

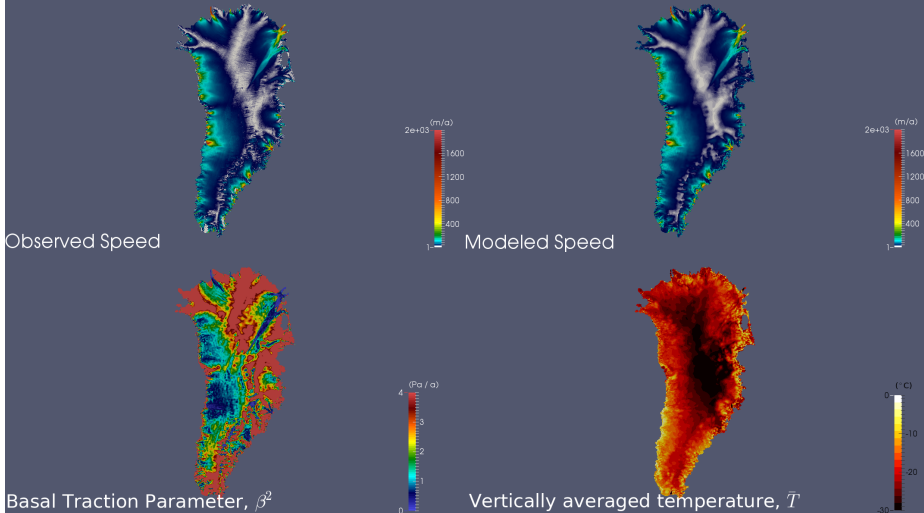
Using data assimilation methods to explore the role of longitudinal stress gradients in Greenland outlet glacier flow

Jesse V. Johnson, Douglas J. Brinkerhoff, Leigh Stearns, and Kees van der Veen

18 June, 2014
Breckenridge, Colorado

Data assimilation technique

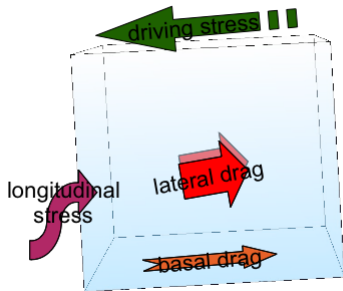
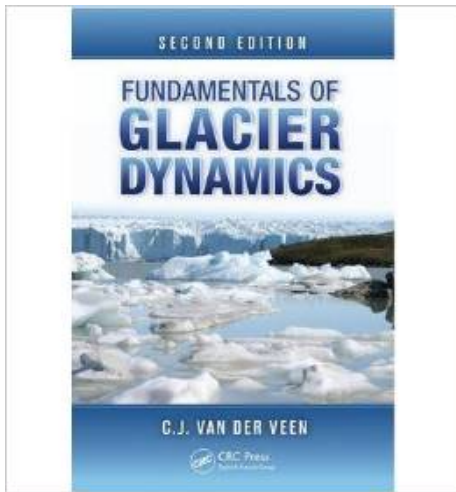
Determine the state of modern Greenland



- Surface velocity data provided by E. Rignot and J. Mouginot Geophysical Research Letters Volume 39, Issue 11, June 2012
- Surface temperature data from Ettema, J., van den Broeke, M. R., van Meijgaard, E., van de Berg, W. J., Bamber, J. L., Box, J. E., and Bales, R. C.: Higher surface mass balance of the Greenland ice sheet revealed by high-resolution climate modeling, Geophys. Res. Lett., 36, L12 501, <http://dx.doi.org/10.1029/2009GL038110>, 2009.
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Application of assimilation: Force Balance

After getting a little 'FOGD'



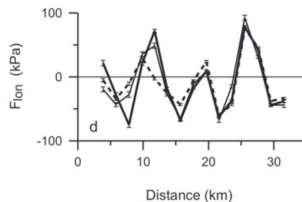
Application of assimilation: Force Balance

770

Journal of Glaciology, Vol. 57, No. 204, 2011

Controls on the recent speed-up of Jakobshavn Isbræ, West Greenland

C.J. VAN DER VEEN,^{1,2} J.C. PLUMMER,^{1,2} L.A. STEARNS^{1,3}



Question

Can data assimilation techniques provide more revealing force budget analyses?

