



An Update on the Albany/FELIX First-Order Stokes Finite Element Solver & Its Coupling to Land Ice Dycores

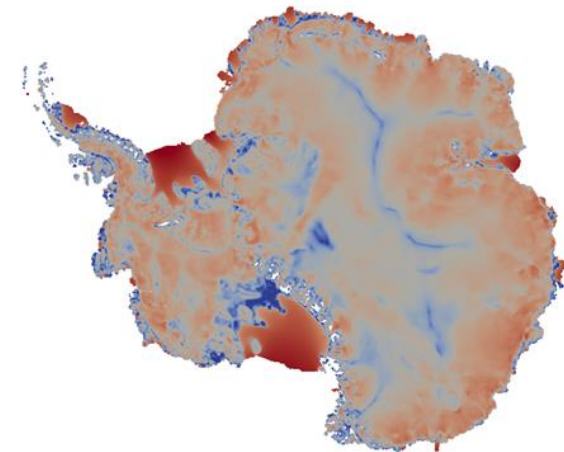
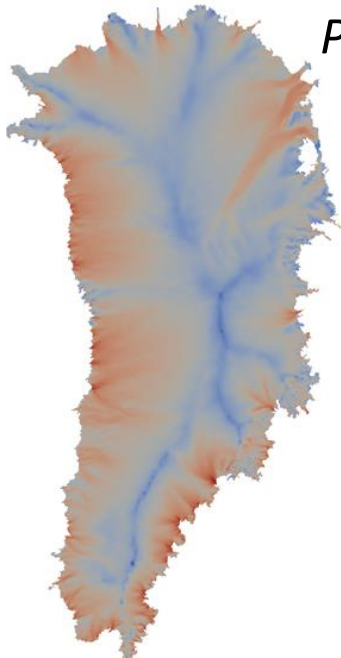
**Irina Kalashnikova, Andy Salinger, Mauro Perego,
Ray Tuminaro, Steve Price**

*In collaboration with Matt Hoffman, Doug Ranken, Kate Evans,
Pat Worley, Matt Norman, Mike Eldred, John Jakeman and
Irina Demeshko.*

Sandia National Laboratories*

CESM Annual Workshop
Wednesday, June 18, 2014

The Village at Breckenridge
Breckenridge, Colorado



PISCEES Project & the Albany/FELIX First-Order Stokes Dycore

To **develop** and **support** a robust and scalable unstructured grid finite element land ice dycore based on the “first-order” (FO) Stokes physics → **Albany/FELIX dycore**

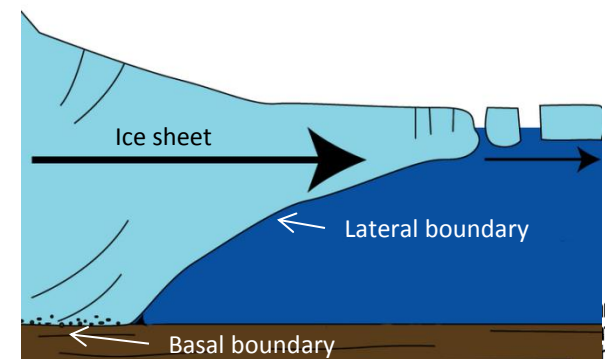
- **Finite element method.**
- Parallel, unstructured grid with **partitioning**.
- **Automatic differentiation** for (exact) Jacobians.
- Globalized **Newton’s method** nonlinear solver.
- Preconditioned (ILU or algebraic multigrid) iterative **Krylov linear solvers**.
- **Performance-portable kernels** to run on new architecture machines / GPUs (in progress).
- **Analysis tools:** UQ, sensitivity analysis, optimization.
- **Software tools:** git / cmake / ctest / jenkins.

First Order Stokes Model

$$\begin{cases} -\nabla \cdot (2\mu\dot{\epsilon}_1) = -\rho g \frac{\partial s}{\partial x} \\ -\nabla \cdot (2\mu\dot{\epsilon}_2) = -\rho g \frac{\partial s}{\partial y} \end{cases}$$

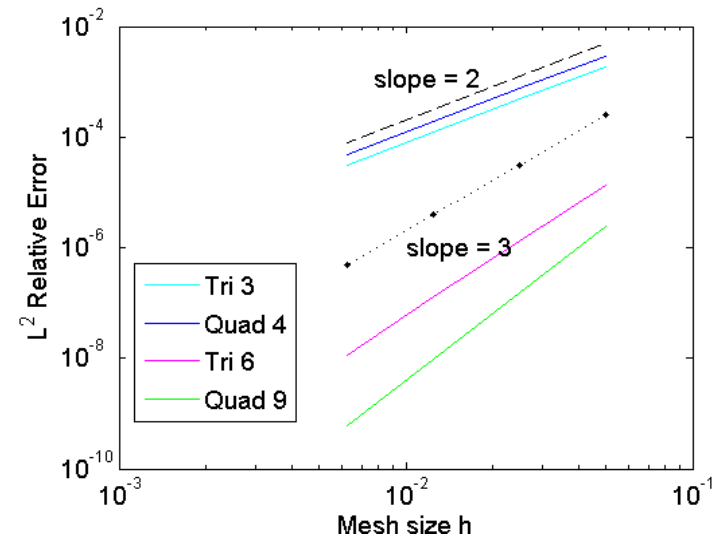
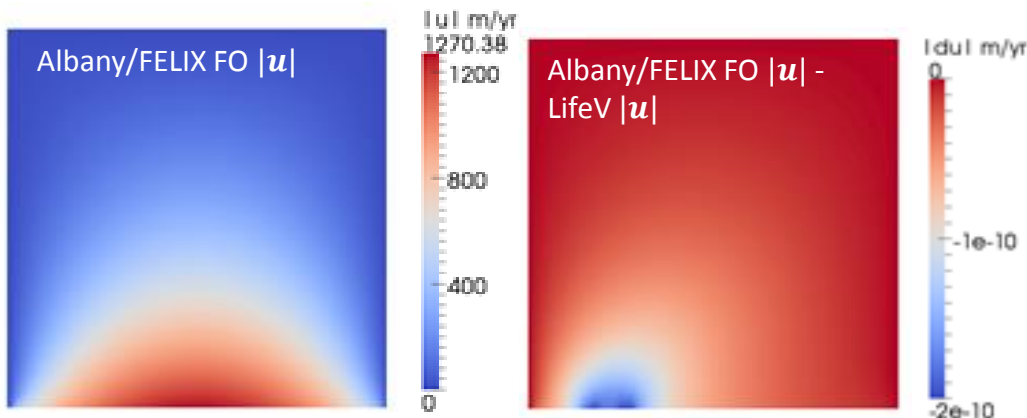
Boundary conditions

