

DART and CESM

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IMAGE/DAReS

Nancy Collins, Jeff Anderson, Tim Hoar, Kevin Raeder

Four Topics

A little about DART

DART and CESM so far

What's next for DART-CESM

Preparation for what's next

A little about DART

A little about DART

Data Assimilation Research Testbed

Ensemble Data Assimilation

Ensemble Data Assimilation



Group of model forecasts

Ensemble Data Assimilation



Group of model forecasts

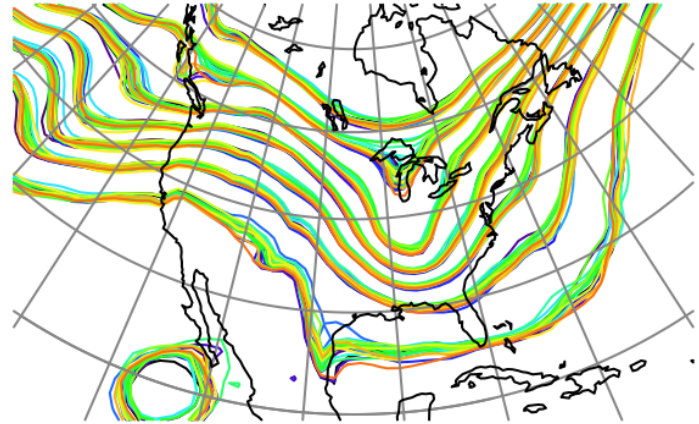
Measurements



Ensemble Data Assimilation

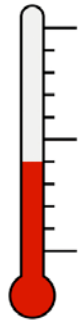


Group of model forecasts



Improved estimate

Measurements

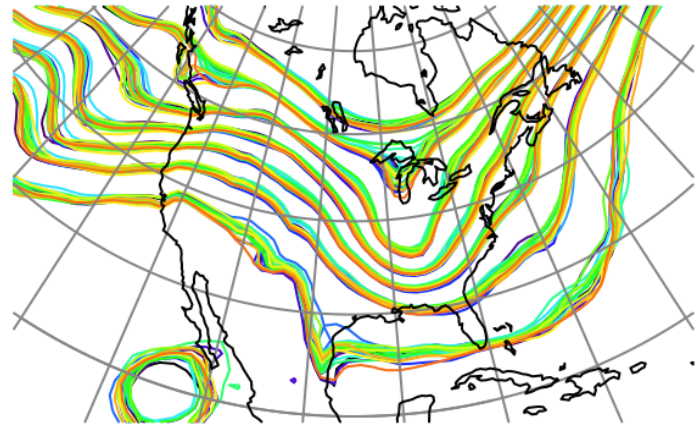
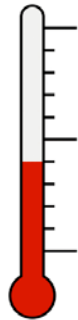


Ensemble Data Assimilation

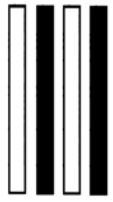
CESM multi-instance

Group of model forecasts

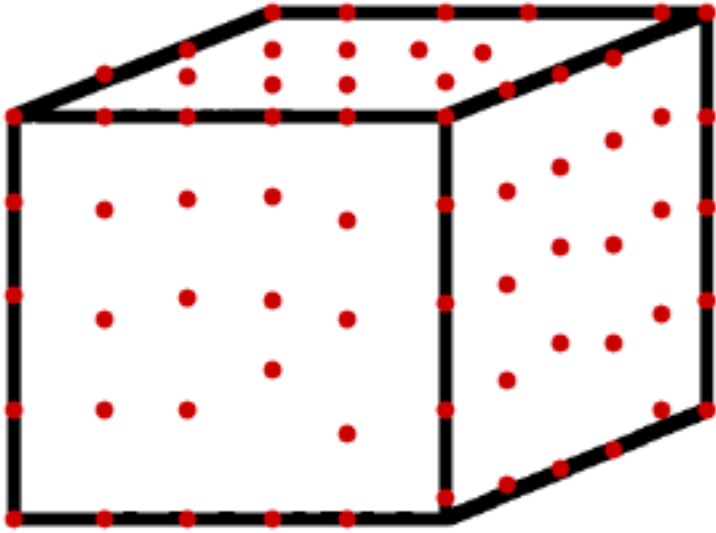
Measurements

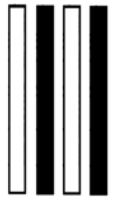


Improved estimate

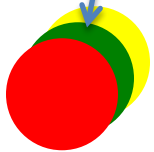
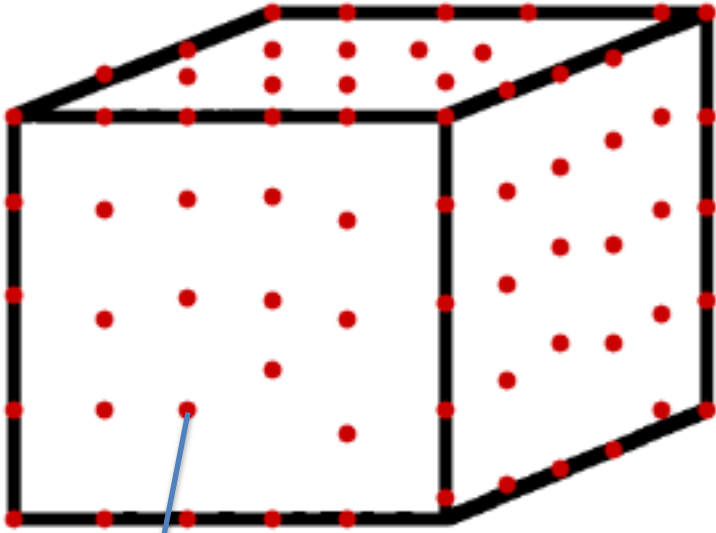


The State

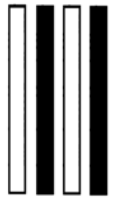




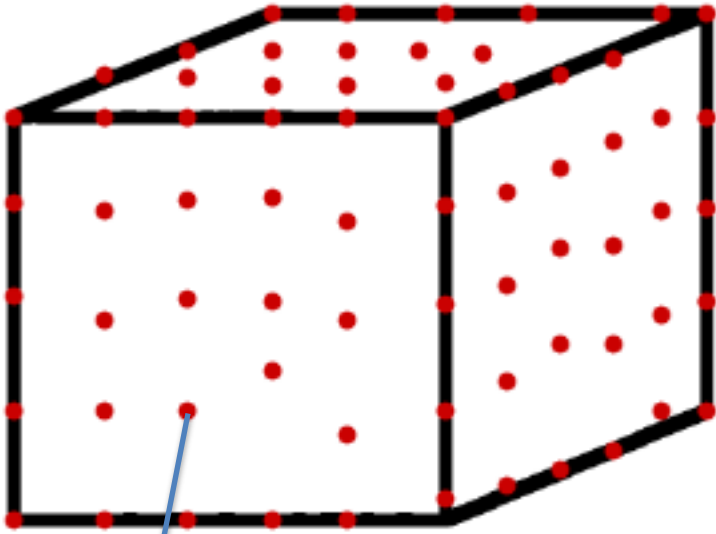
The State



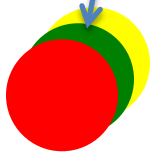
pressure
temperature
vapor mixing ratio



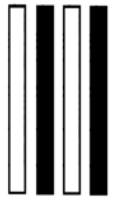
The State



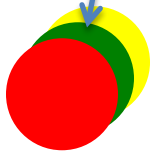
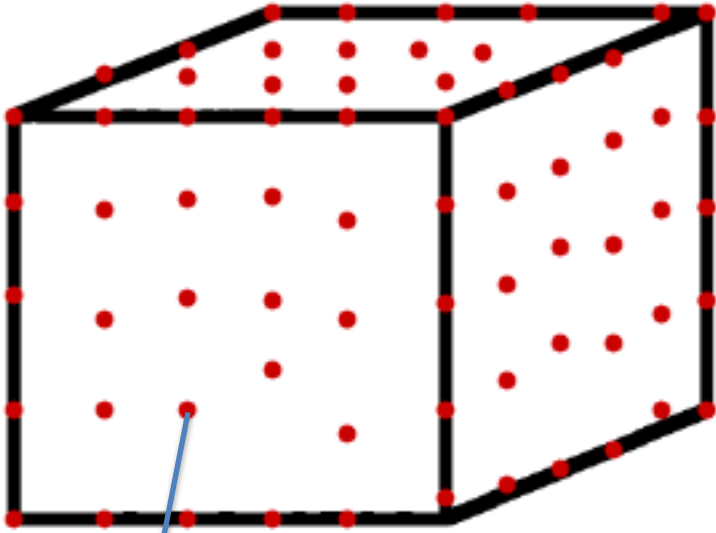
DART state vector



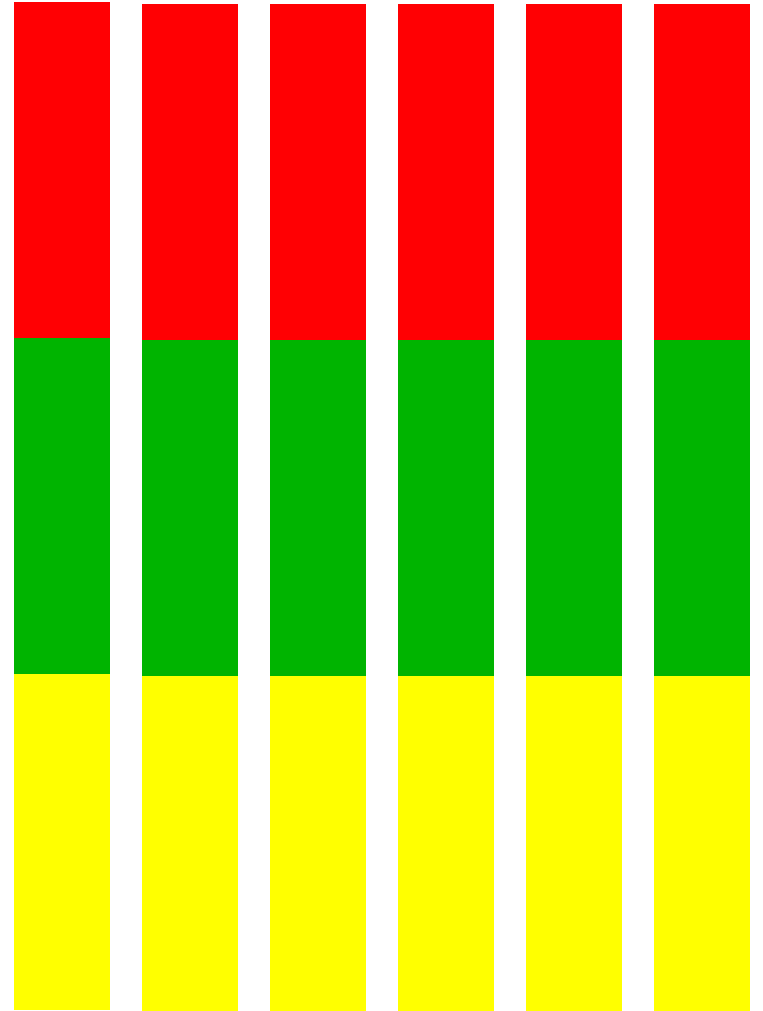
pressure
temperature
vapor mixing ratio



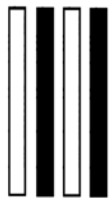
The State



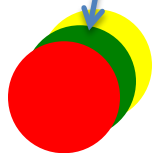
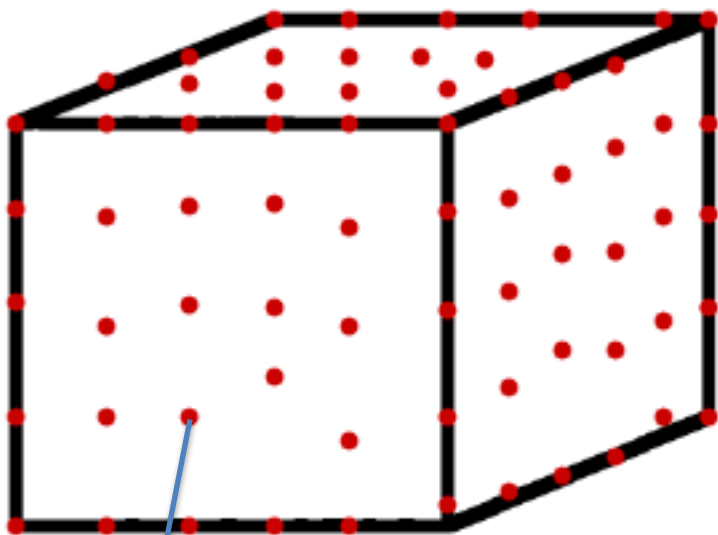
pressure
temperature
vapor mixing ratio