Some reasons they might:

- smoothing of data provided by model, not ad-hoc.
- surface velocity not equal to depth averaged
- temperature dependant rate factors
- no residuals to close budget

Does a new force budget provide insights into glacier dynamics?

Coordinate transformation

Begin from a well known point

“Classic” vertically integrated flow equations (SSA)

Force balance in x direction

$$\frac{\partial}{\partial x} \left(2\nu H \left(2 \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(\nu H \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right) = \rho g H \frac{\partial z_s}{\partial x} - \beta^2 u$$

Force balance in y direction

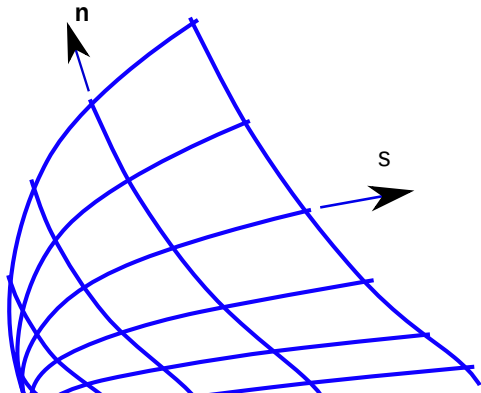
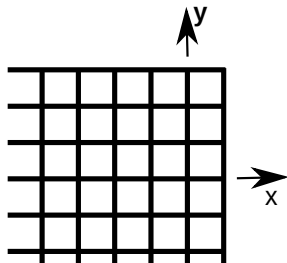
$$\frac{\partial}{\partial y} \left(2\nu H \left(2 \frac{\partial v}{\partial y} + \frac{\partial u}{\partial x} \right) \right) + \frac{\partial}{\partial x} \left(\nu H \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right) = \rho g H \frac{\partial z_s}{\partial y} - \beta^2 v,$$

Note that the xy coordinate system here has nothing to do with flow directions.

Coordinate transformation

Move to a more convenient coordinate system

- Define sn coordinate system.
- \mathbf{s} is along modeled flow direction,
- \mathbf{n} is across modeled flow.



Coordinate transformation

Along flow force balance

$$\frac{\partial}{\partial s} \left(2\nu H \left(2\frac{\partial \tilde{u}}{\partial s} + \frac{\partial \tilde{v}}{\partial n} \right) \right) + \frac{\partial}{\partial n} \left(\nu H \left(\frac{\partial \tilde{u}}{\partial n} + \frac{\partial \tilde{v}}{\partial s} \right) \right) = \rho g H \frac{\partial z_s}{\partial s} - \beta^2 \tilde{u}$$

and

Across flow force balance

$$\frac{\partial}{\partial n} \left(2\nu H \left(2\frac{\partial \tilde{v}}{\partial n} + \frac{\partial \tilde{u}}{\partial s} \right) \right) + \frac{\partial}{\partial s} \left(\nu H \left(\frac{\partial \tilde{u}}{\partial n} + \frac{\partial \tilde{v}}{\partial s} \right) \right) = \rho g H \frac{\partial z_s}{\partial n} - \beta^2 \tilde{v}$$

Coordinate transformation

Force balance procedure

- 1 Assimilate surface velocity by adjusting traction
- 2 Determine \mathbf{s} and \mathbf{n} vectors from assimilated velocity
- 3 Apply directional derivatives:

$$\frac{\partial \tilde{u}}{\partial \mathbf{s}} = \mathbf{s} \cdot \nabla \tilde{u}$$

And similar for other derivatives; $\frac{\partial \tilde{u}}{\partial \mathbf{n}}$, $\frac{\partial \tilde{v}}{\partial \mathbf{s}}$, $\frac{\partial \tilde{v}}{\partial \mathbf{n}}$

- 4 Substitute directional derivative for each term in along and across flow stress balance
- 5 Viscosity, η and β^2 from assimilation
- 6 Solve coordinate transformed SSA equations for \tilde{u} and \tilde{v}

Force budget in rotated coordinate system

Red terms are from assimilation, all partial derivative require directional derivative substitution