- No-slip
- Basal Sliding
- Stress-free
- Open-ocean



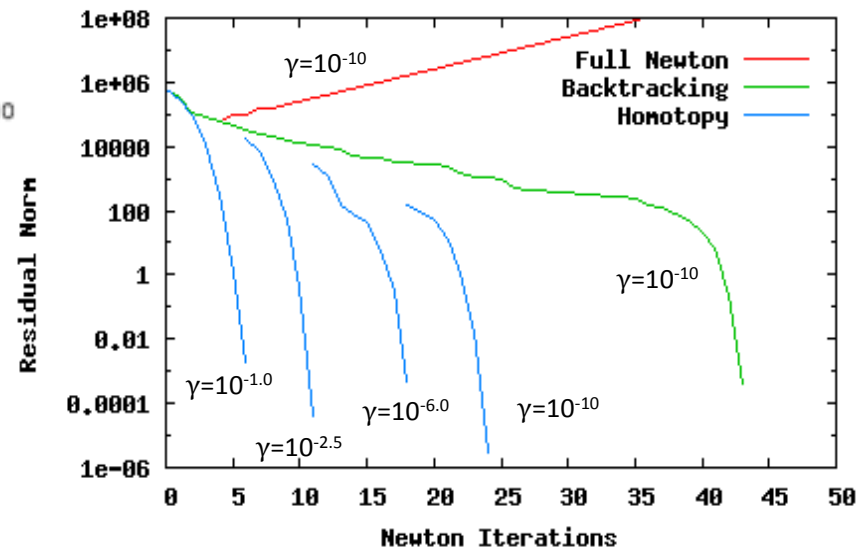
Code Verification and Performance

- Implementation of PDEs + BCs (no-slip, stress-free, basal sliding, open-ocean) has been **verified** through MMS tests (right) and code-to-code comparisons (confined-shelf, below).

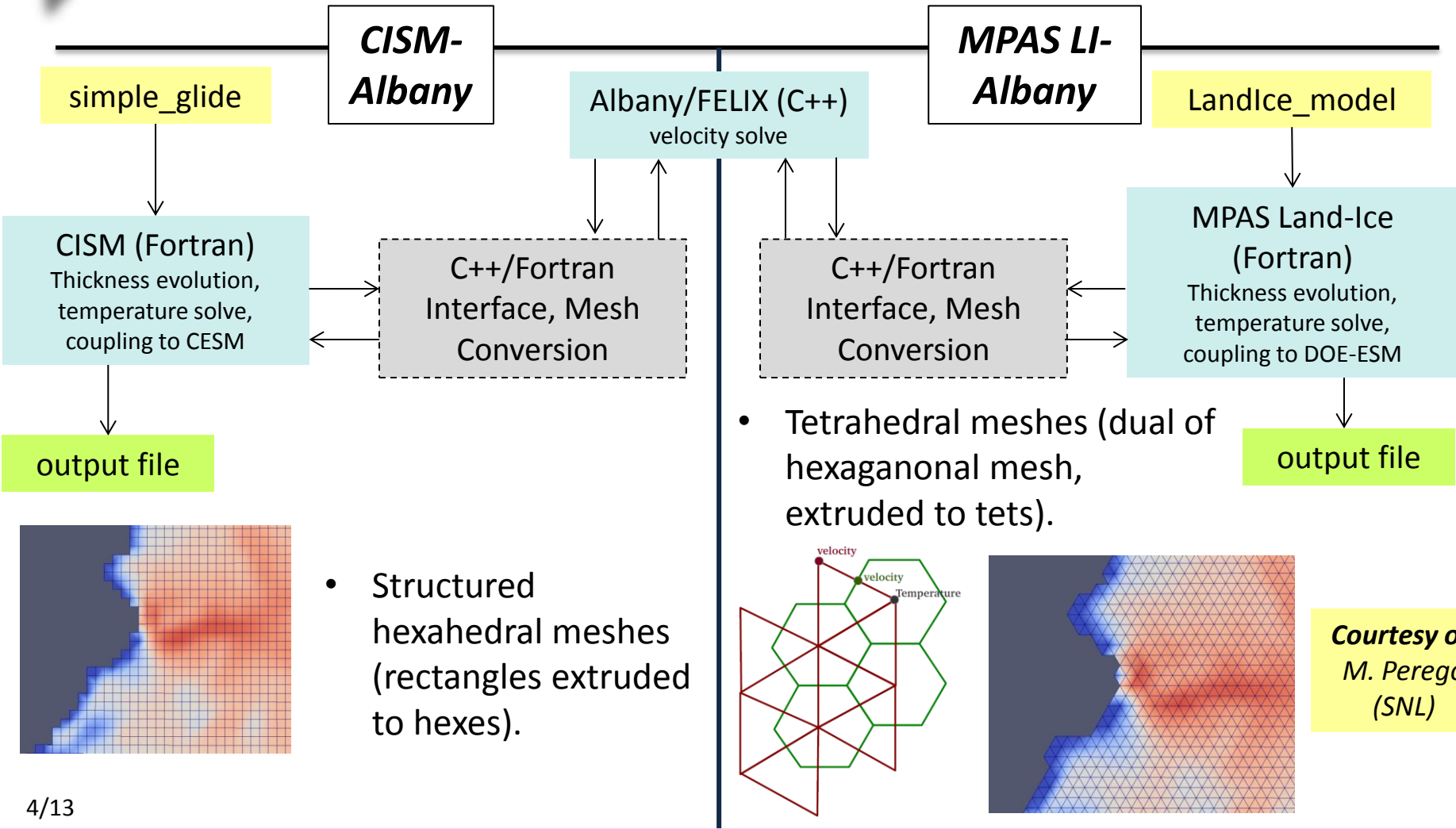


- Robust** nonlinear solves (Newton converges out-of-the-box!) with **homotopy** continuation of γ in Glen's law viscosity:

$$\mu = \frac{1}{2} A^{-\frac{1}{n}} \left(\frac{1}{2} \sum_{ij} \dot{\epsilon}_{ij}^2 + \gamma \right)^{\left(\frac{1}{2n} - \frac{1}{2} \right)}$$

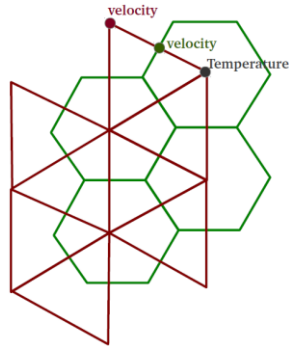


Dycore Interfaces and Meshes



- Structured hexahedral meshes (rectangles extruded to hexes).

- Tetrahedral meshes (dual of hexagonal mesh, extruded to tets).



Courtesy of:
M. Perego
(SNL)

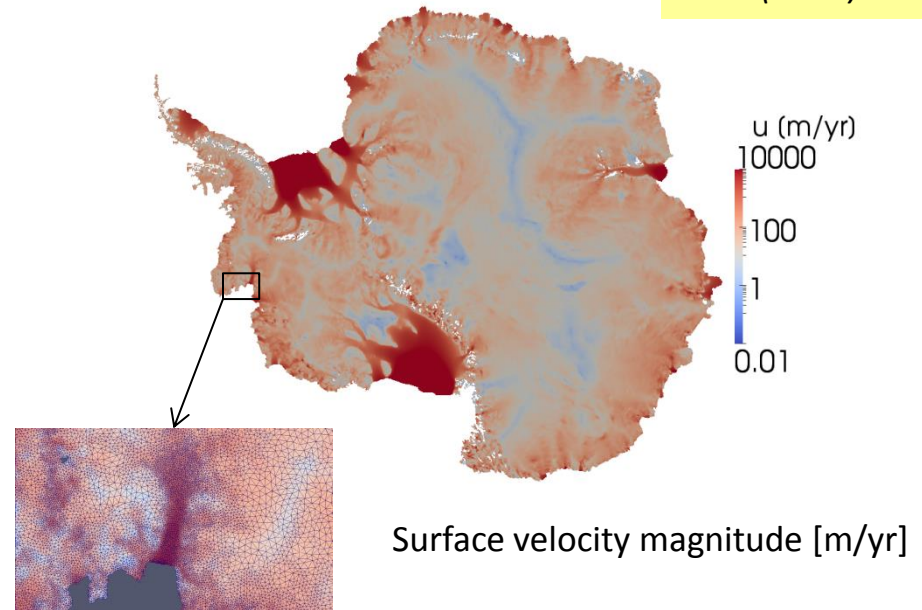
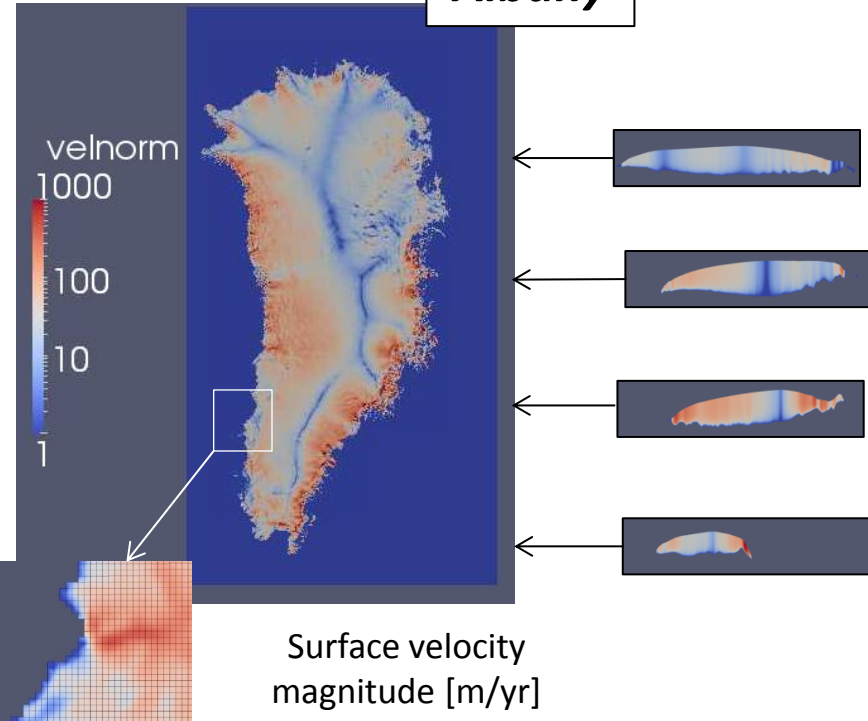
We support several full **mesh/data** (geometry, topography, surface height, basal traction, temperature, etc.) import methods: ***.exo**, **ASCII** (stand-alone Albany), ***.nc** (Dycore-Albany);

Steady Runs Using Dycore Interfaces

**CISM-
Albany**

**MPAS LI -
Albany**

*Courtesy of:
M. Perego (SNL);
Dan Martin
(LBNL)*

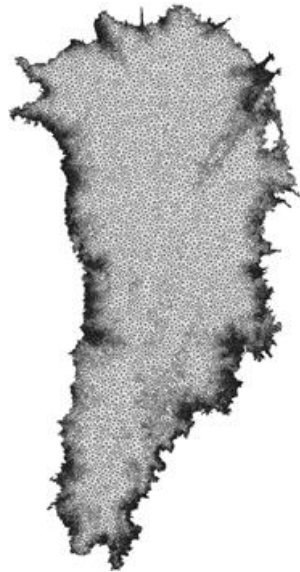


Albany/FELIX converged **out-of-the-box** for these problems!