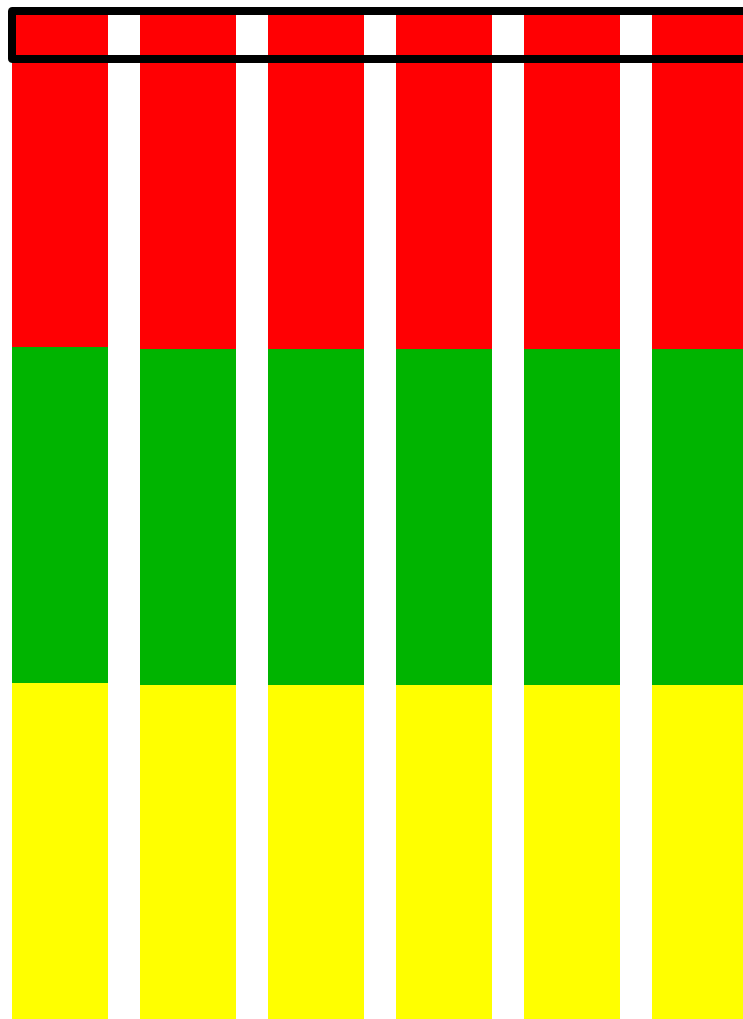
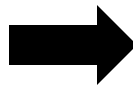
multiple copies



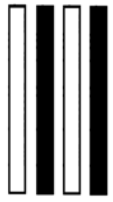
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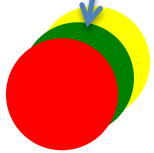
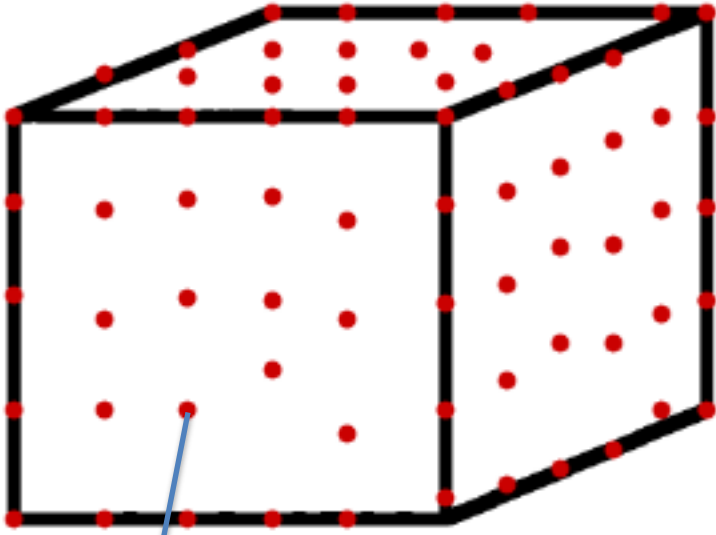
pressure
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multiple copies



The State



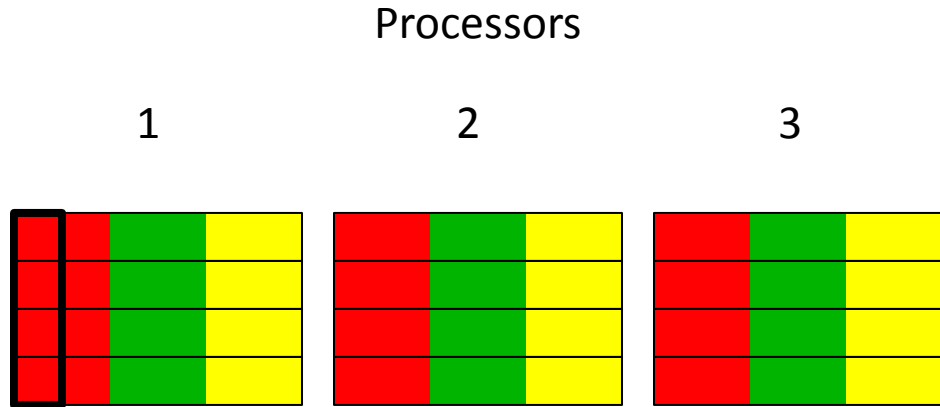
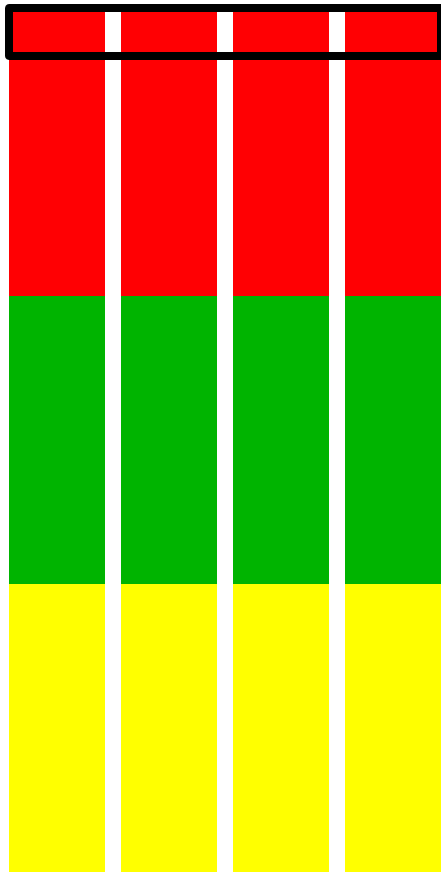
pressure
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multiple copies



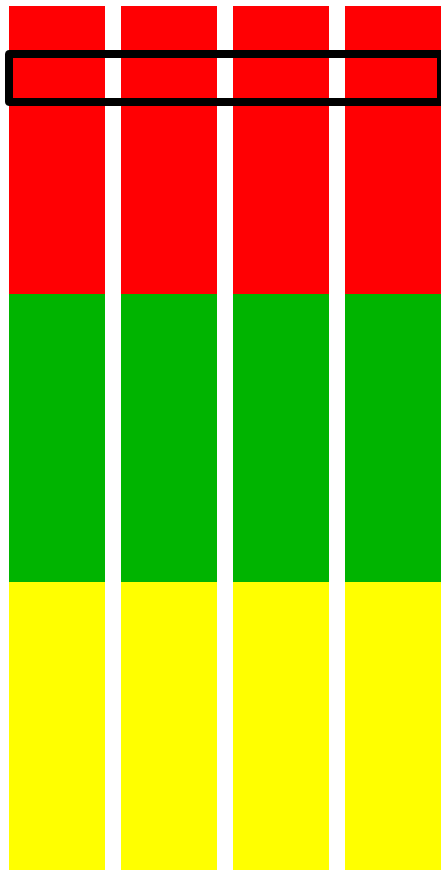
Assimilation



- Apply observation updates in parallel
- Round robin layout for load balancing
- localization



Assimilation

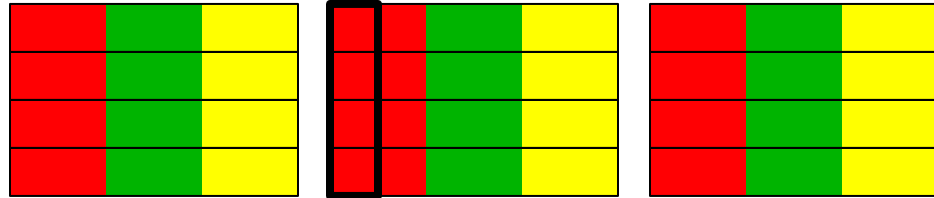


Processors

1

2

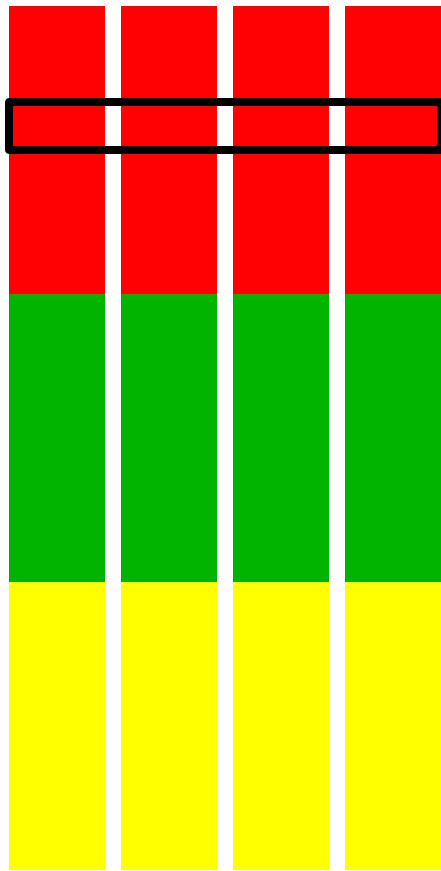
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Assimilation

