

# MPAS AND CESM

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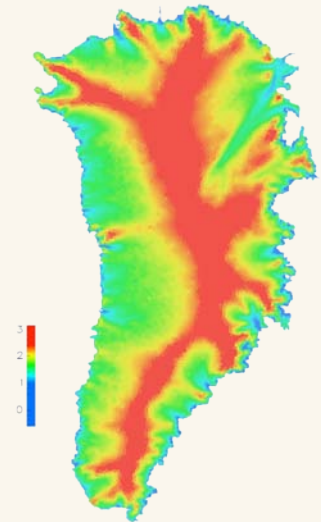
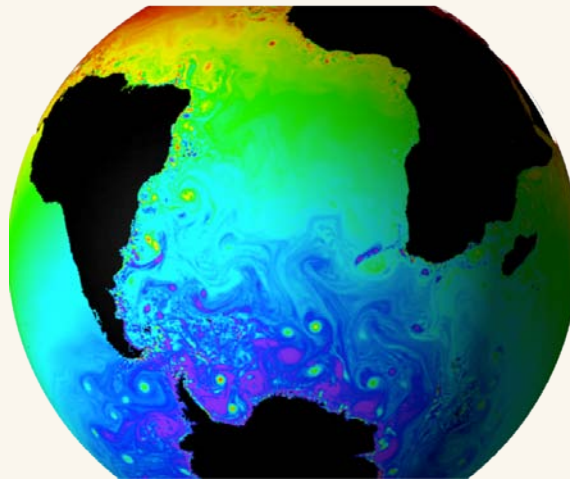
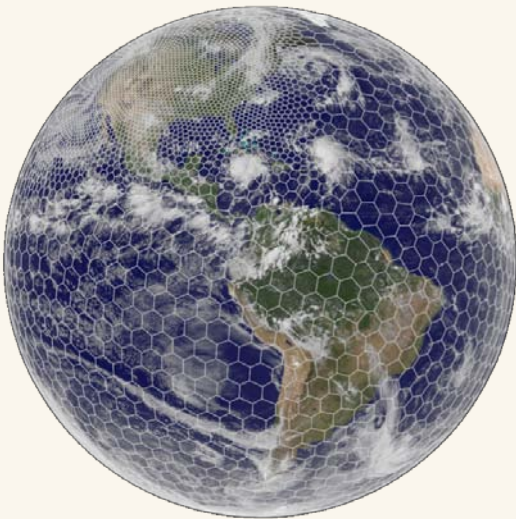
\*NCAR is funded by the National Science Foundation

# WHAT IS MPAS?

A collaboration between LANL (COSIM) and NCAR (MMM) to develop models for climate, regional climate, and NWP applications:

- MPAS-Atmosphere (NCAR)
- MPAS-Ocean (LANL)
- MPAS-Ice (LANL)
- MPAS framework, infrastructure (NCAR, LANL)

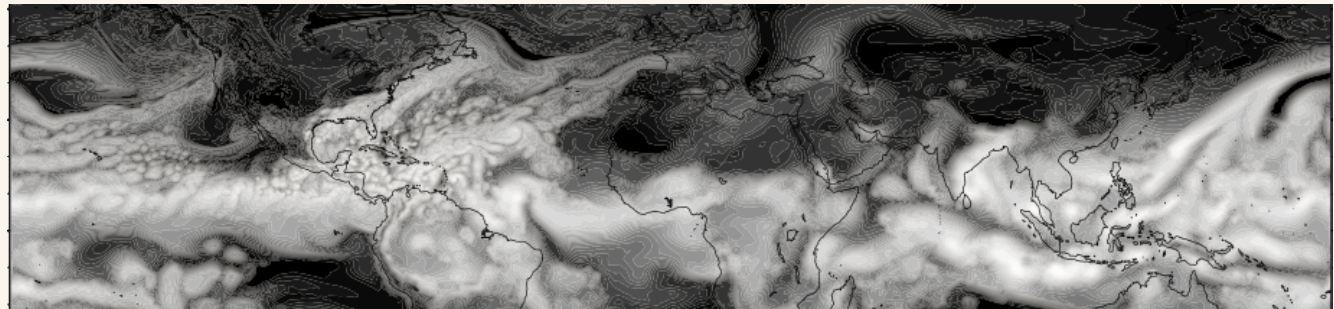
MPAS models are based on the centroidal Voronoi tessellation (CVT) with a C-grid staggering; models are conservative (total energy, mass, and potential vorticity)