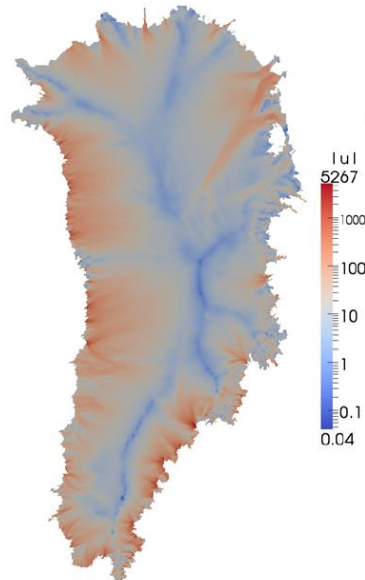
15 km - 2 km resolution Antarctica
17.4M tet elements
6.6M unknowns
Variable β , T (from BISICLES)

1 km resolution GIS
16.6M hex elements
37M unknowns
Constant β , T (no-slip)

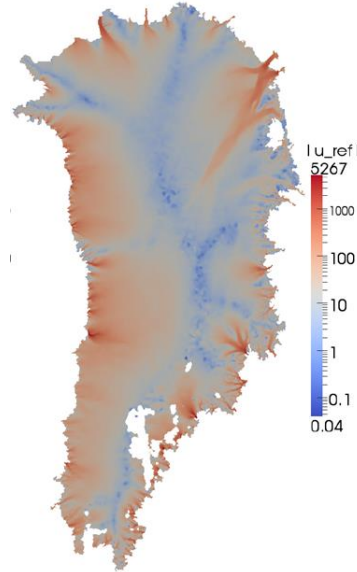
Regional Refinement (work-in-progress using MPAS LI)



Unstructured Delaunay
triangle mesh



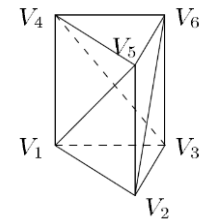
|computed surface
velocity| [m/yr]



|reference surface
velocity| [m/yr]

Mesh Details

Min h : 4 km
Max h : 15 km
32K nodes



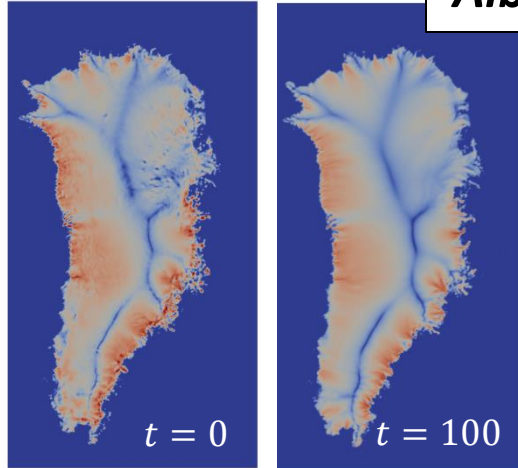
- **Step 1:** determine geometry boundaries and possible holes (*MATLAB*).
- **Step 2:** generate uniform triangular mesh and refine based on *gradient of measured surface velocity (Triangle – a 2D meshing software)*.
- **Step 3:** obtain 3D mesh by extruding the 2D mesh in the vertical direction as *prism*, then splitting each prism into 3 *tetrahedra (Albany)*.

Courtesy of:
M. Perego
(SNL)

Dynamic Runs Using Dycore Interfaces (work-in-progress)

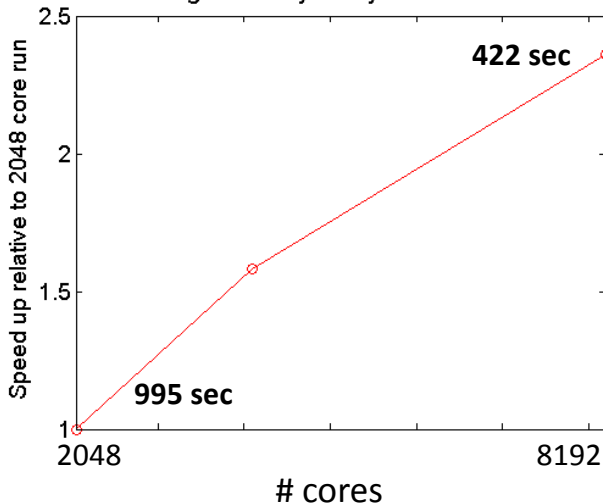
CISM- Albany

Surface velocity [m/yr]



100 year 4 km GIS transient run using converges on Titan **out-of-the box** ($\Delta t = 0.1$ years)!