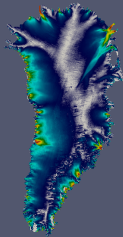
Along flow force balance

$$\underbrace{\frac{\partial}{\partial s} \left(2\nu H \left(2 \frac{\partial \tilde{u}}{\partial s} + \frac{\partial \tilde{v}}{\partial n} \right) \right)}_{\text{Longitudinal stress gradient}} + \underbrace{\frac{\partial}{\partial n} \left(\nu H \left(\frac{\partial \tilde{u}}{\partial n} + \frac{\partial \tilde{v}}{\partial s} \right) \right)}_{\text{Lateral stress gradient}} = \underbrace{\rho g H \frac{\partial z_s}{\partial s}}_{\text{Driving stress}} - \underbrace{\beta^2 \tilde{u}}_{\text{Basal drag}}$$

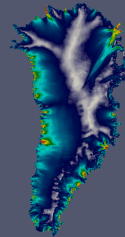
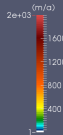
Across flow force balance

$$\frac{\partial}{\partial n} \left(2\nu H \left(2 \frac{\partial \tilde{v}}{\partial n} + \frac{\partial \tilde{u}}{\partial s} \right) \right) + \frac{\partial}{\partial s} \left(\nu H \left(\frac{\partial \tilde{u}}{\partial n} + \frac{\partial \tilde{v}}{\partial s} \right) \right) = \rho g H \frac{\partial z_s}{\partial n} - \beta^2 \tilde{v}$$

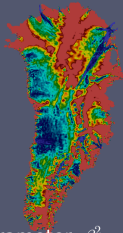
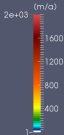
Across flow force balance is challenging to interpret!



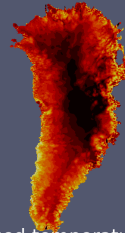
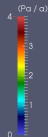
Observed Speed



Modeled Speed



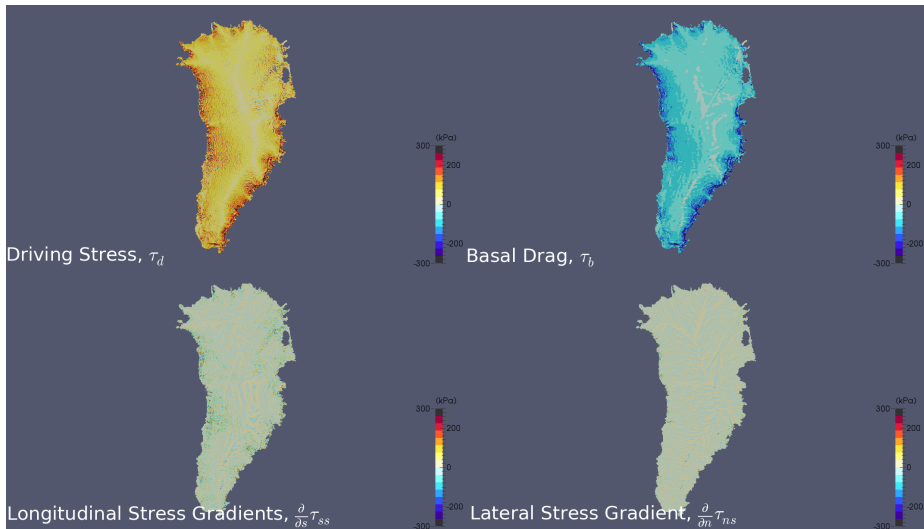
Basal Traction Parameter, β^2



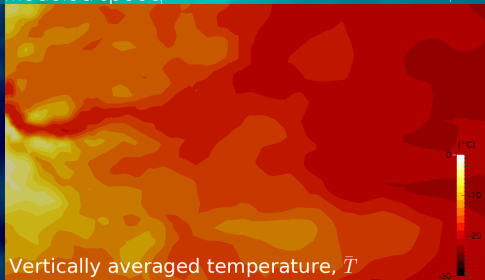
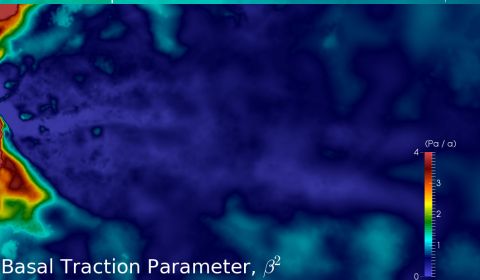
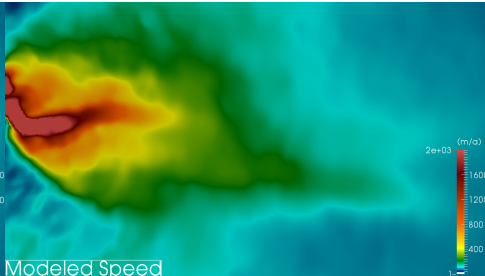
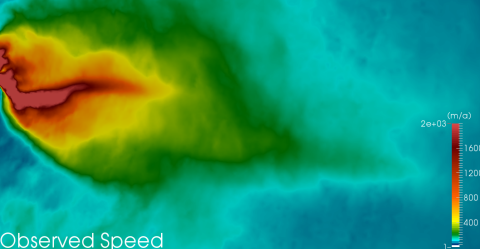
Vertically averaged temperature, \bar{T}



