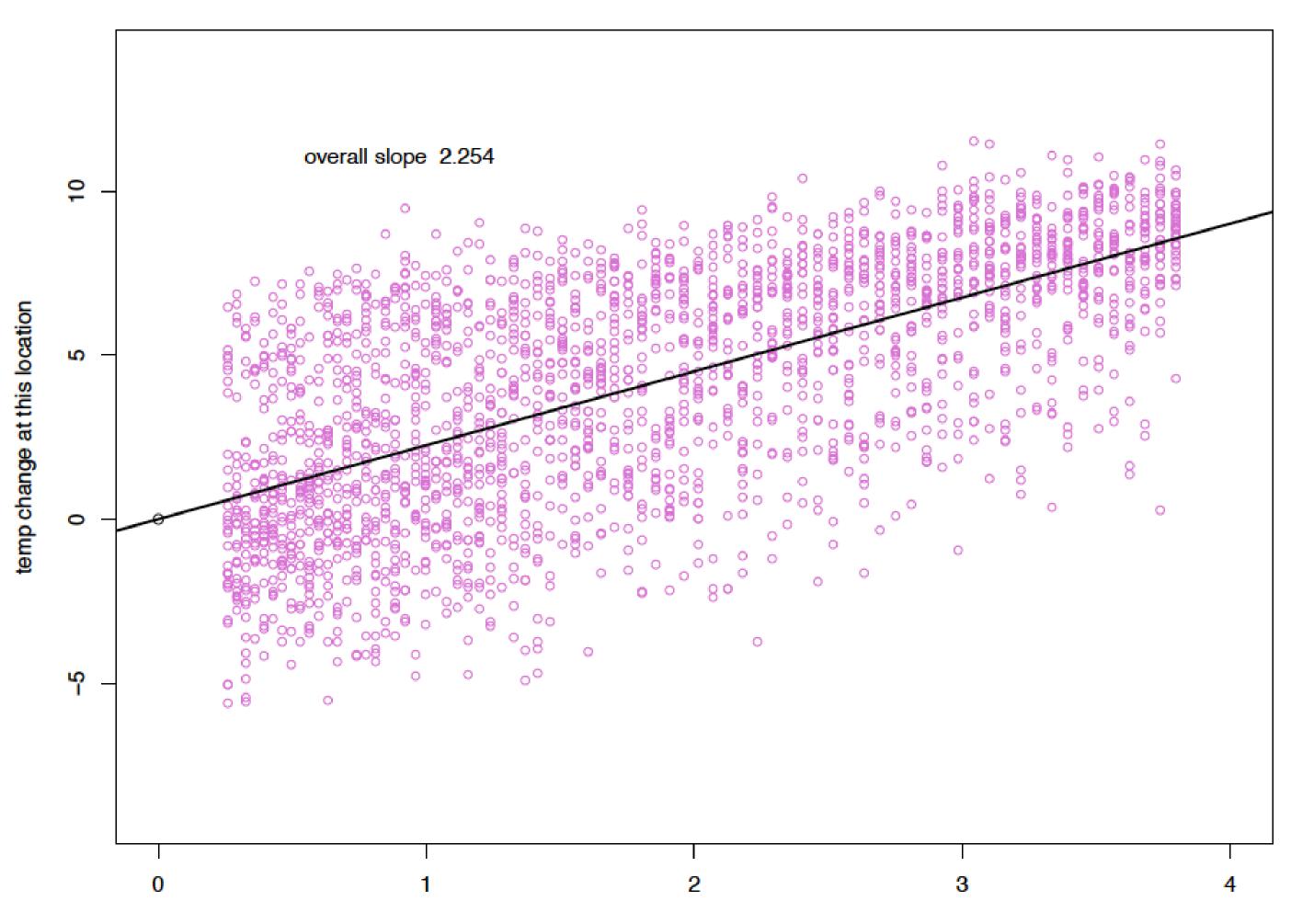
the value of global mean temperature



Spatial correlation for a given ensemble member and year: we preserve them by sampling the

Long-term temporal trends in variance: we preserve it by sampling that window conditionally on