Strong Scalability: 100 year 4km GIS run

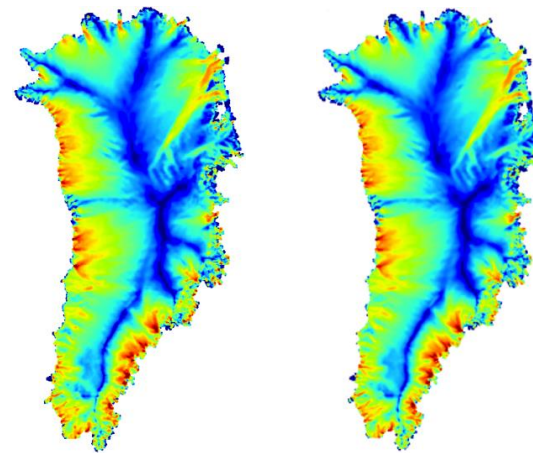


Strong scaling study:
2.35 × speedup with 4 × # cores

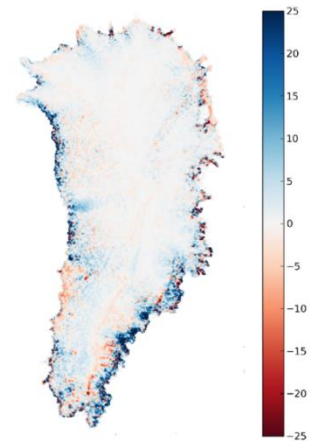
Courtesy of:
P. Worley (ORNL)

MPAS LI- Albany

Surface velocity [km/yr]



Elevation change [m]



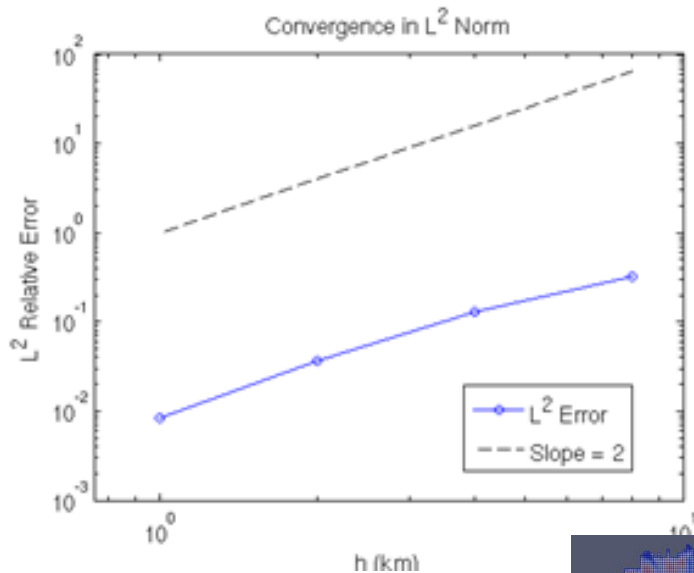
- Preliminary (proof-of-concept, 5 km GIS) result up to $t = 13$ years (CFL violated with $\Delta t = 0.1$ years).
- MPAS temperature solve is work-in-progress.

Courtesy of: M. Perego (SNL);
M. Hoffman (LANL)

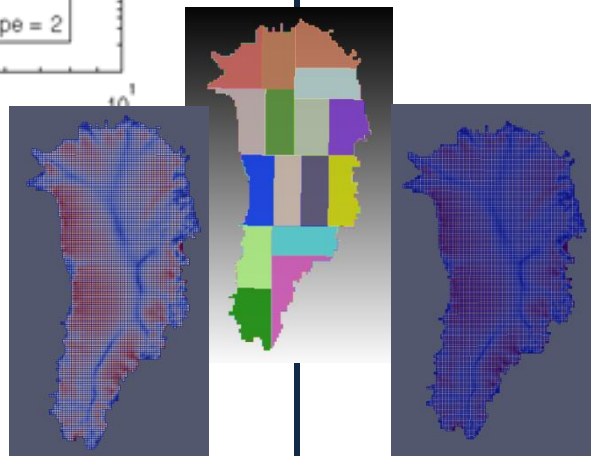
Greenland Mesh Convergence Study

Full 3D Mesh-Convergence Study

*Are the GIS problems resolved?
Is theoretical convergence rate achieved?*



- **Full 3D mesh convergence** study (uniform refinement, fixed data w.r.t. reference solution) for GIS gives theoretical convergence rate of 2 in L^2 norm.



z Mesh-Convergence Study

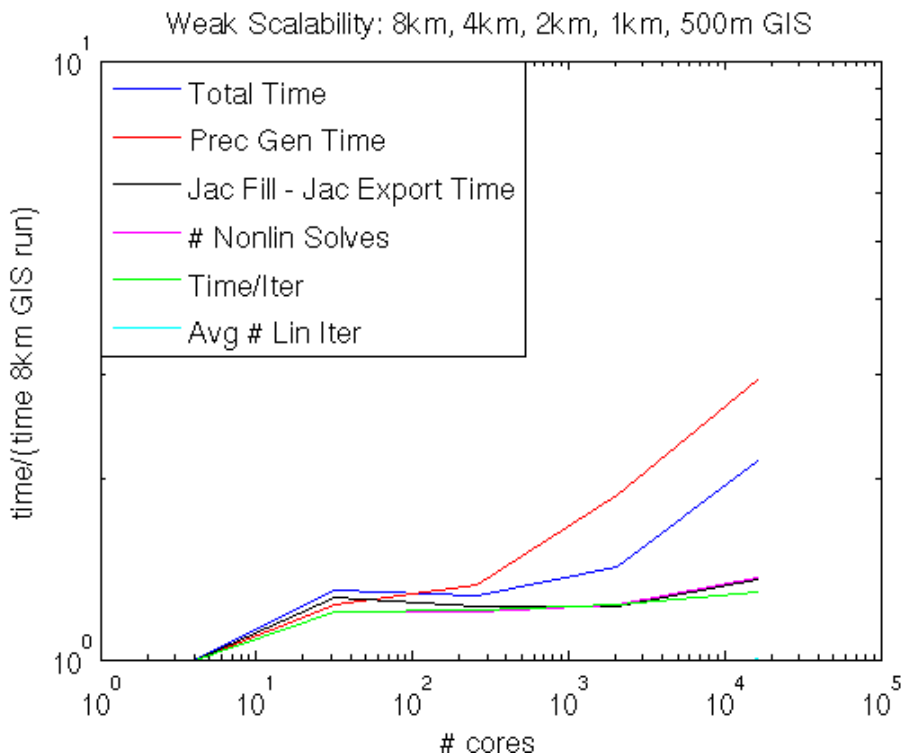
How many vertical layers are needed?