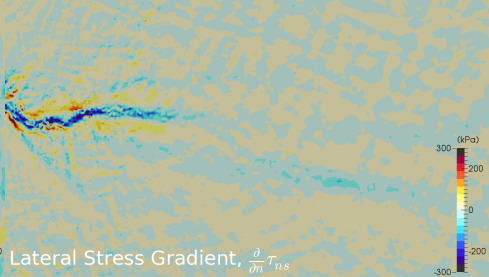
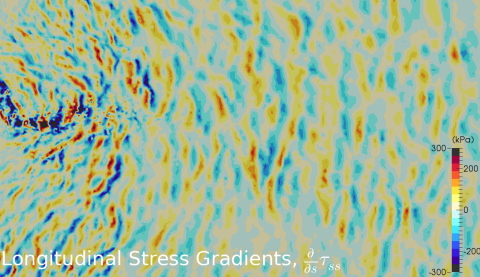
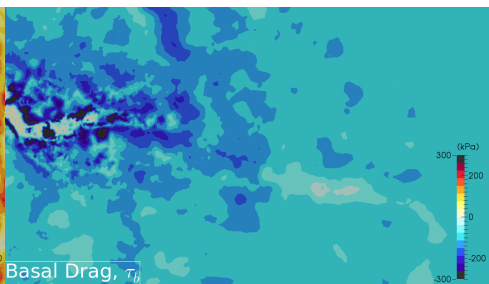
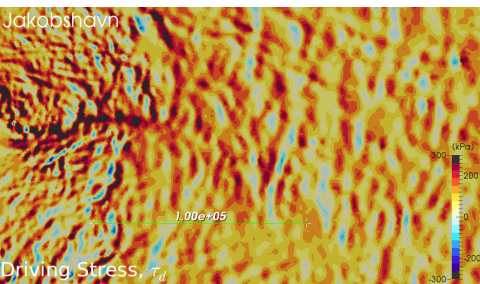
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Jakobshavn