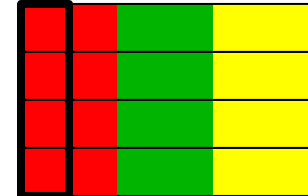


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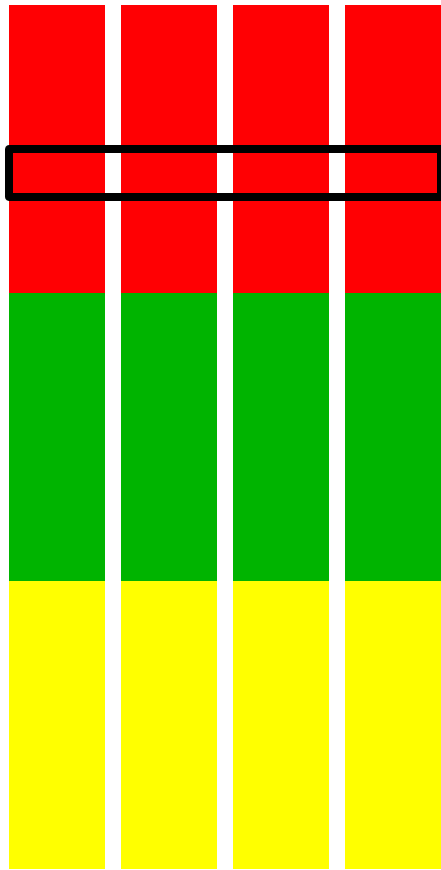
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Assimilation



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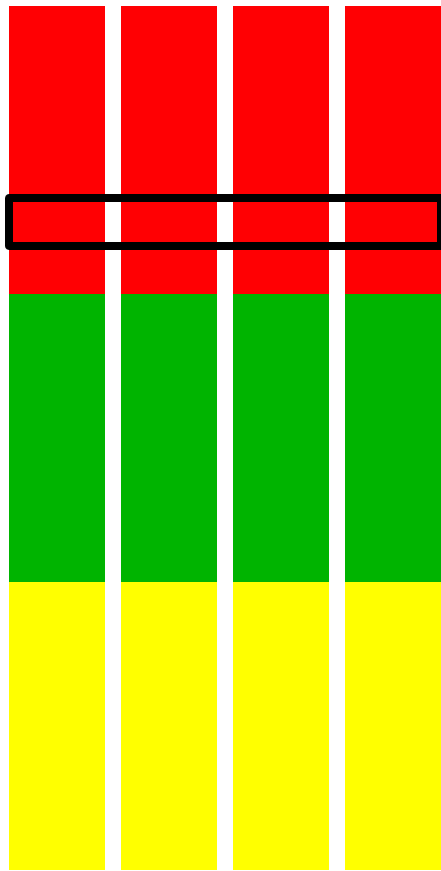
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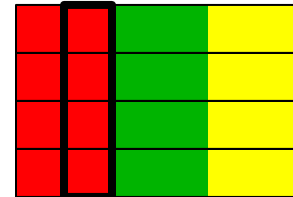


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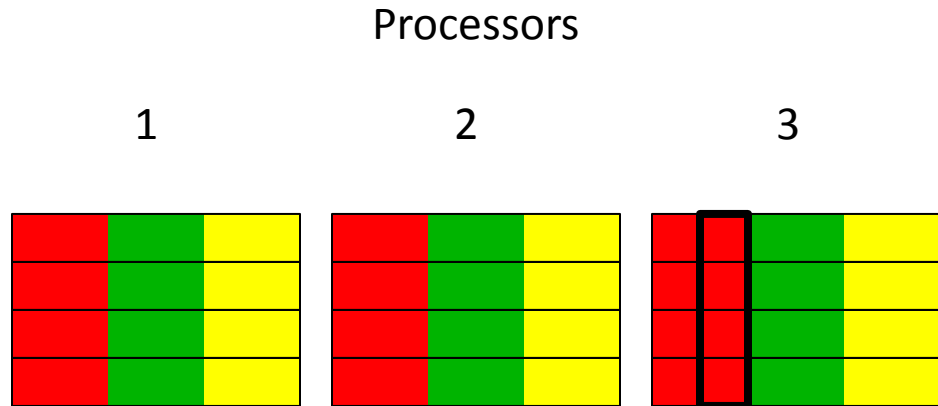
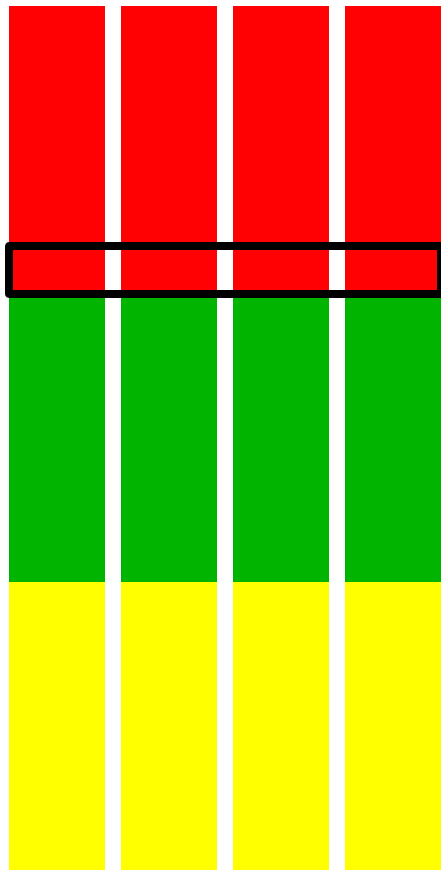
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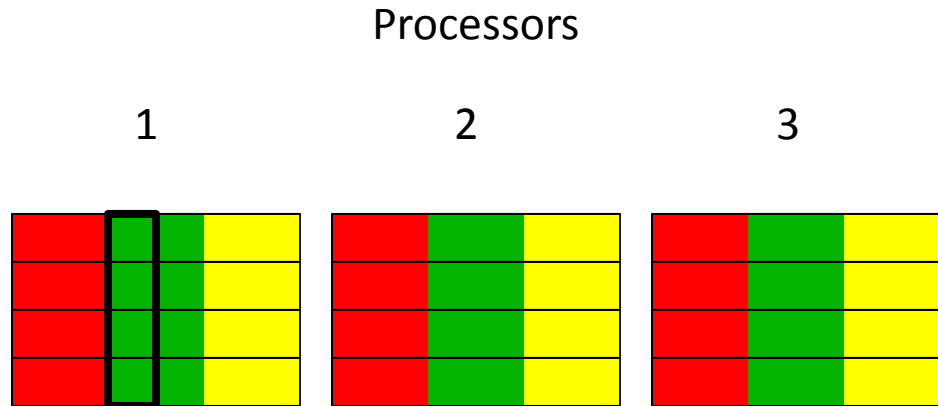
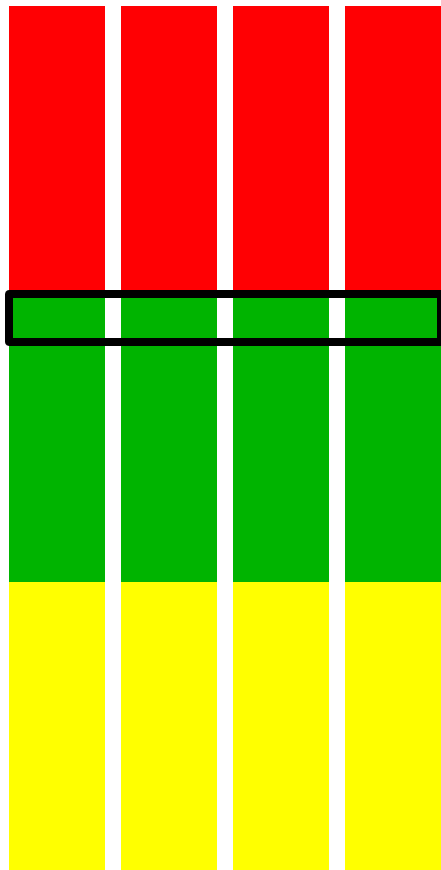
Assimilation



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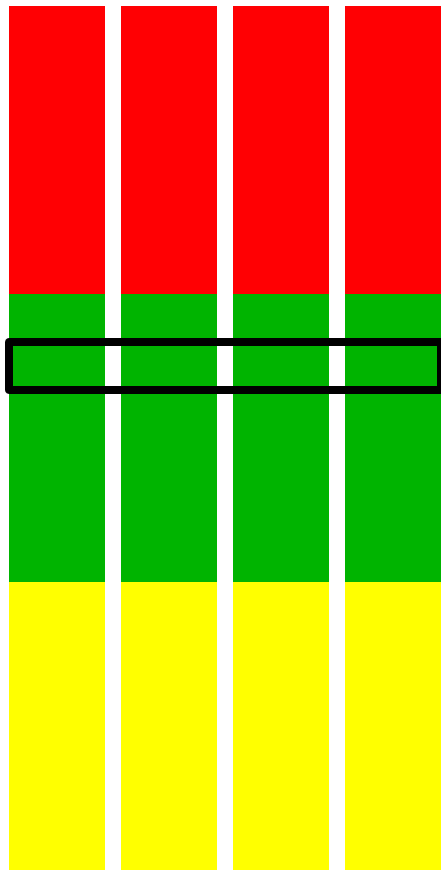
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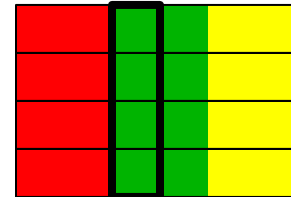


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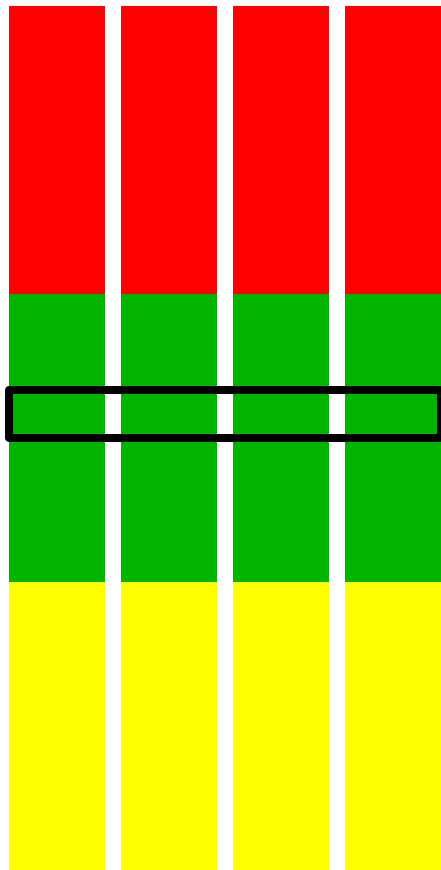
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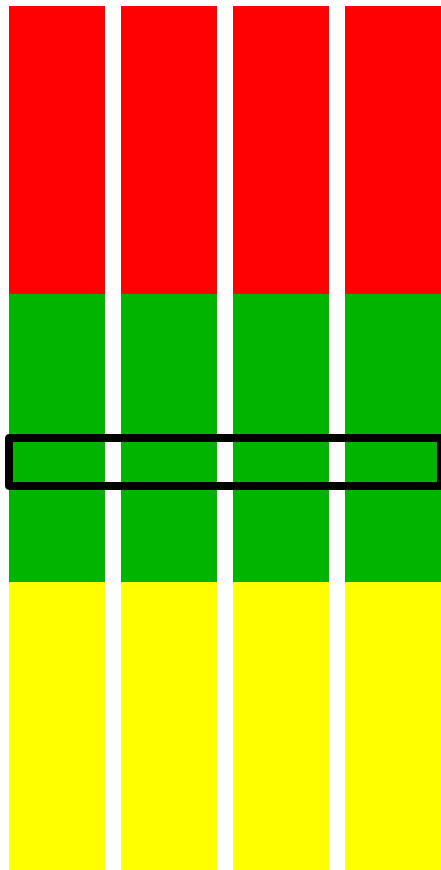
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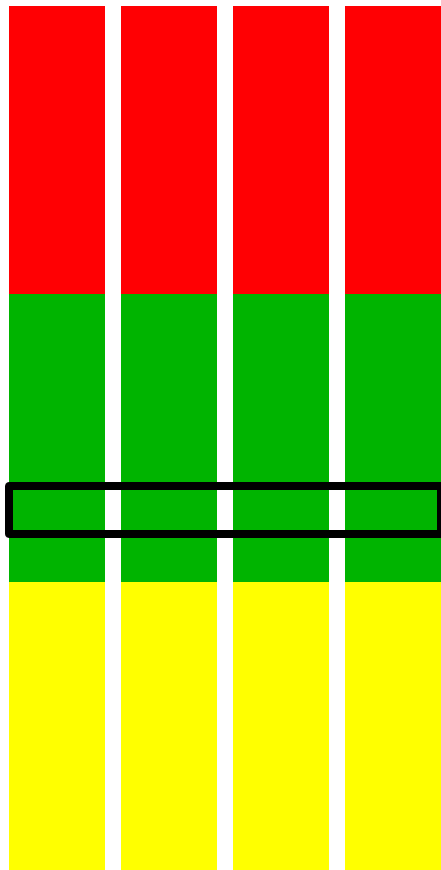
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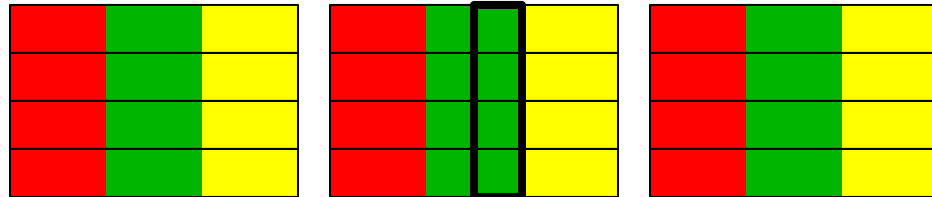