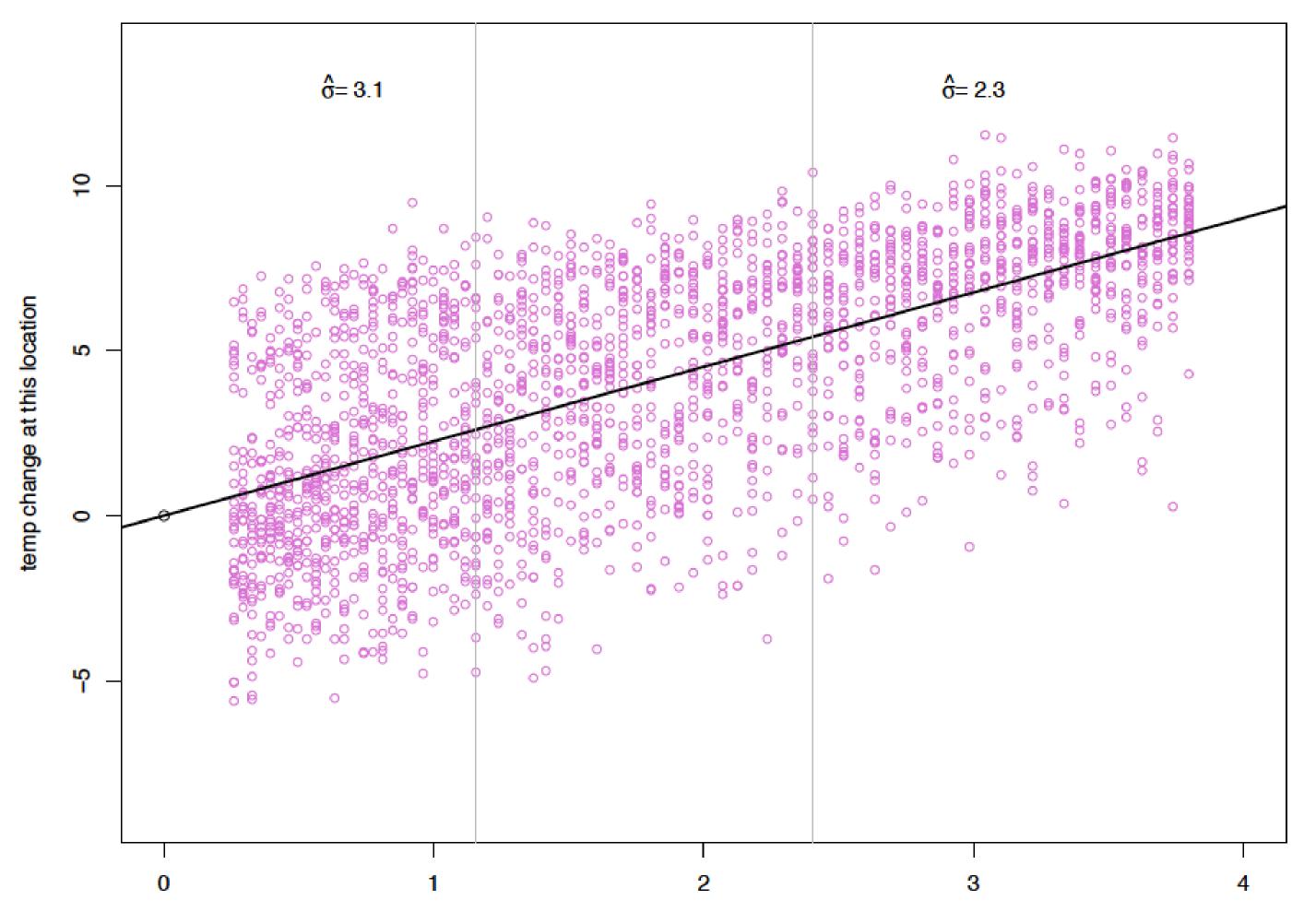
Zooming in on another gridpoint



Salt Lake City, UT in winter (DJF)