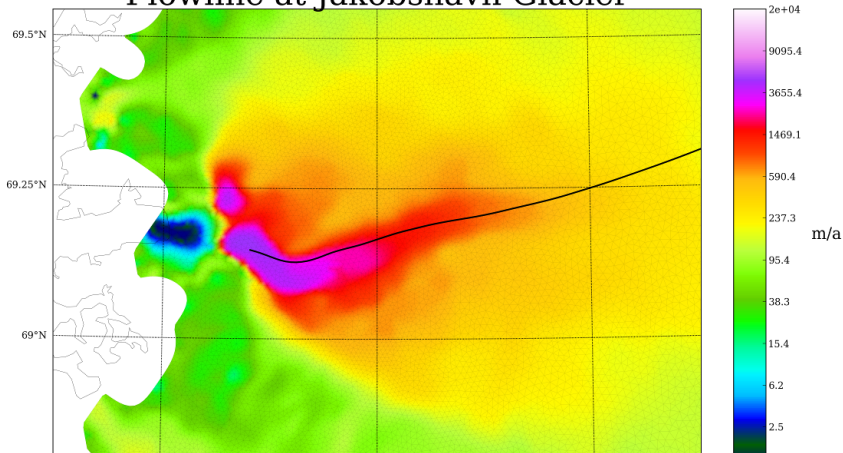
Jakobshavn



Evaluation along a flow line

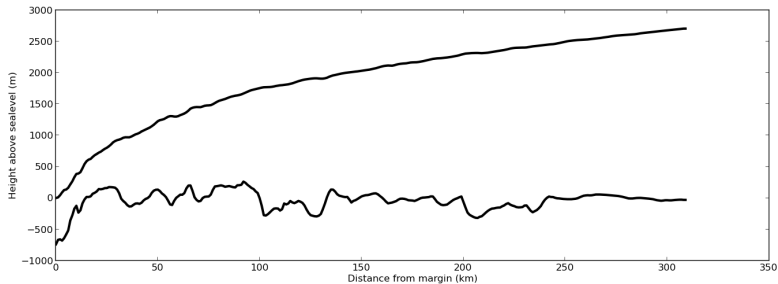
Simplify interpretation

Flowline at Jakobshavn Glacier



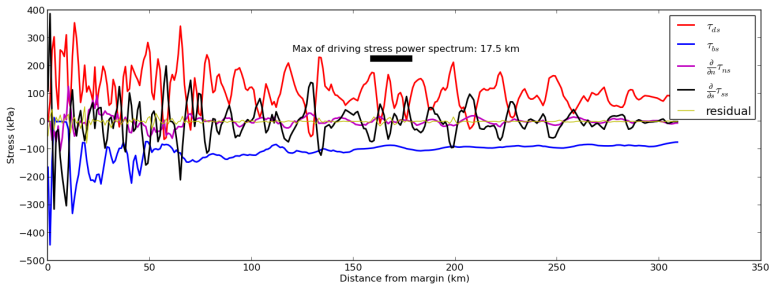
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Simplify interpretation



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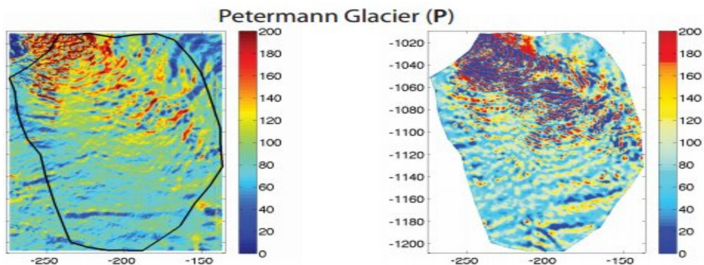


Conclusions

- Longitudinal stress gradients are a large part of the force budget
- These gradients vary very quickly and out of phase with driving stress.
- This is a highly local phenomena
- Speed up in Jakobshavns would depend on integral over coupling length, this is still small.
- Beyond back stress?

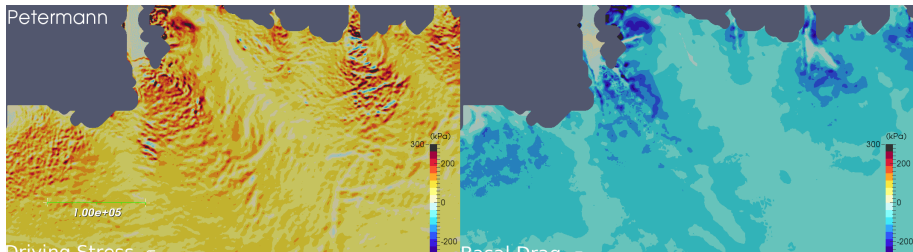
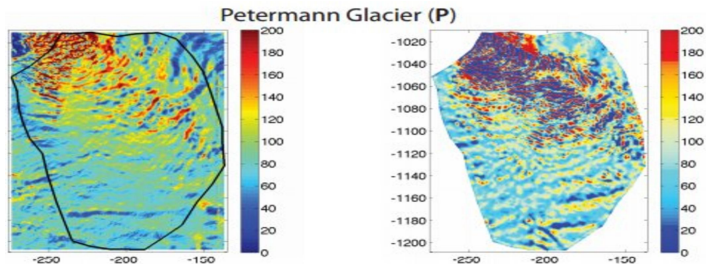
What about the rib-like features?

Can they be seen in our basal traction?