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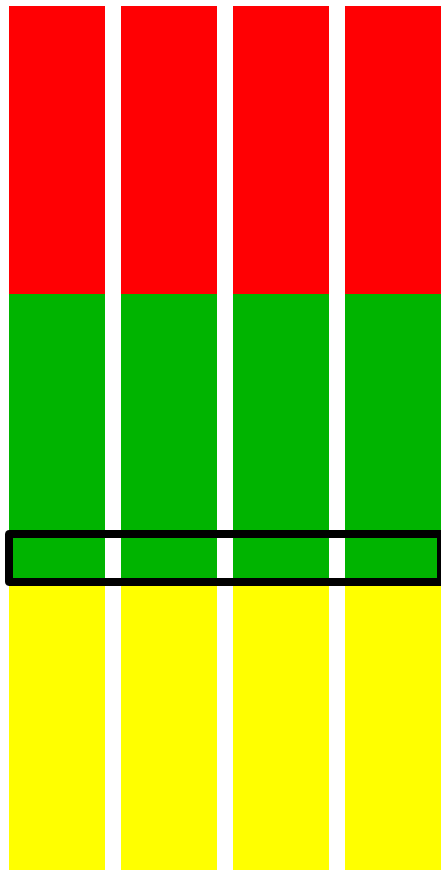
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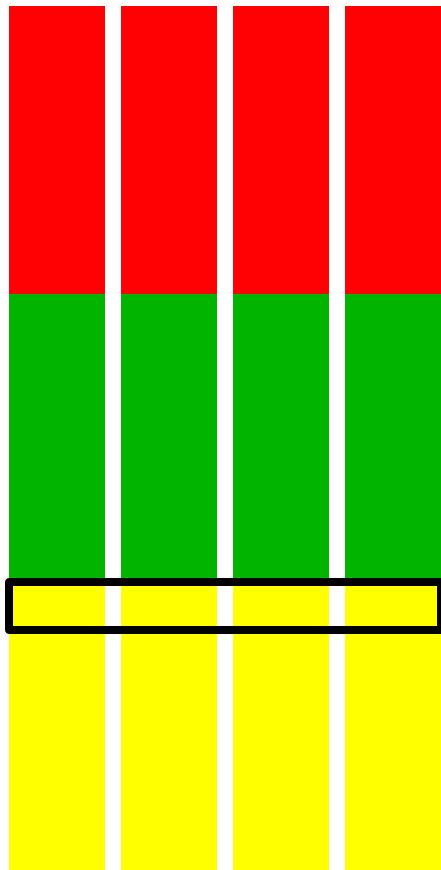
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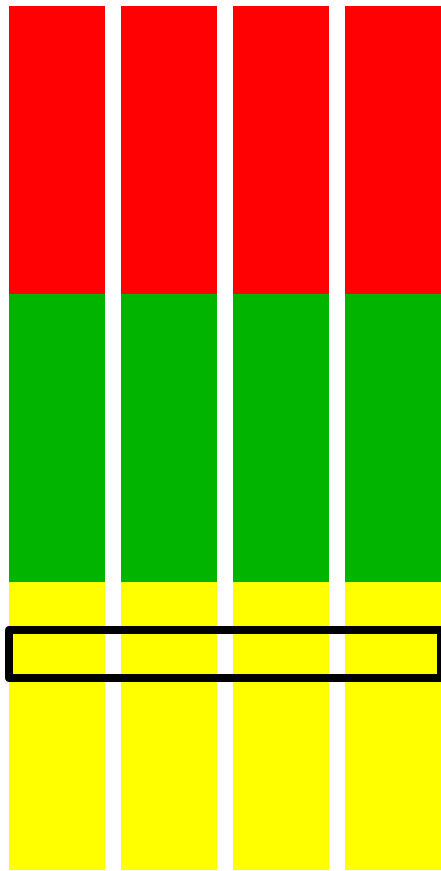
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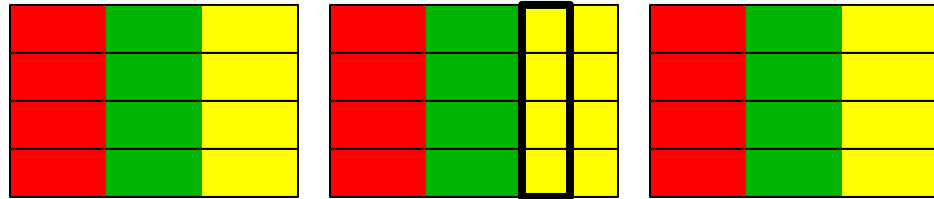


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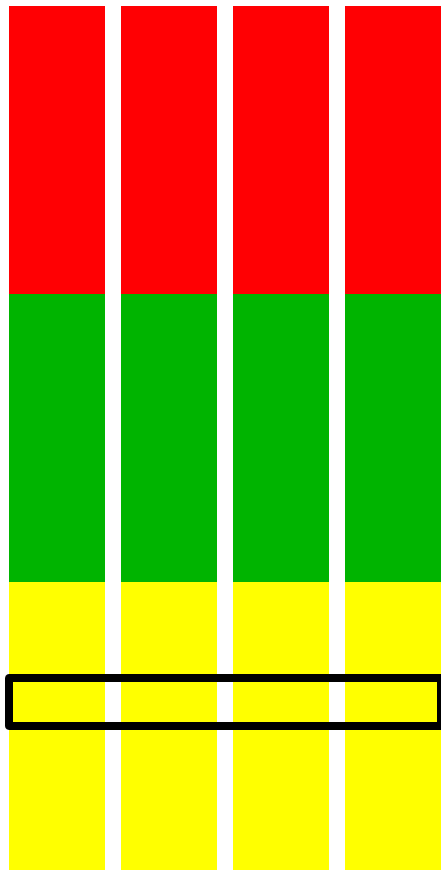
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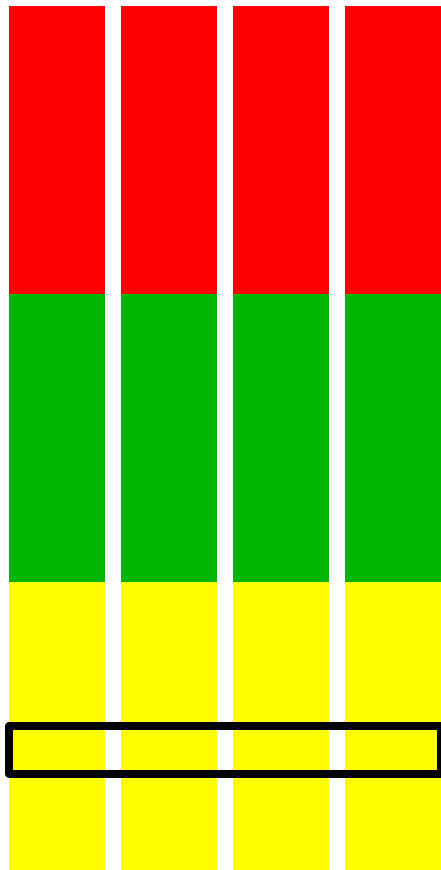
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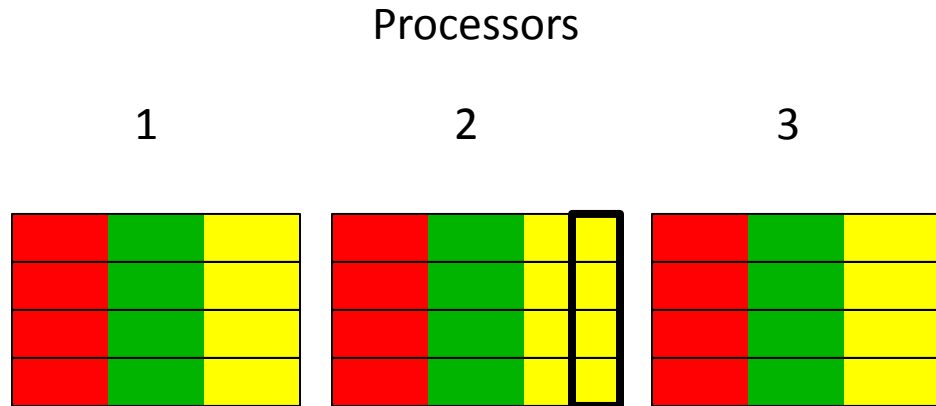
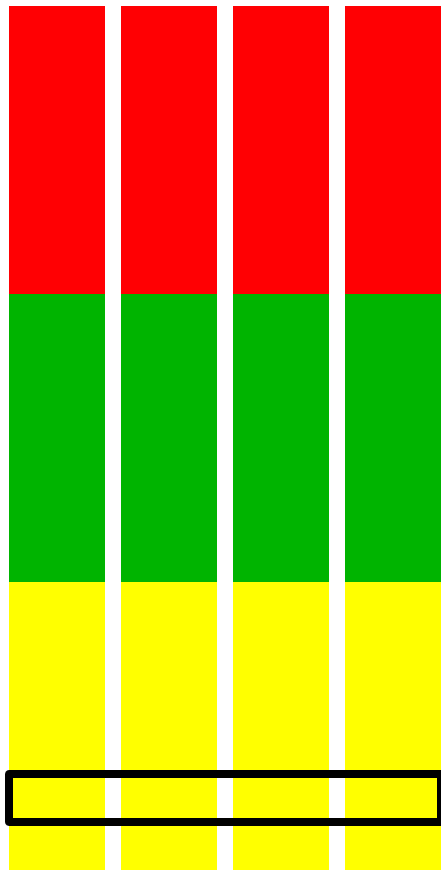
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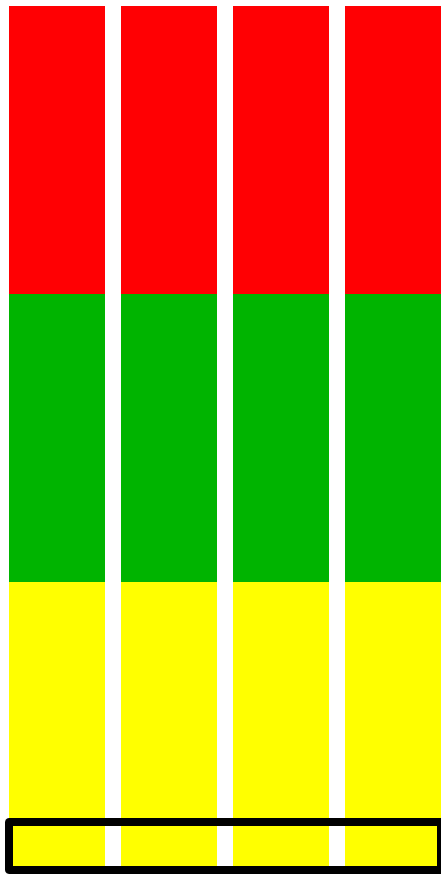
Assimilation