# z layers/ # cores	# dofs	Total Time – Mesh Import	Solution Average	Error
5/128	21.0M	519.4 sec	2.827	3.17e-2
10/256	38.5M	525.4 sec	2.896	8.04e-3
20/512	73.5M	499.8 sec	2.924	2.01e-3
40/1024	143M	1282 sec	2.937	4.96e-4
80/2048	283M	1294 sec	2.943	1.20e-4
160/4096	563M	1727 sec	2.945	2.76e-5

- z mesh-convergence study for 1 km GIS.
- Important to do **partition** of **2D mesh** for parallel refined mesh (center).
- QOI (solution average) does change with z-refinement.

Greenland Controlled Weak Scalability Study

*In collaboration with:
R. Tuminaro (SNL)*



4 cores
334K dofs
8 km GIS,
5 vertical layers

× 8⁴
scale up

16,384 cores
1.12B dofs(!)
0.5 km GIS,
80 vertical layers

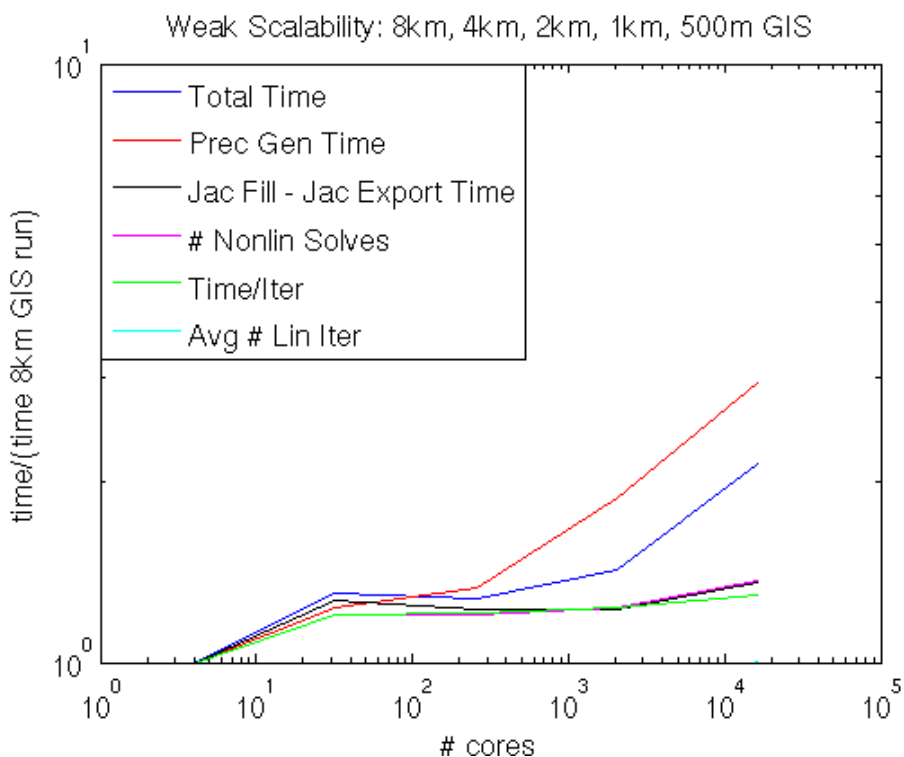
- Weak scaling study with fixed dataset, 4 mesh bisections.
- ~70-80K dofs/core.
- **Conjugate Gradient (CG) iterative method** for linear solves (faster convergence than GMRES).
- **New algebraic multigrid preconditioner (ML)** developed by R. Tuminaro based on **semi-coarsening** (coarsening in z-direction only).
- **Significant improvement** in scalability with new ML preconditioner over ILU preconditioner!



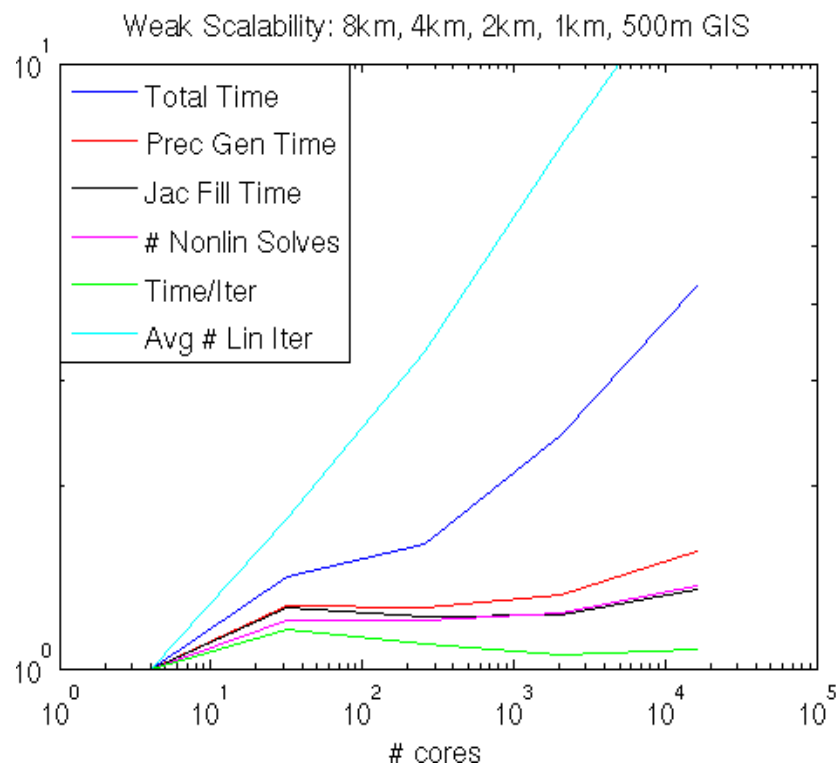
Greenland Controlled Weak Scalability Study