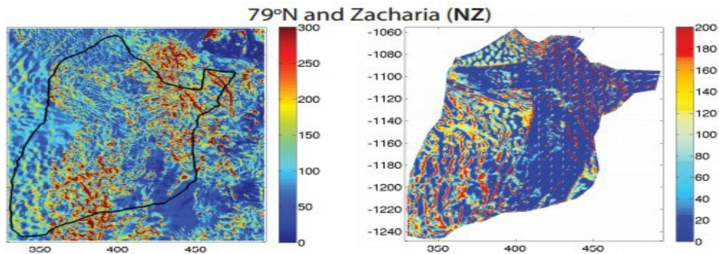
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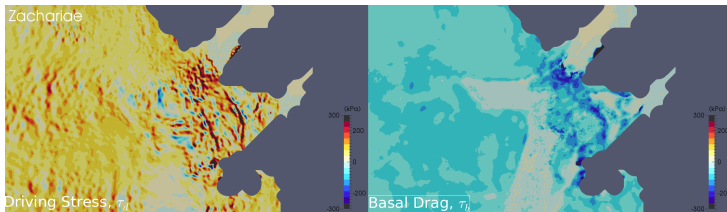
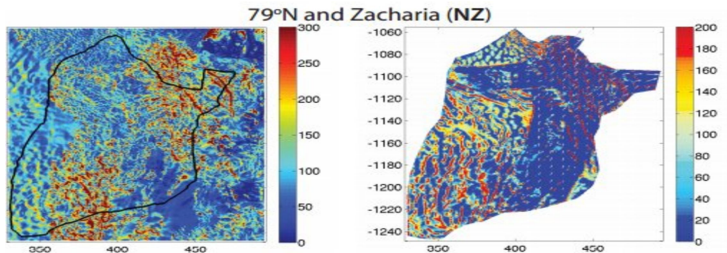
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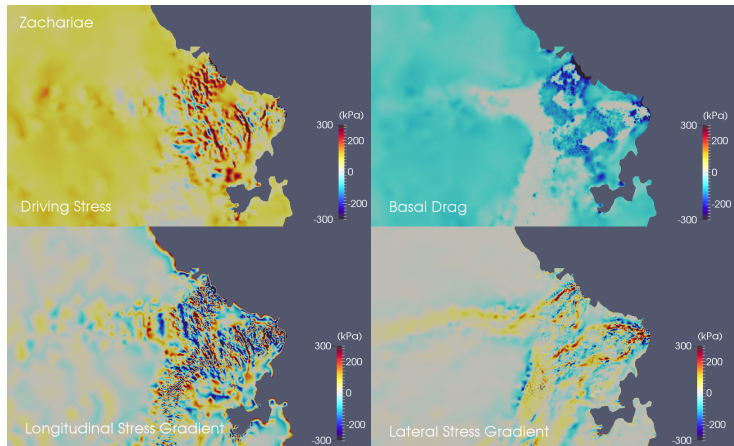
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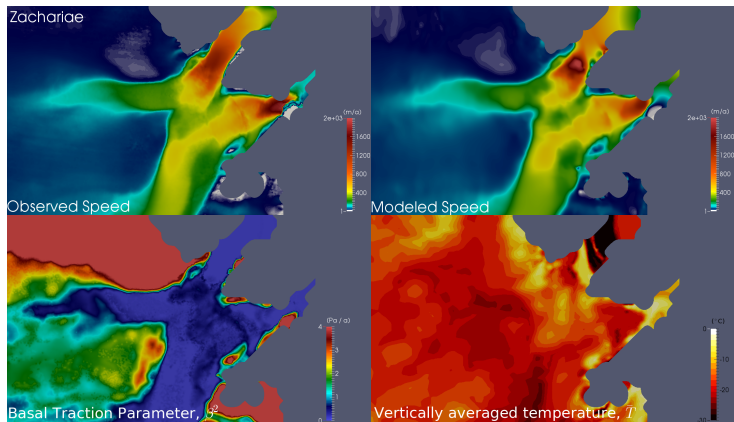
What about the rib-like features?

Is it the full-Stoke's treatment?



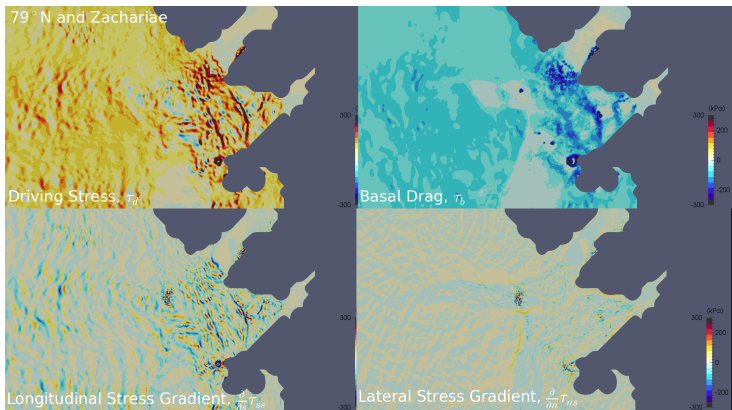
What about the rib-like features?