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Assimilation



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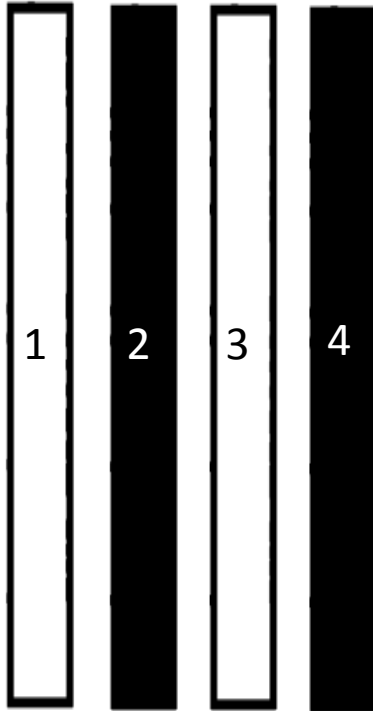
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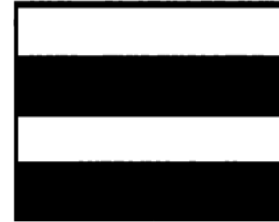


- Apply observation updates in parallel
- Round robin layout for load balancing
- localization

Data storage

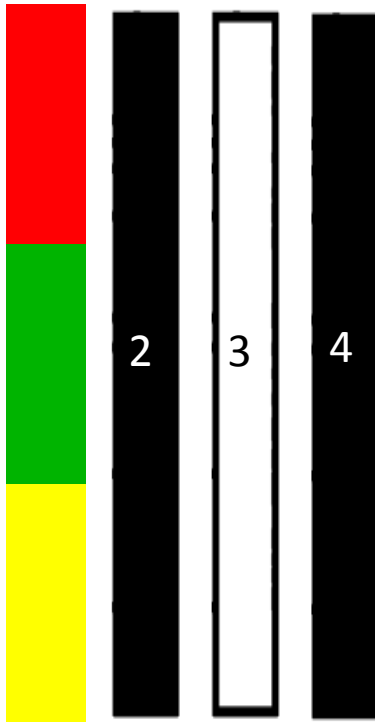


Whole model state available to a single processor

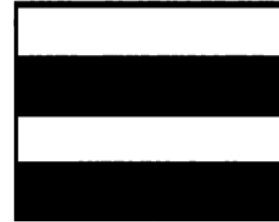


All copies of some variables available to a single processor

Data storage

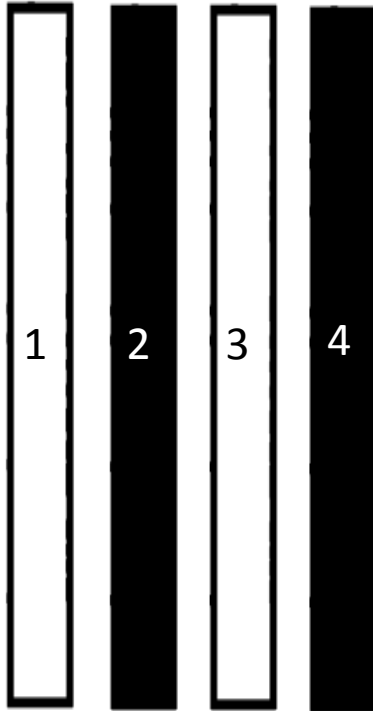


Whole model state available to a single processor

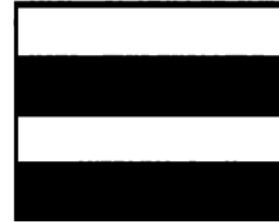


All copies of some variables available to a single processor

Data storage



Whole model state available to a single processor

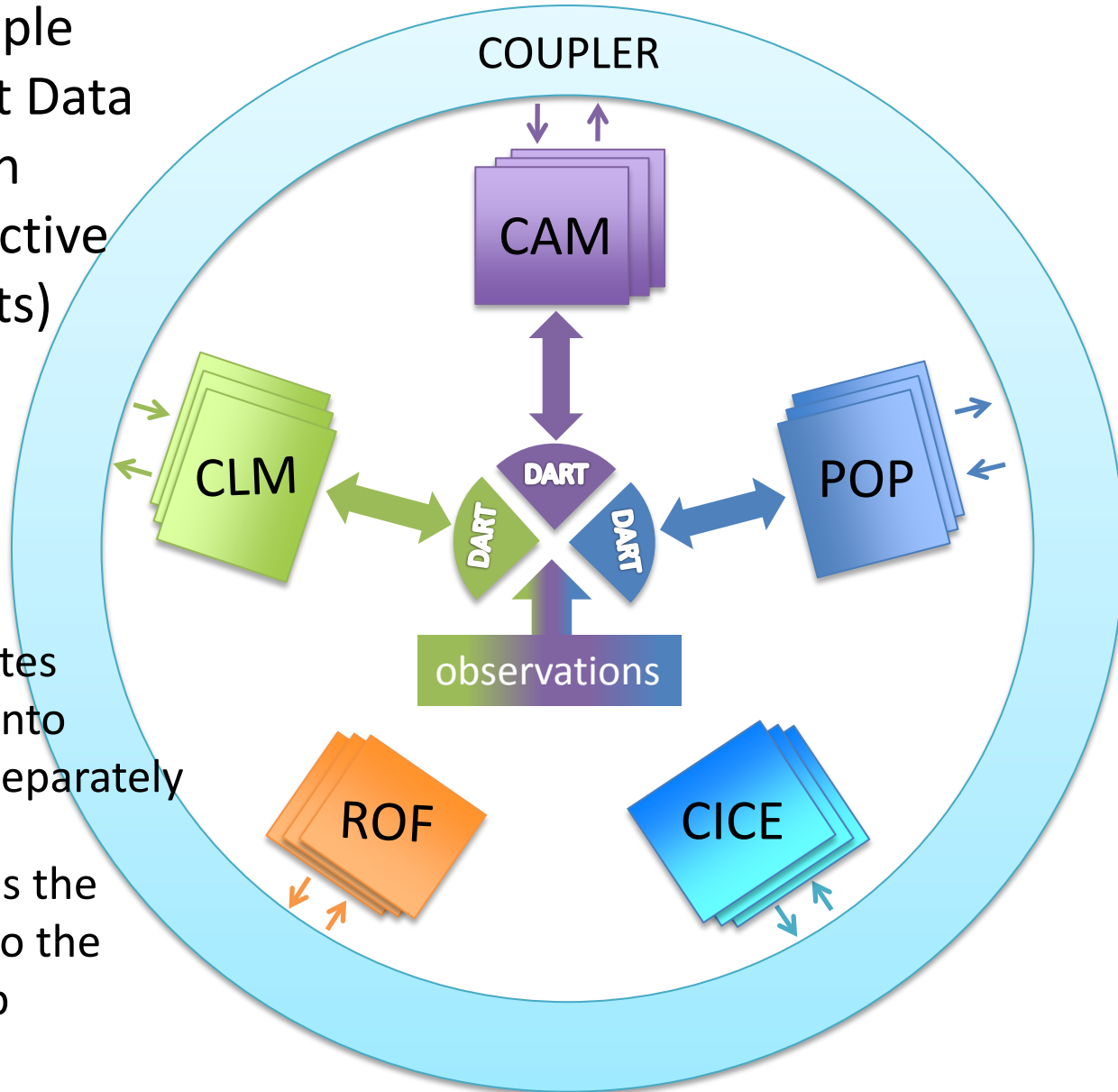


All copies of some variables available to a single processor

DART and CESM

so far ...

DART Multiple
Component Data
Assimilation
(Multiple Active
Components)



DART assimilates
observations into
components separately

Coupler moves the
components to the
next time step

DART-CESM

Single-Component Assimilations

Yongfei Zhang (*University of Texas*):

Assimilating snow cover fraction into the land model

Nick Pedatella (*UCAR COSMIC*):

WACCM (Whole Atmosphere Community Climate Model)
assimilating TIMED/SABER and aura MLS satellite measurements

Andrew Fox (*NEON*):

Assimilating tower fluxes of latent heat (LE), sensible heat (H),
and net ecosystem production into the land model

DART-CESM

Multi-Component Assimilations

Abhishek Chatterjee (*NCAR*):

coupled atmosphere-ocean-land

Alicia Karspeck (*NCAR*):