# A BRIEF HISTORY OF MPAS DEVELOPMENT

- Code development began in late 2008
  - Mesh generation, simple toy framework, shallow water model
- Fall 2009: First version of hydrostatic atmosphere model
- Summer 2010: First version of non-hydrostatic atmosphere model
- **Summer 2010: Completed work for implementation of hydrostatic model in CAM**
- Current status
  - Real bathymetry ocean simulations
  - Real-data simulations in non-hydrostatic atmosphere core
  - **Initial testing of coupled simulations (F-configuration) using hydrostatic atmosphere core in CESM**

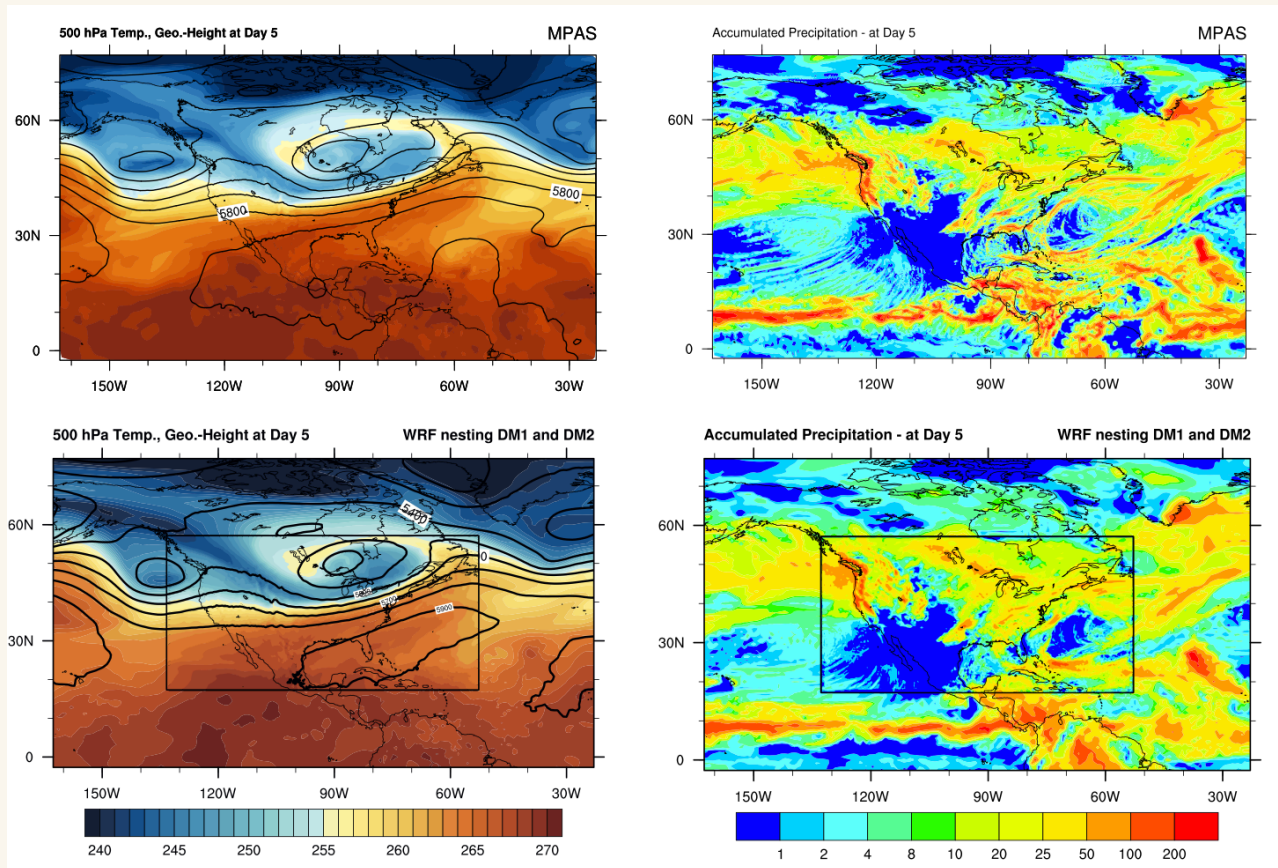
Lower-troposphere water vapor field from day 5 of an MPAS non-hydrostatic atmosphere simulation with ~160 km to ~21 km mesh refinement over North America



# CURRENT STATUS OF MPAS-A (NON-HYDROSTATIC)

Testing of multi-resolution atmospheric simulations has recently begun using realistic topography, land use, ICs, etc.