Rate factor?

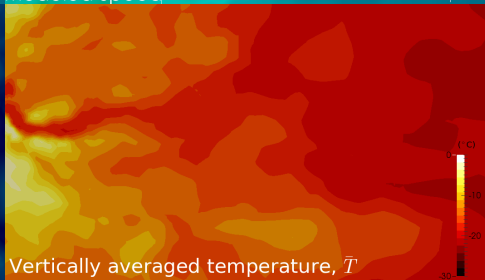
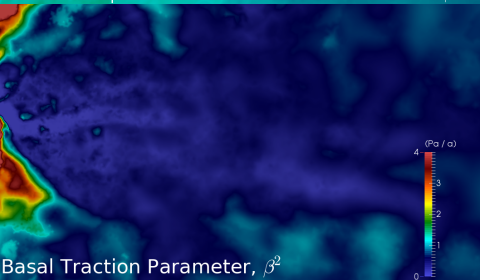
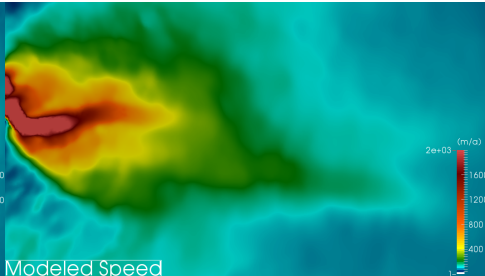
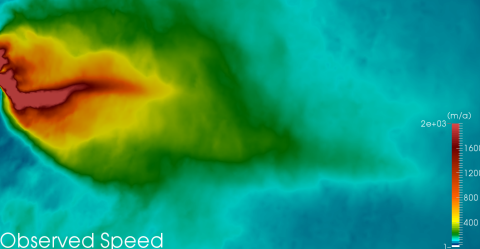


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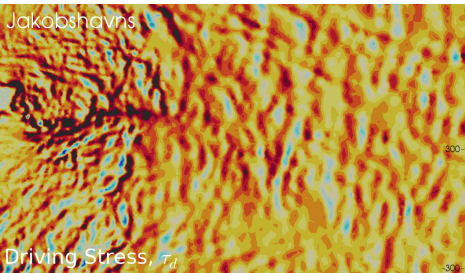
With temperatures -2°C everywhere



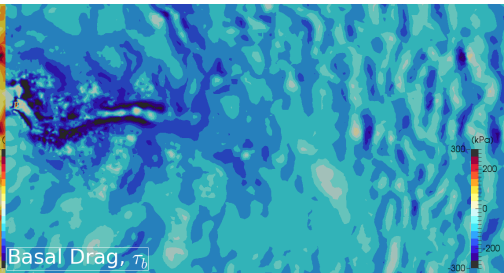
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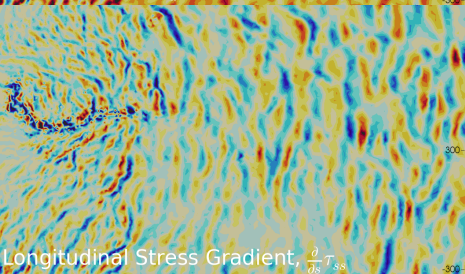
Jakobshavn