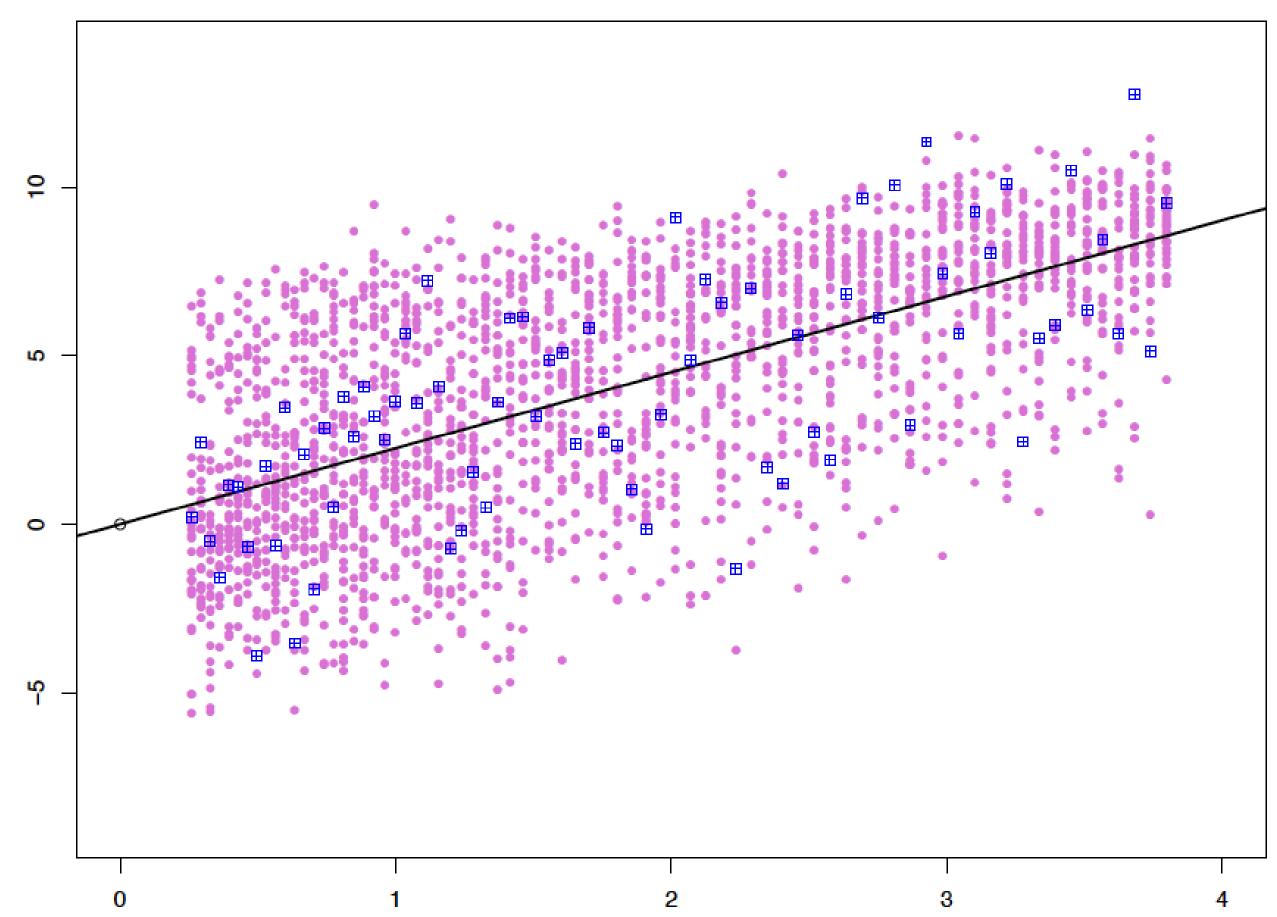
Zooming in on another gridpoint

Salt Lake City, UT in winter (DJF)



Zooming in on another gridpoint

Generate new observation for Salt Lake City, UT in winter (DJF)



temp change at this location

The devil is in the details

Spatial processes (remember those randome effects?) have to account for non-stationarity and peculiar features (continents vs. oceans, high vs. low latitudes) and need to be estimated over a large (cylindrical) grid (typically T42, ~8000 grid points).

coherence for input to impact models

Parameters should be valid for multiple models, allowing us to simulate new models and new scenarios.

• Simulation should be joint for temperature and precipitation and across seasons to provide not only geographic, but also temporal and climatologic

- Joint Temperature/Precipitation/Other variables? Which ones? Seasonally-consistent modeling
- Downscaling to daily time resolution
- Modeling of regional effects from aerosols/land use
- **Emulators for extremes**

Hyper-parameterization to characterize the CMIP family of GCMs

Who is going to do it? NCAR?

- Workshop on Pattern Scaling and emulators (Spring 2014)
- Lessons learned: need for cataloguing, systematizing, identifying specific needs (variables/time scales) for a range of impact modeling
- **Review papers in preparation**
 - In-house Expertise and Resources
- Climate modeling and Analysis, Integrated Assessment Modeling, Scenarios, Statistics, Computational Power and Methods
- Linkages: TGICA, ICONICS, ScenarioMIP, SAMSI, MetOffice