- Comparisons against WRF and analyses are encouraging



Cutout from an MPAS multi-resolution simulation (~92 km refined to ~25 km over the North American region)

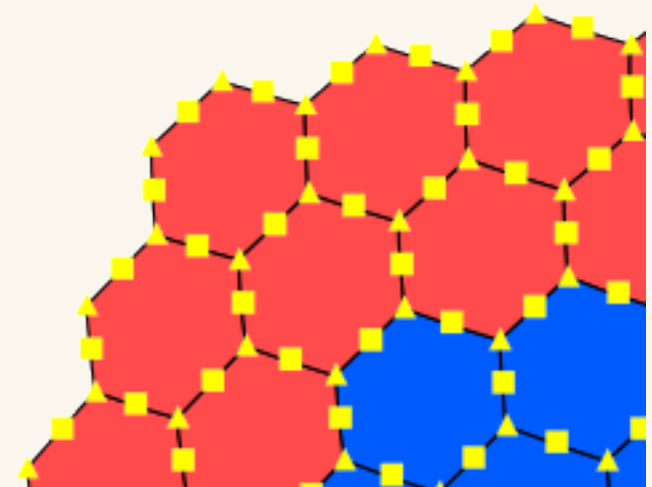
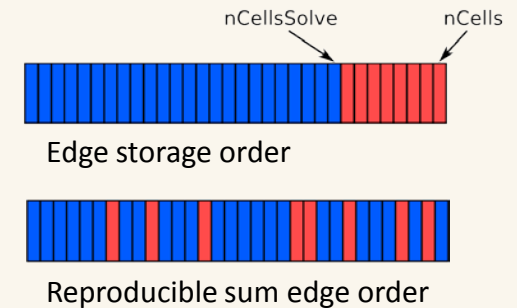
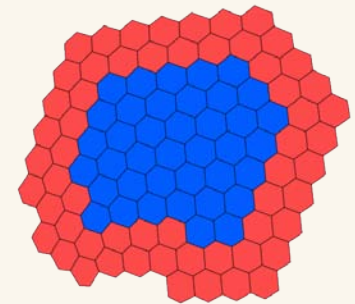
Cutout from a global WRF (90 km) simulation with a nest (30 km) over the boxed area

Figures from Fowler et al. "Cloud- and Global-Scale Simulations in MPAS and WRF," poster P.15, 12<sup>th</sup> WRF Users' Workshop.

# MPAS SOFTWARE STATUS AND ISSUES

- Bit-for-bit restartability (with physics in stand-alone MPAS-A)
  - Was simple to achieve
- Bit-identical results on different task counts (currently dynamics only in MPAS-A)
  - Required dealing with order-of-summation issues
  - Can be easily dealt with in ocean and hydrostatic cores, too
  - Changing to highlighted code gives ~11% performance hit on bluefire for the example loop shown below

```
do iEdge = 1,grid % nEdges
do iEdge1 = 1,grid % nEdges
iEdge = grid % edgePermutation % array(iEdge1)
do k=1,nVertLevels
circulation(k,verticesOnEdge(1,iEdge)) -= dcEdge(iEdge)
* u(k,iEdge)
circulation(k,verticesOnEdge(2,iEdge)) += dcEdge(iEdge)
* u(k,iEdge)
end do
end do
```