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New ML preconditioner



ILU preconditioner



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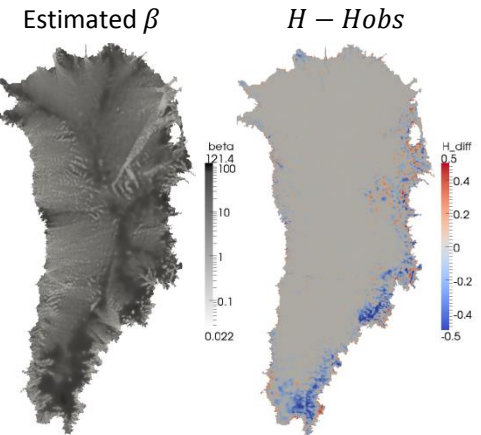


Deterministic Inversion: Estimation of Ice Sheet Initial State

First-Order Stokes PDE Constrained Optimization Problem:

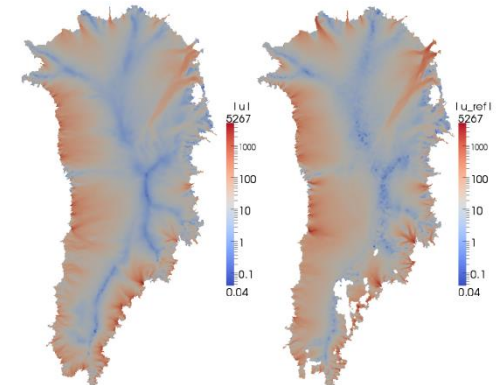
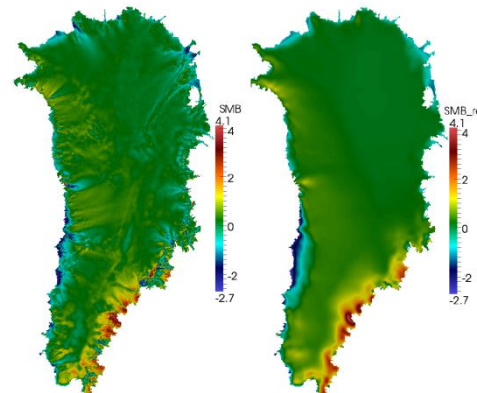
$$J(\beta, H) = \frac{1}{2} \alpha \int_{\Gamma} |\text{div}(\mathbf{U}H) - \text{SMB}|^2 ds + \frac{1}{2} \alpha_v \int_{\Gamma_{\text{top}}} |\mathbf{u} - \mathbf{u}^{\text{obs}}|^2 ds + \frac{1}{2} \alpha_H \int_{\Gamma_{\text{top}}} |H - H^{\text{obs}}|^2 ds + \mathcal{R}(\beta) + \mathcal{R}(H)$$

- Minimize difference between:
 - Computed divergence flux and measured **surface mass balance (SMB)**.
 - Computed and measured **surface velocity (\mathbf{u}^{obs})**.
 - Computed and **reference thickness (H^{obs})**.
- Control variables:
 - Basal friction (β)**.
 - Thickness (H)**.
- Software tools: **LifeV** (assembly), **Trilinos** (linear/nonlinear solvers), **ROL** (gradient-based optimization).



Estimated divergence (left) vs. reference SMB (right)

Estimated (left) vs. reference surface velocity (right)



Courtesy of: M. Perego (SNL); S. Price (LANL); G. Stadler (UT)

Bayesian Inversion/Uncertainty Quantification (work-in-progress)

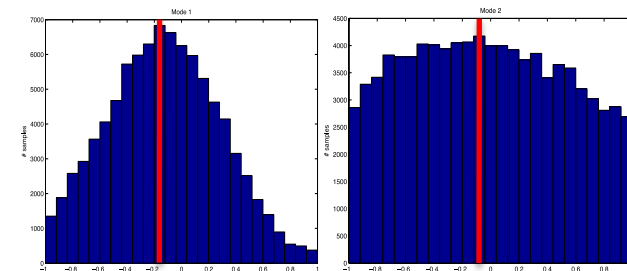
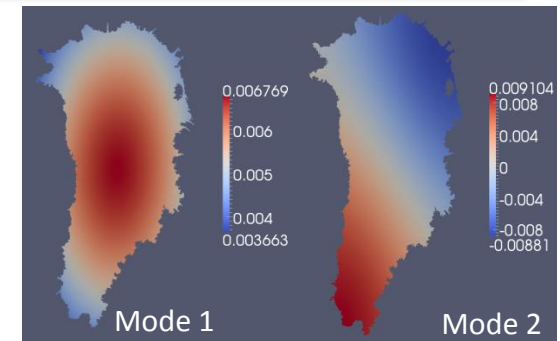
Difficulty in UQ: “Curse of Dimensionality”

The β -field inversion problem has $O(20,000)$ dimensions!

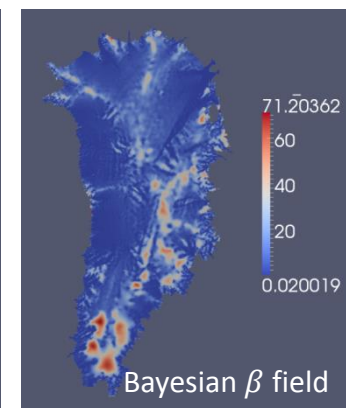
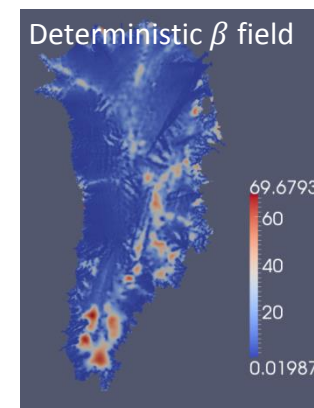
- **Step 1:** Model reduction (from $O(20,000)$ parameters to $O(5)$ parameters) using *Karhunen-Loeve Expansion* (or *eigenvectors of Hessian*, in future) of basal sliding field:

$$\log(\beta(\omega)) = \bar{\beta} + \sum_{k=1}^K \sqrt{\lambda_k} \phi_k \xi_k(\omega)$$

- **Step 2:** *Polynomial Chaos Expansion (PCE)* emulator for mismatch over surface velocity discrepancy.
- **Step 3:** *Markov Chain Monte Carlo (MCMC)* calibration using PCE emulator.



