The Rationale for **Developing Neural Network Emulations for CAM5** and CESM1/CAM5

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Background – 1

- Any parameterization of model physics can be reproduced (emulated) to a very high accuracy using Neural Network (NN)
- A "representative" training dataset consisting of "inputs" (the "intent in" variables) and outputs (the "intent out") variables that appear in a parameterization should be given to train NN.
- "Representative" set spans the range of variation that one expects the parameterization to be subjected to. It can be created using model simulated data.
- We call such a NN emulation a "parameterization emulator"

Background – 2

- "A posteriori" corrections to the NN emulation to guarantee, for example, that the heating rates and fluxes are internally consistent, can be introduced.
- Parameterization emulator is carefully tested:
 - on independent (not used for training) set of simulated data
 - in parallel runs: (1) Control run (model with the original parameterization) and (2) NN run (model with the NN emulation)
- Several methods have been developed to control the accuracy of the NN emulation and correct it during the model run.
- NN emulation can be adjusted to climate changes
- This method has been applied to develop:
 - NN emulation of CAMRT long- and short wave radiation
 - NN emulation of RRTM long- and short wave radiation in NCEP CFS
 - NN based convection parameterization using CRM data
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Pros and Cons

- Pros
 - one can develop an NN "emulation" of a parameterization that is indistinguishable from the original parameterization, but is one to two orders of magnitude faster than the original, which can be used to:
 - Speed up the model integration (~25% for NCEP CFS) T126L64)
 - Increase the frequency of radiation calculations (e.g., calculate it every time step)
 - Use ensemble of NNs (perturbed and stochastic physics)
 - Increase model resolution, etc
- Cons
 - Is not physically transparent as the original parameterization is
 - Should be retrained after major changes in the model (e.g., after a change of vertical resolution). 6

Conclusions

- Several NN emulations of model physics have been successfully developed:
 - NN emulation of CAMRT long- and short wave radiations (Krasnopolsky et al., MWR, 2005 and 2008)
 - NN emulation of RRTM long- and short wave radiations in NCEP CFS (Krasnopolsky et al., MWR, 2010)
 - NN based convection parameterization using CRM data
- The approach is carefully tested and ready for "production" (including NN ensembles)
- Why would you not adopt such a strategy for CAM5 and CESM1/CAM5?

Additional Slides

FAQ

- **Q:** Why ECMWF uses NeuroFlux for 4D-Var only but not for NWP?
- A: Because NeuroFlux has many limitations related to its design (Morcrette et al., 2008) and also (Krasnopolsky et al. 2005):
 - both accuracy and rapidity could not be kept at once at higher vertical resolution (60 and more layers)
 - The accuracy in the lowest and uppermost atmospheric layers is not satisfactory due to the increased non-linearity there.
- Our NN emulation approach is different and free of the above limitations so that it has been successfully applied to:
 - LWR and SWR for CAMRT and NCEP CFS RRTM
 - Currently it is being applied to convection
 - Works with high vertical resolution
 - Is significantly more accurate and faster
 - Provides a better Jacobian
 - Allows using NN ensembles as stochastic physics to reduced uncertainties

Evaluation of NN emulation

- Validation on independent set of simulated data:
 - Accuracy of approximation
 - Speed up (code by code comparison)
- Validation in parallel runs:
 - (1) Control run (model with the original parameterization) and (2) NN run (model with NN emulation)
 - Differences are evaluated and are comparable with:
 - Observation errors
 - Uncertainties of reanalysis
 - Model "internal variability"

Radiation – a computational bottleneck

- Cost of the radiation is a problem for GCMs, NWP and other models:
 - ECMWF calculates radiation on a coarse grid and then interpolates horizontally to a fine grid
 - Canadian operational model calculates radiation at reduced vertical resolution and then interpolates vertically
 - NCAR, NCEP and UKMO calculate radiation less frequently then other model components

Background

 Any parameterization of model physics is a relationship or MAPPING (continuous or almost continuous) between two vectors: a vector of input parameters, X, and a vector of output parameters, Y,

 $Y = F(X); \quad X \in \Re^n \text{ and } Y \in \Re^m$

 NN is a generic approximation for any continuous or almost continuous mapping given by a set of its input/output records:

SET =
$$\{X_i, Y_i\}_{i=1,...,N}$$

Fast and Accurate Neural Network Radiation

- Fast NN emulations of LWR and SWR:
 - Are very accurate; the changes they introduce in the model results are of the order of the model "internal variability"
 - Reduce significantly (one to two orders of magnitude) the computation cost of radiation
 - Improve the load balance
- NN radiation is very flexible, the improved computational performance can be used to:
 - Speed up the model integration (~25% for NCEP CFS T126L64)
 - Increase the frequency of radiation calculations (e.g., calculate it every time step)
 - Use ensemble of NNs (perturbed and stochastic physics)
 - Increase model resolution, etc

Bulk Approximation Statistics (all errors are in K/Day)

| Statistics Types | Statistics | LWR | | | SWR | |
|--|------------|---------------------------|----------------------|-----------------------|------------------------|------------------------|
| | | NCAR CAMRT (L = 26) | NCEP CFS $(L = 64)$ | | NCAR CAM | NCEP CFS $(L = 64)$ |
| | | | RRTMG | RRTMF | (L = 26) | RRTMG |
| Total (3D) Error Statistics (K/day) | Bias | $3. \cdot 10^{-4}$ | 210-3 | 7. · 10 ⁻⁴ | $-4. \cdot 10^{-3}$ | 5. · 10 ⁻³ |
| | RMSE | 0.34 | 0.49 | 0.42 | 0.19 | 0.20 |
| Bottom Layer (2D) Error Statistics | Bias | -2. 10-3 | -110-2 | 6. · 10 ⁻³ | -5. · 10 ⁻³ | 9. · 10 ⁻³ |
| | RMSE | 0.86 | 0.64 | 0.67 | 0.43 | 0.22 |
| Top Layer Error (2D) Statistics | Bias | -1. · 10 ⁻³ | -9.·10 ⁻³ | $2. \cdot 10^{-3}$ | $2. \cdot 10^{-3}$ | 1.3 · 10 ⁻² |
| | RMSE | 0.06 | 0.18 | 0.09 | 0.17 | 0.21 |
| Speedup, η | Times | 150 | 16 (20) | 21 | 20 | 60 (90) |

Neural Network Continuous Input to Output Mapping

$Y = F_{NN}(X)$



Neuron
$$t_j = \tanh(b_j + \sum_{i=1}^n \Omega_{ji} \cdot x_i)$$

Major Advantages of NNs:

- NNs are generic, very accurate and convenient mathematical (statistical) models which are able to emulate numerical model components, which are complicated nonlinear input/output relationships (continuous or almost continuous mappings).
- NNs are *robust* with respect to random noise and faulttolerant.
- NNs are analytically differentiable (training, error and sensitivity analyses): almost free Jacobian!
- > NNs emulations are accurate and fast but there is

NO FREE LUNCH!

- Training is a complicated and time consuming nonlinear optimization procedure; <u>however, training should be done</u> <u>only once for a particular application!</u>
- NNs are well-suited for parallel and vector processing

Development of NN Emulations of Model Physics Parameterizations

Learning from Data