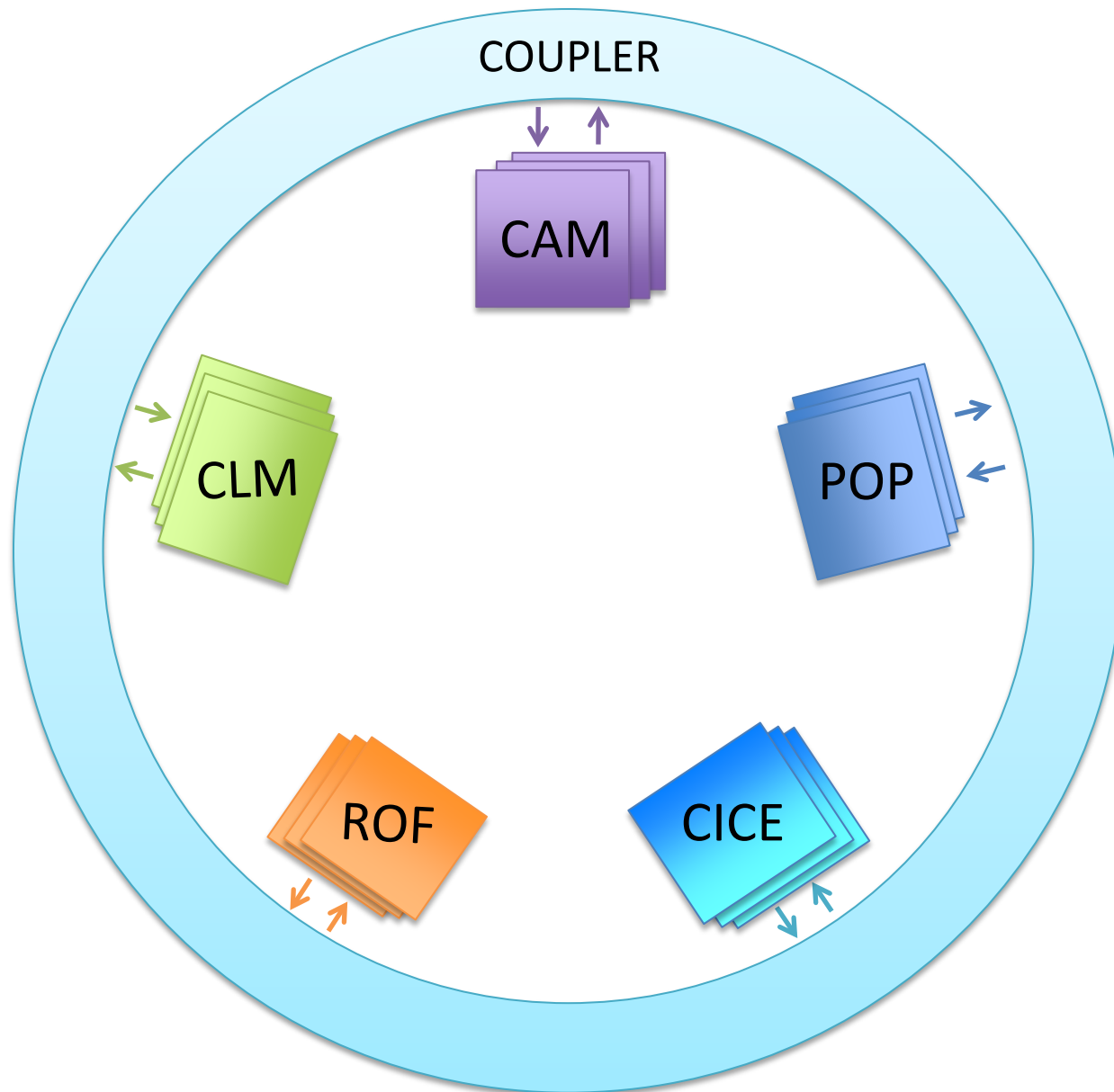
coupled atmosphere-ocean and ocean

What's Next?

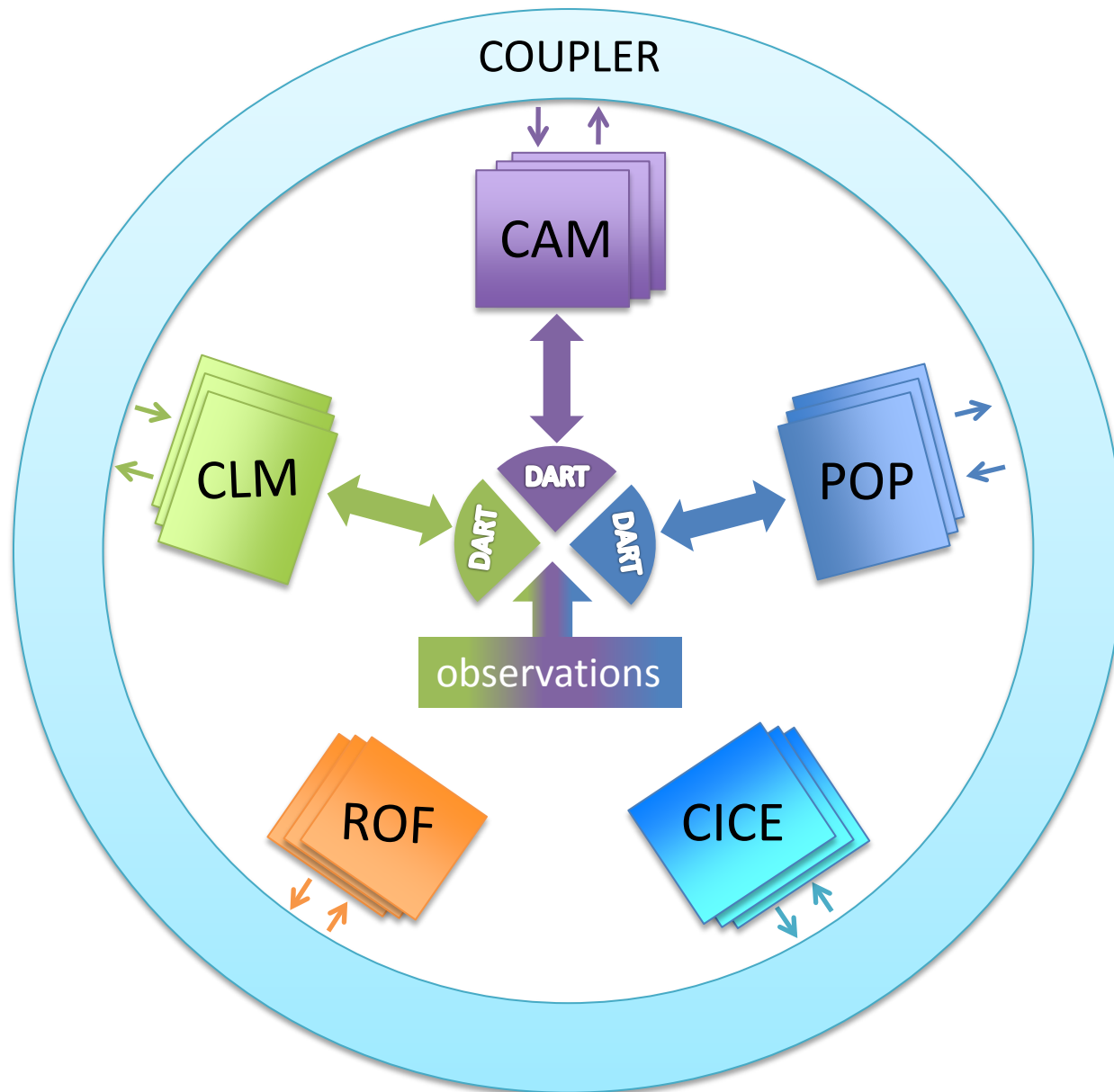
What's Next?