Posterior Distributions of 1st 2 KLE coefficients



With:
J. Jakeman,
M. Eldred (SNL)

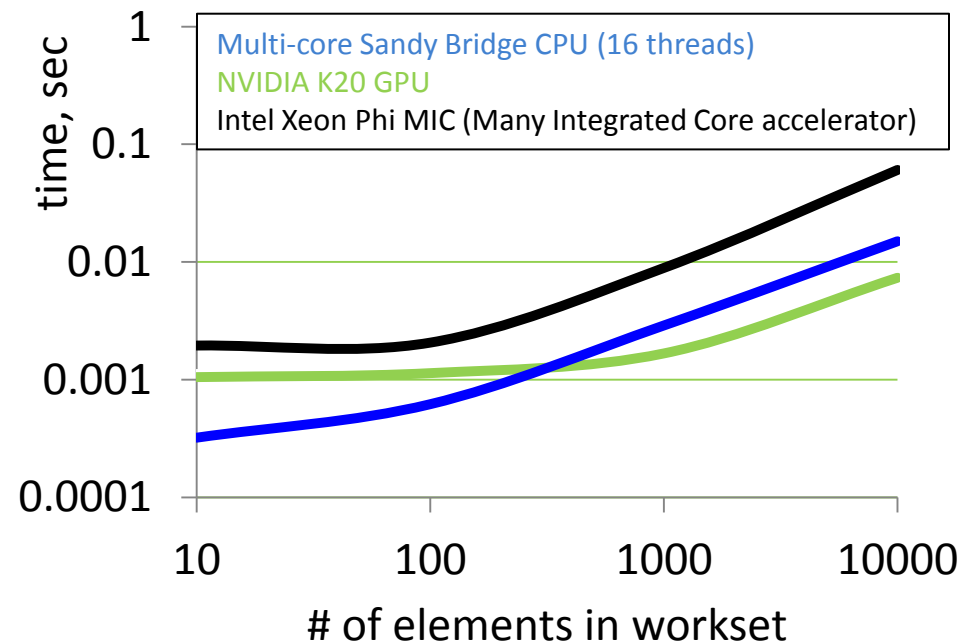


Conversion to Performance-Portable Kernels (work-in-progress)

We need to be able to run Albany/FELIX on *new architecture machines* (hybrid systems) and *manycore devices* (multi-core CPU, NVIDIA GPU, Intel Xeon Phi, etc.) .

- **Kokkos**: Trilinos C++ library that provides performance portability across diverse devices with different memory models.
- With Kokkos, you write an algorithm once, and just change a template parameter to get the optimal data layout for your hardware.
- Albany/FELIX *finite element assembly* has been converted to **Kokkos functors** in Albany/FELIX MiniDriver (I. Demeshko).

Albany/FELIX MiniDriver, 20 km GIS



Courtesy of: I. Demeshko (SNL)



Summary and Future Work

Summary:

- Albany/FELIX first-order Stokes dycore can be run on Greenland/Antarctica problems discretized by several kinds of meshes and is nearly ready for science.
- The Albany/FELIX dycore has been hooked up to the CISM and MPAS codes.
- Convergence, scalability and robustness of the Albany/FELIX code has been verified.

Verification, Greenland/Antarctica runs, scalability, robustness, UQ, advanced analysis, performance-portability: all attained in **~2 FTE of effort!**

Ongoing/future work:

- Mature dynamic evolution capabilities.
- Perform deterministic and stochastic initialization runs.
- Finish conversion to performance-portable kernels.
- Journal article on Albany/FELIX (I. Kalashnikova, A. Salinger, M. Peregó, R. Tuminaro, S. Price, M. Hoffman).
- Delivering code to users in climate community.
- Coupling to an earth system model (ESM).

Funding/Acknowledgements

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PISCEES team members: W. Lipscomb, S. Price, M. Hoffman, A. Salinger, M. Perego, I. Kalashnikova, R. Tuminaro, P. Jones, K. Evans, P. Worley, M. Gunzburger, C. Jackson;
Trilinos/Dakota collaborators: E. Phipps, M. Eldred, J. Jakeman, L. Swiler.

Thank you! Questions?



References

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- [2] F. Pattyn *et al.* “Benchmark experiments for higher-order and full-Stokes ice sheet models (ISMIP-HOM)”. *Cryosphere* **2**(2) 95-108 (2008).
- [3] M. Perego, M. Gunzburger, J. Burkardt. “Parallel finite-element implementation for higher-order ice-sheet models”. *J. Glaciology* **58**(207) 76-88 (2012).
- [4] J. Dukowicz, S.F. Price, W.H. Lipscomb. “Incorporating arbitrary basal topography in the variational formulation of ice-sheet models”. *J. Glaciology* **57**(203) 461-466 (2011).
- [5] A.G. Salinger, E. T. Phipps, R.A. Bartlett, G.A. Hansen, **I. Kalashnikova**, J.T. Ostien, W. Sun, Q. Chen, A. Mota, R.A. Muller, E. Nielsen, X. Gao. "Albany: A Component-Based Partial Differential Equation Code Build on Trilinos", submitted to *ACM. Trans. Math. Software*.
- [6] M. Hoffman, **I. Kalashnikova**, M. Perego, S. Price, A. Salinger, R. Tuminaro. "A New Parallel, Scalable and Robust Finite Element Higher-Order Stokes Ice Sheet Dycore Built for Advanced Analysis", in preparation for submission to *The Cryosphere*.