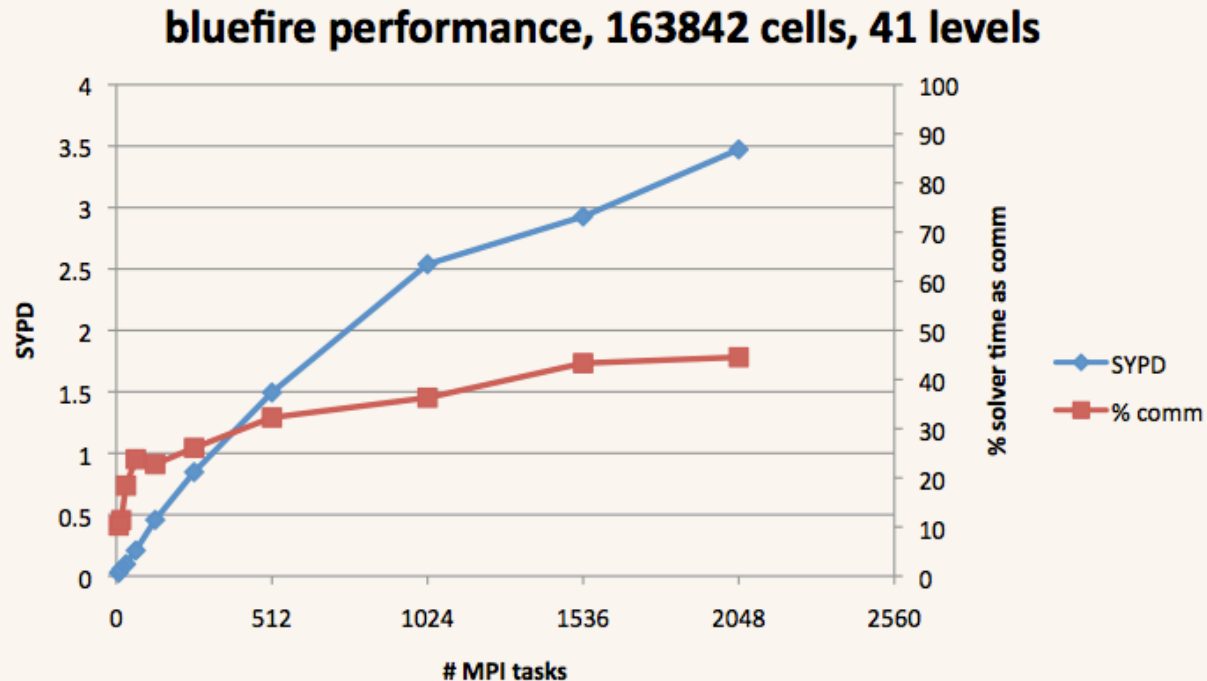




# MPAS SOFTWARE STATUS AND ISSUES

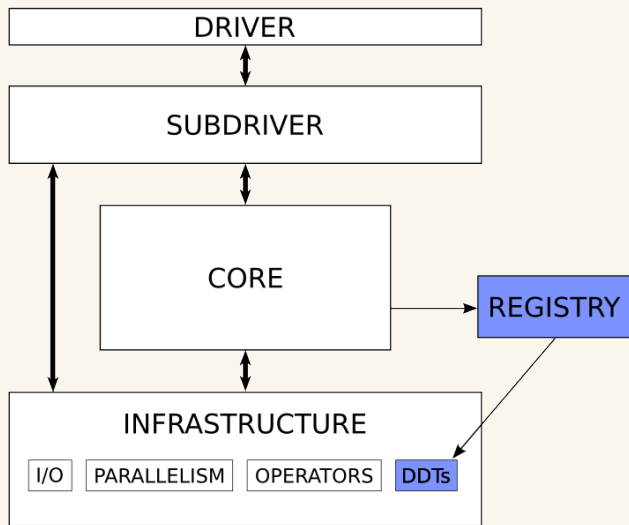
**NB: We've placed no emphasis on writing fast code so far! Correctness and rapid development have been foremost.**

Right: Initial performance for MPAS non-hydrostatic atmosphere core on bluefire with a ~60-km global mesh; times for dynamical solver only; SYPD assumes a 300 s time step.