Cross-component data assimilation

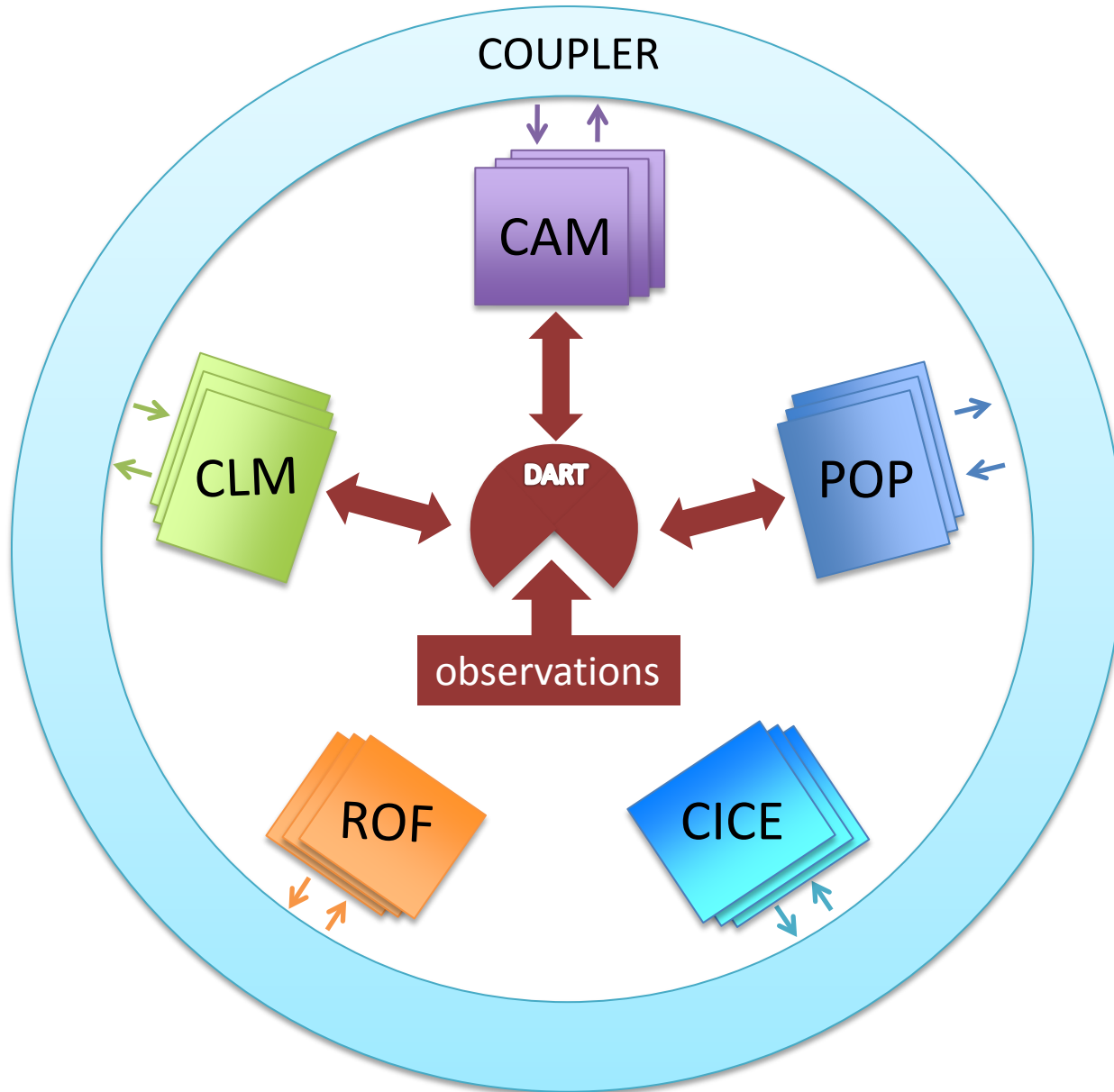
Cross-Component Data Assimilation



Cross-Component Data Assimilation

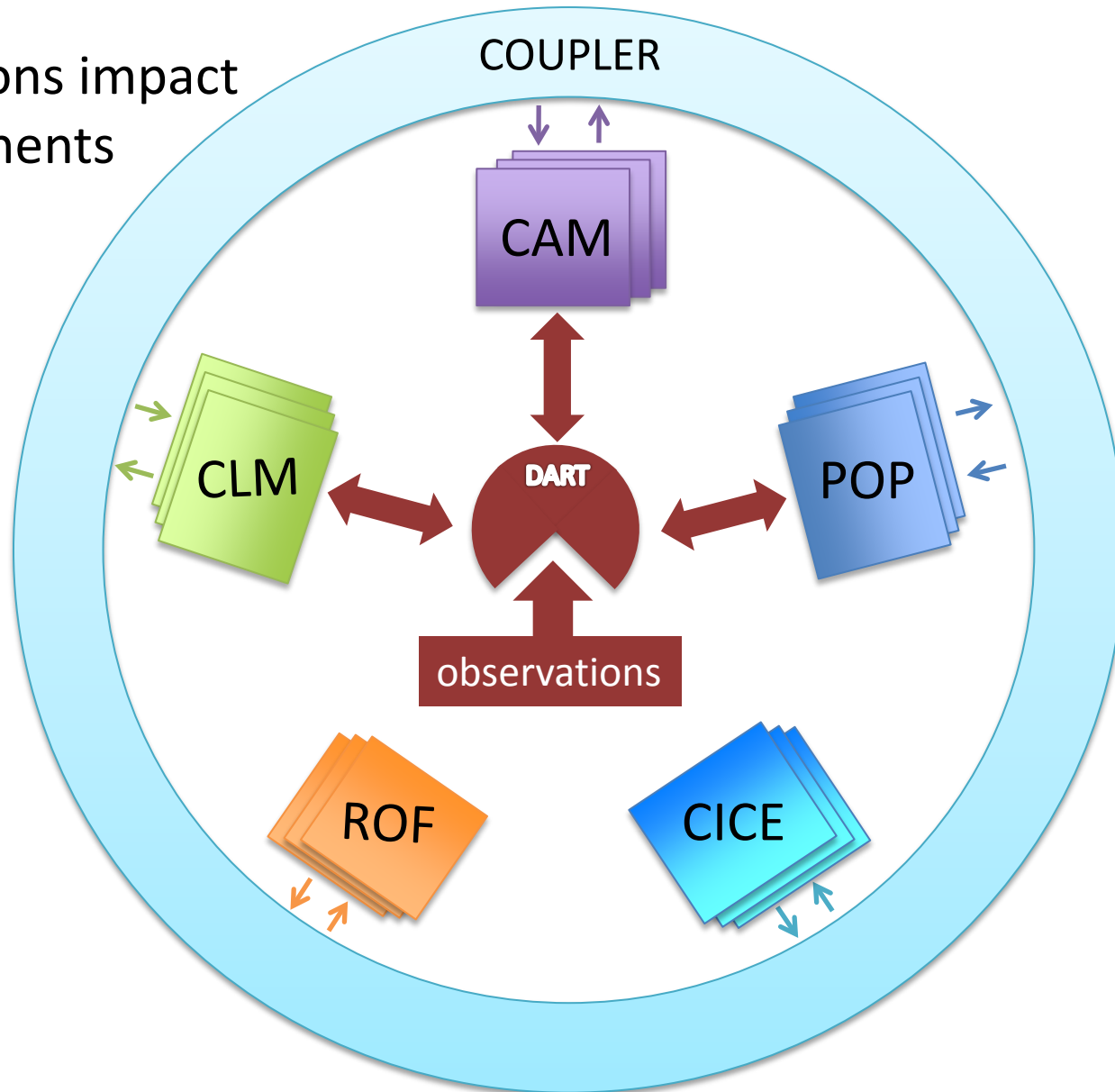


Cross-Component Data Assimilation



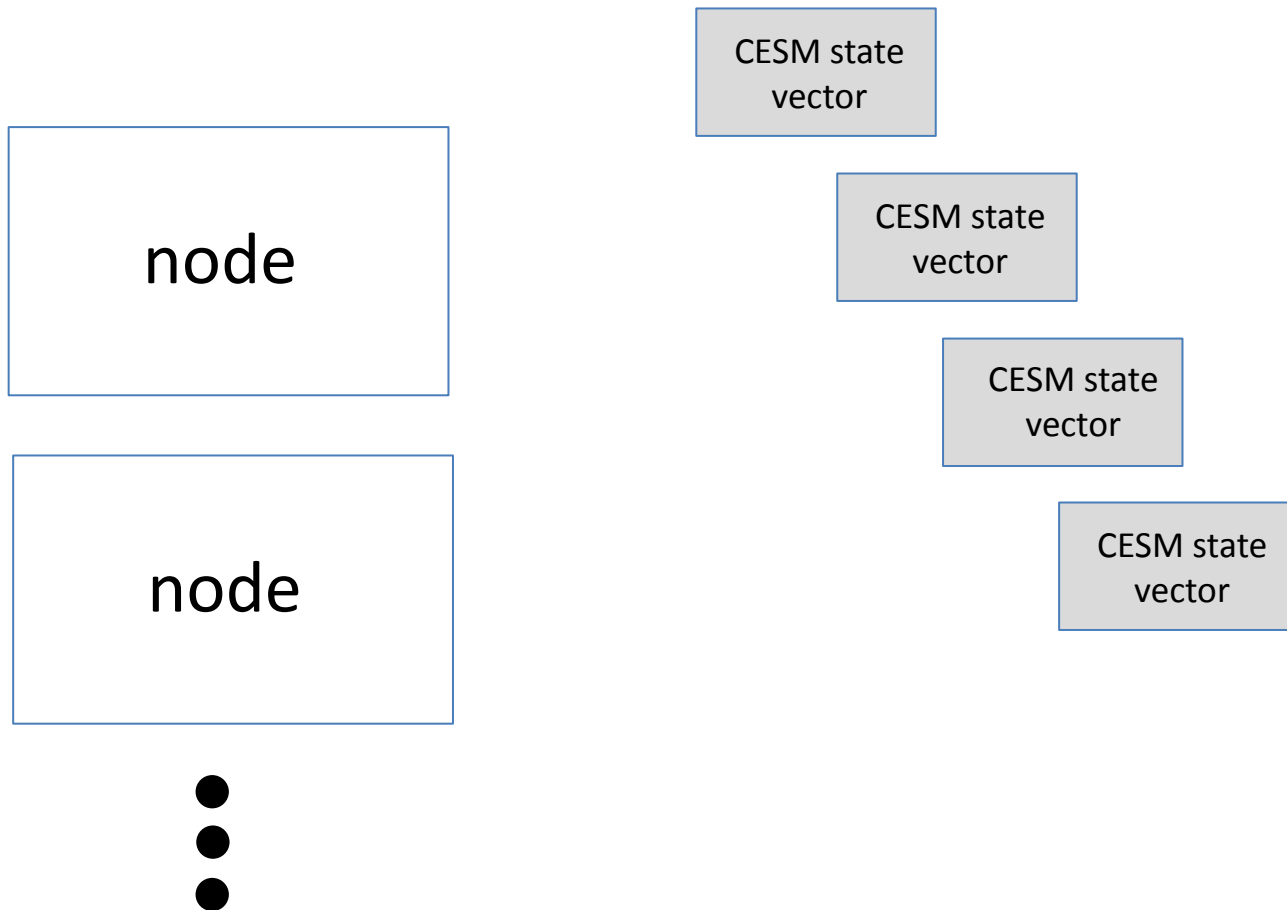
Cross-Component Data Assimilation

Observations impact
all components



Preparing for Cross-Component DA

Preparing for Cross-Component DA



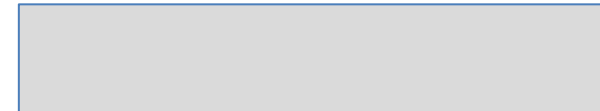
Preparing for Cross-Component DA

node

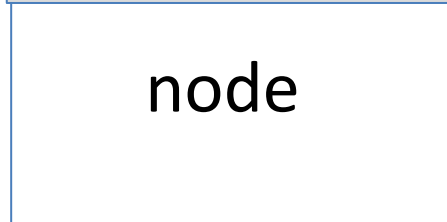
CESM state
vector

node

CESM state
vector



Preparing for Cross-Component DA



Why do we have the whole state?

Why do we have the whole state?

For each state element:

Where am I?

Which observations are nearby?

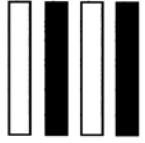
Why do we have the whole state?

For each **observation**:

Where am I?

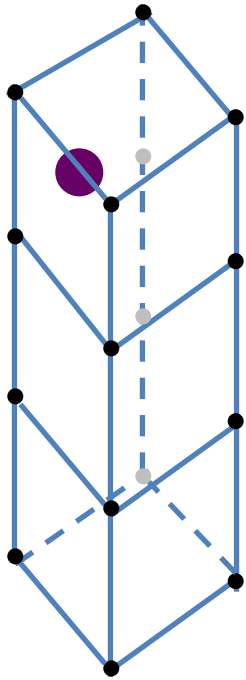
Which observations are nearby?

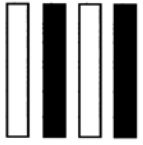
What does each state think I should be?



Calculation of the forward operator

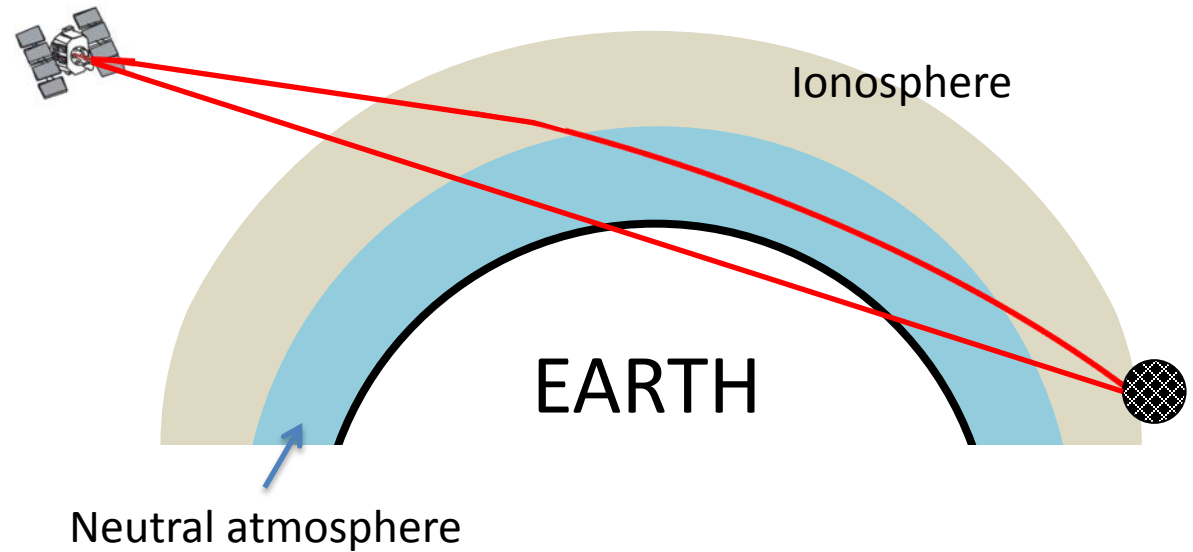
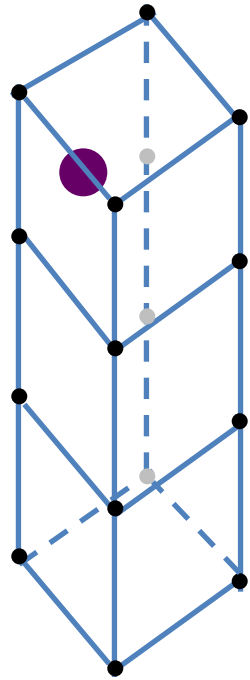
Or, what a state thinks the observation should be





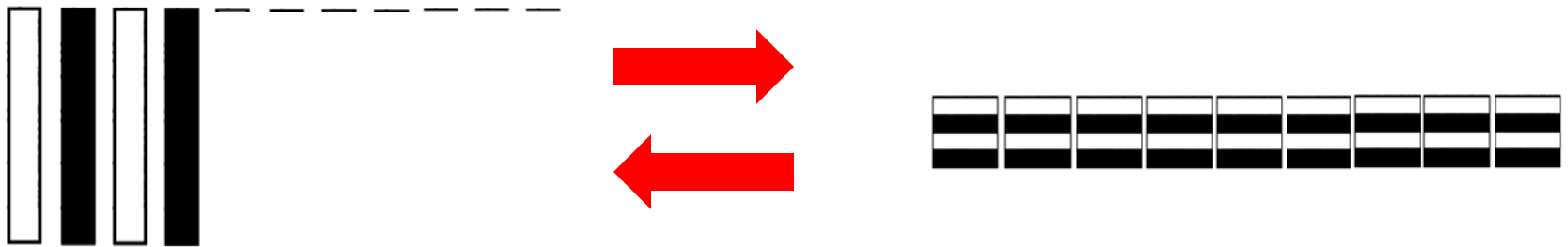
Calculation of the forward operator

Or, what a state thinks the observation should be



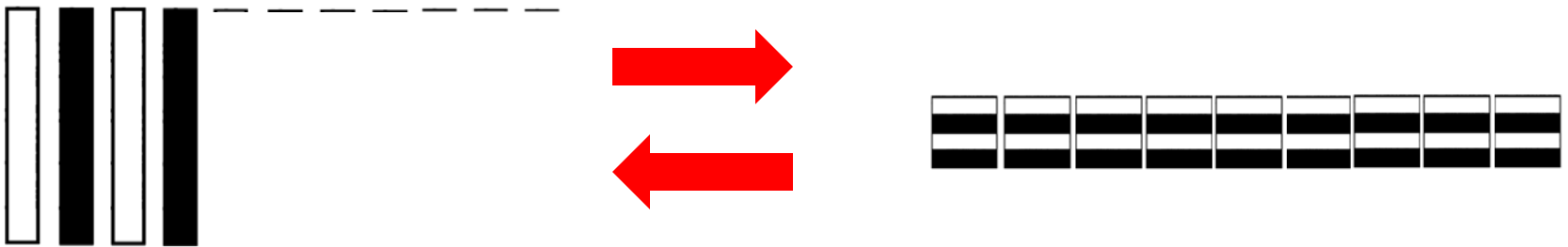
Limitations caused by data storage

- Hard minimum on calculation time
- Hard maximum on model size
- You have to move all your data



What do we do?