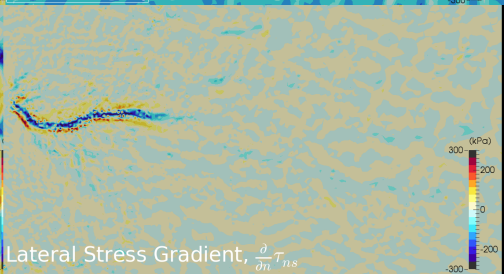
Driving Stress, τ_d



Basal Drag, τ_b



Longitudinal Stress Gradient, $\frac{\partial}{\partial s} \tau_{ss}$

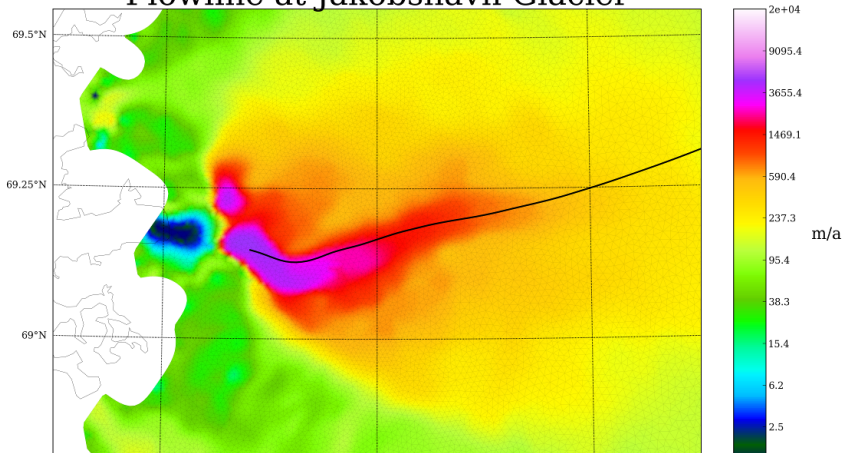


Lateral Stress Gradient, $\frac{\partial}{\partial n} \tau_{ns}$

Evaluation along a flow line

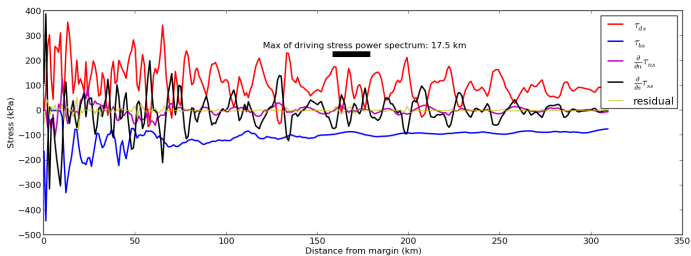
Simplify interpretation

Flowline at Jakobshavn Glacier



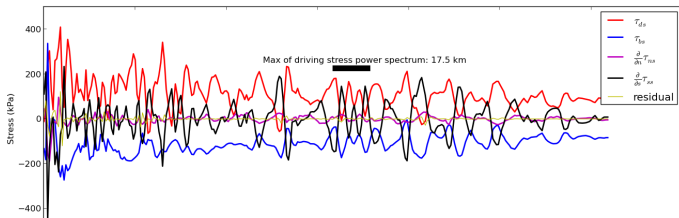
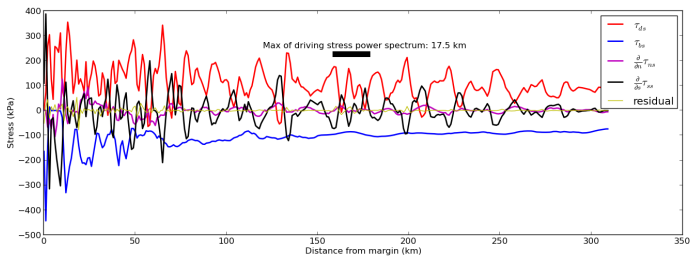
Evaluation along a flow line

Simplify interpretation



Evaluation along a flow line

Simplify interpretation



Summary

- Rib like patterns in basal drag are less common in assimilations using full temperature balance.
- Our model has lower resolution (one ice thickness).
- Our model has lower order (L1L2, or SSA hybrid) momentum balance. Alignment of features.
- Our model may be too cold.
- Driving stress anomalies *could* be supported by longitudinal stress gradients.

Along flow force balance

$$\underbrace{\frac{\partial}{\partial s} \left(2\nu H \left(2 \frac{\partial \tilde{u}}{\partial s} + \frac{\partial \tilde{v}}{\partial n} \right) \right)}_{\text{Longitudinal stress gradient}} + \underbrace{\frac{\partial}{\partial n} \left(\nu H \left(\frac{\partial \tilde{u}}{\partial n} + \frac{\partial \tilde{v}}{\partial s} \right) \right)}_{\text{Lateral stress gradient}} = \underbrace{\rho g H \frac{\partial z_s}{\partial s}}_{\text{Driving stress}} - \underbrace{\beta^2 \tilde{u}}_{\text{Basal drag}}$$