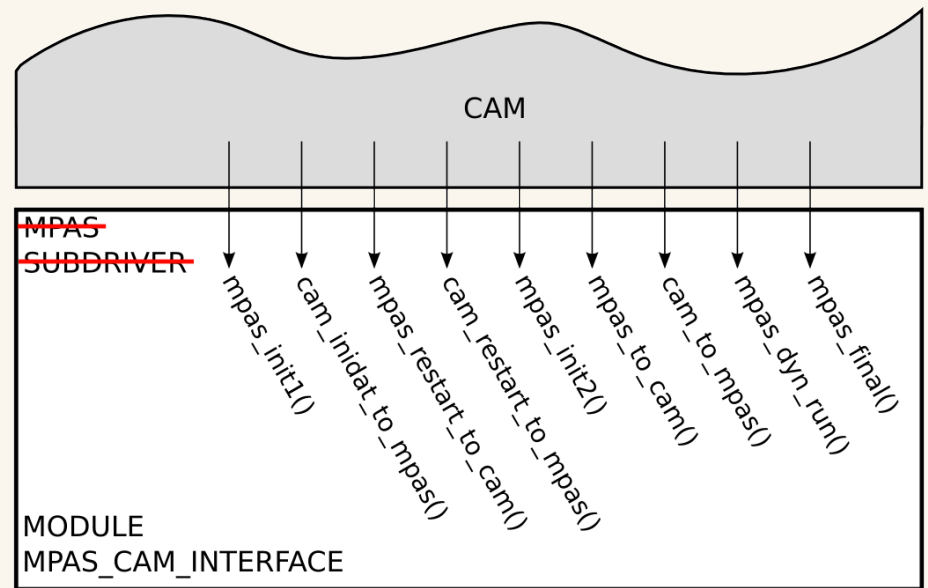


- Experience indicates that atmospheric solvers are about 2-3x slower than, e.g., CAM FV core
- What is considered good scaling on bluefire? Access to other hardware may be helpful
- My opinion: we have quite a few opportunities for improving performance and scalability in MPAS

# MPAS HYDROSTATIC CORE IN CAM



*Above: An idealized schematic of the MPAS software architecture*



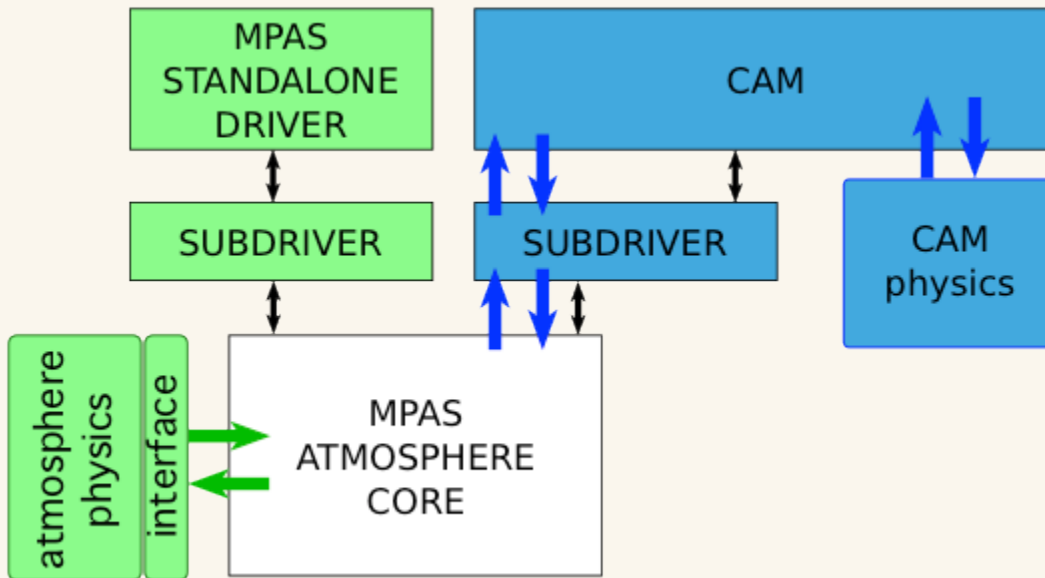
MPAS development essentially involved re-implementing the SUBDRIVER module with CAM-specific interface routines

- Some generalization to MPAS routines (e.g., optional MPI communicator argument to parallelism infrastructure init)

Import state	Export state	Control
cam_inidat_to_mpas cam_restart_to_mpas cam_to_mpas	mpas_restart_to_cam mpas_to_cam	mpas_init1 mpas_init2 mpas_dyn_run mpas_final

# MPAS HAS BEEN INTEGRATED INTO CAM

- A separate branch of the MPAS code has been used for integration work so far
  - The changes required in this branch should be merged back in to the MPAS trunk



**BLUE=code used when running MPAS in CAM,CESM**

**GREEN = code used when running stand-alone MPAS**

- When running MPAS hydrostatic core within CAM, physics tendencies are stored in tendency arrays; no calls through physics interface
- When running MPAS non-hydrostatic core, physics tendencies placed in tendency arrays within calls through physics interface



# MPAS HAS BEEN INTEGRATED INTO CAM

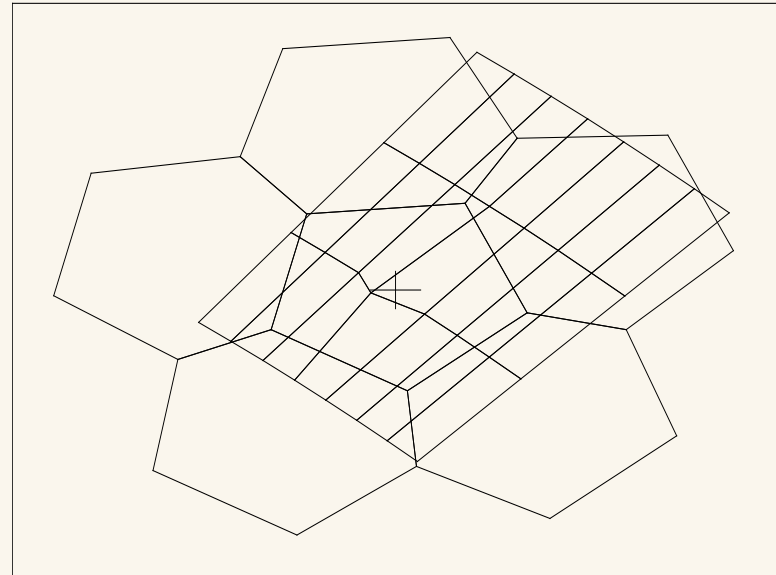
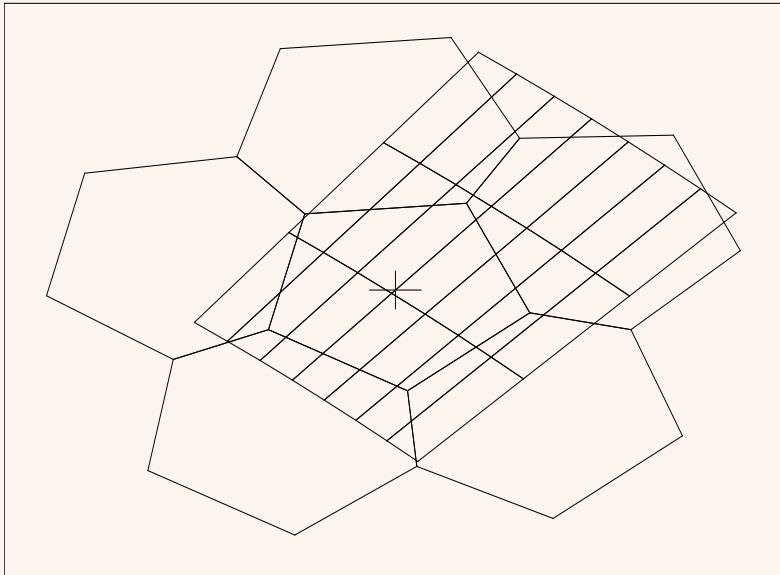
- Integration procedure similar to that of SE (HOMME) dycore
- CAM calls MPAS driver and interface routines
  - dynamics state transferred from MPAS to CAM
  - physics tendencies transferred from CAM to MPAS
- Physics evolves on MPAS grid
  - physics load-balancing options supported
- Vertical coordinate (eta-based) uses dry rather than total pressure
- Code validation
  - dynamics validated using Jablonowski/Williamson baroclinic wave test
  - physics validated by comparing tendencies with FV dycore
- Aqua-planet validation cases carried out on quasi-uniform grids of 120km, 60km and 30km, and on 60-120km locally refined grid

# CAM/MPAS HAS BEEN INTEGRATED INTO CESM

- This enables simulations with land (CAM/MPAS supports only aqua-planet scenarios)
- The only additional steps were to modify a few files in the *scripts* directory
- The code integration is based on cesm1\_0\_beta07
- Scrip was (initially) used to compute conservation remap files between the MPAS (1-deg; 40962 points) grid and both the land (0.9x1.25) and ocean (gx1v6) grids
- We carried out one-year CESM/MPAS demonstration case using the F-configuration (active land, prescribed sea-ice, data ocean)

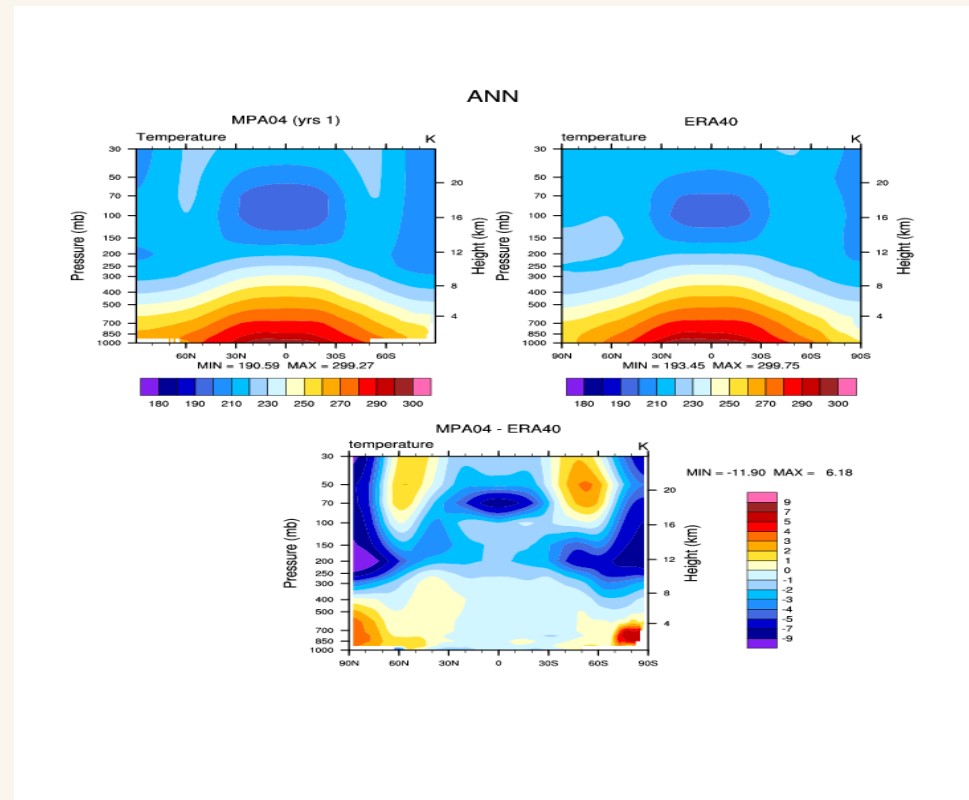
# WE ENCOUNTERED DIFFICULTIES REMAPPING TO GX1V6 GRID

- The ocean grid box boundary lies extremely close to north pole
- SCRIP has difficulty handling the polar singularity
- We moved a single ocean grid point towards a neighboring point to eliminate negative weights
- We subsequently discovered that the ESMF remapping utility does not exhibit the negative weight problem



# ACCOMPLISHED CESM/MPAS TRI-GRID DEMONSTRATION CALCULATION

- We carried out one-year CESM/MPAS demonstration case at 1-deg resolution using the F-configuration (active land, prescribed sea-ice, data ocean)
  - atmosphere – 40962 points
  - land – 0.9x1.25
  - ocean – gx1v6
- Post-processed with AMWG diagnostics package



# CONCLUSIONS

- MPAS hydrostatic atmosphere core has been implemented within CESM; initial testing has been done
  - Issues with vertical coordinate in physics and remapping have been addressed
- The mpas\_cam\_coupling branch should be merged with MPAS trunk
  - Plans are in place to merge MPAS branch of CAM onto the CAM repository trunk(?)
- Begin to examine and address performance and efficiency of dynamical cores
- **Consider changes to MPAS architecture to ease the implementation of the ocean and non-hydrostatic atmosphere cores in CESM**