- Hard minimum on calculation time
- Hard maximum on model size
- You have to move all your data



Don't move the data

Don't move the data

Use **one sided communication** to grab state elements when needed

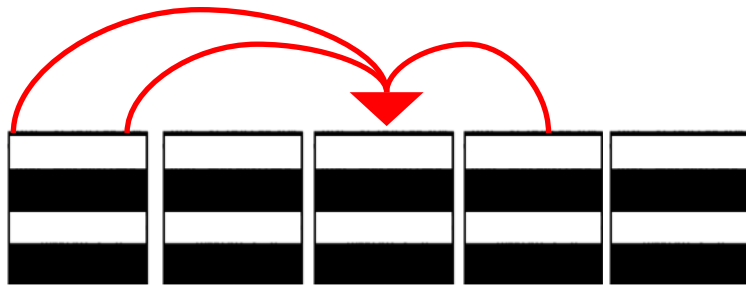
Don't move the data

Use **one sided communication** to grab state elements when needed



Don't move the data

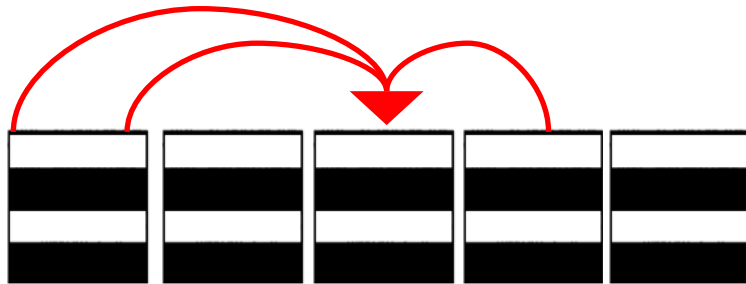
Use **one sided communication** to grab state elements when needed



Reduce data movement

Don't move the data

Use **one sided communication** to grab state elements when needed

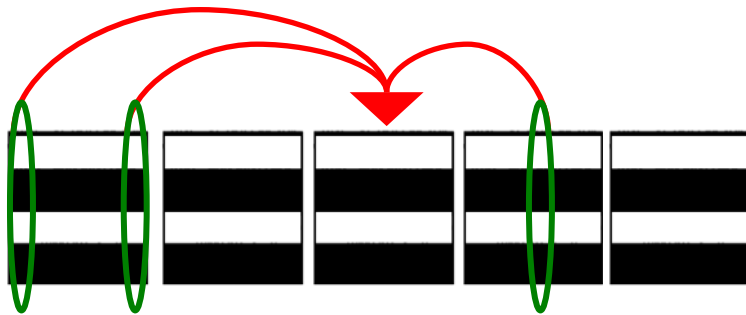


Reduce data movement

Removes hard memory limit

Don't move the data

Use **one sided communication** to grab state elements when needed



Reduce data movement

Removes hard memory limit

Vectorization of forward operator calculations

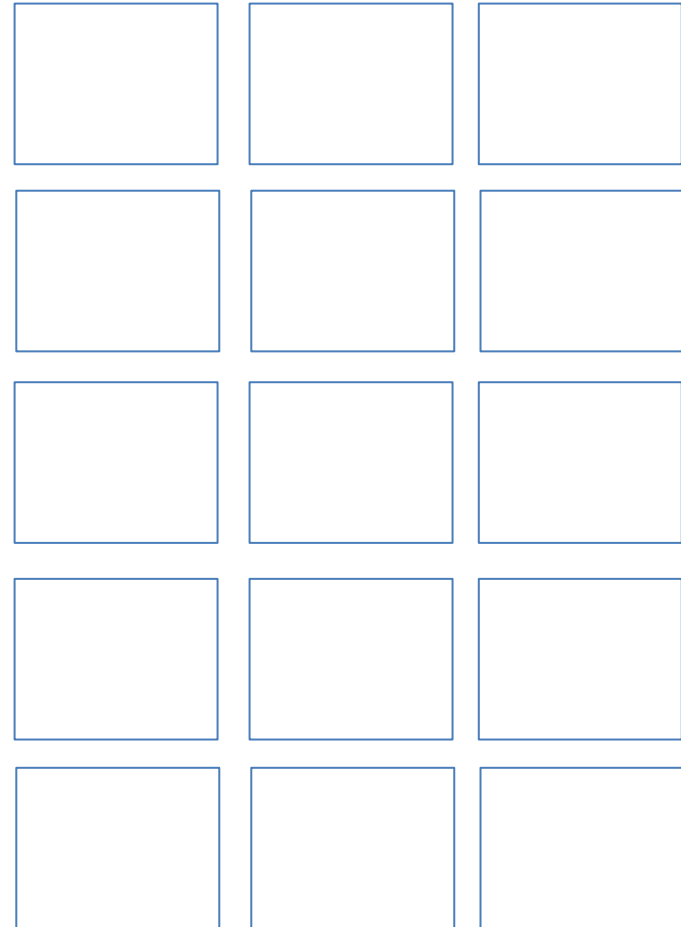
One-sided communication

One-sided communication



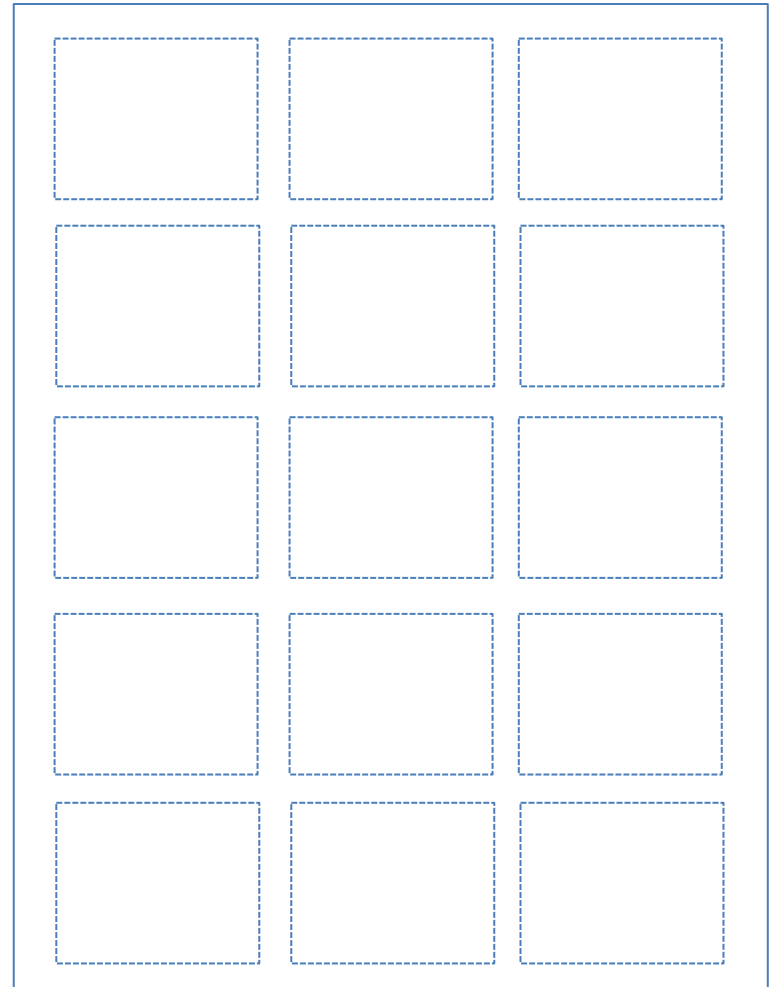
Me

One-sided communication



One-sided communication

Me



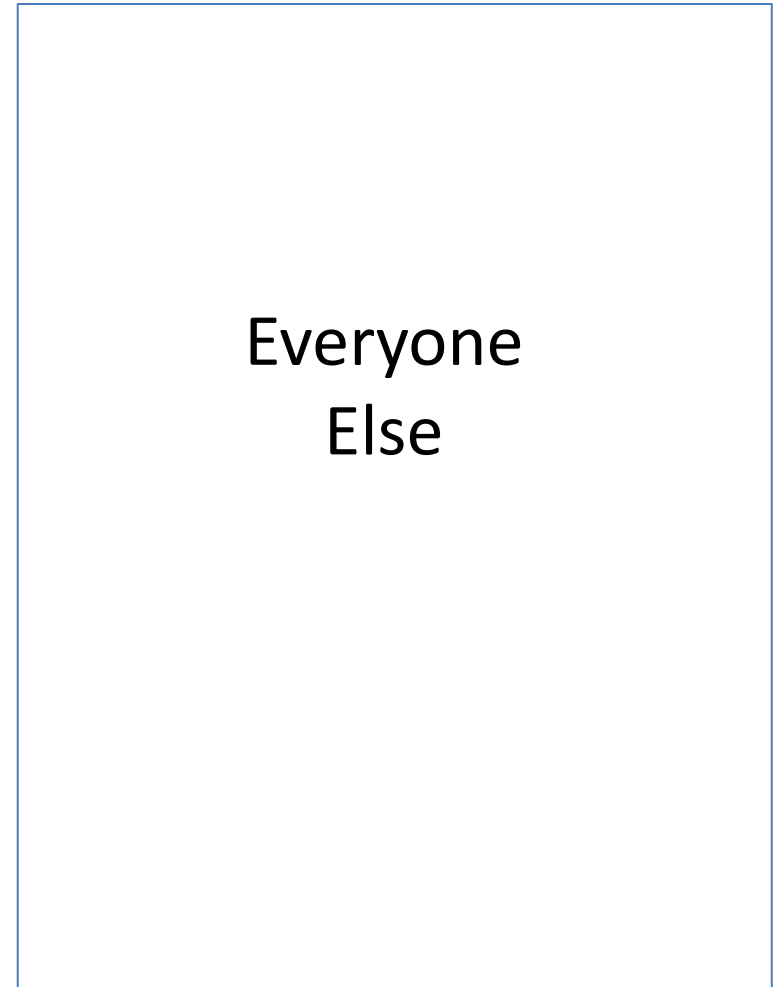
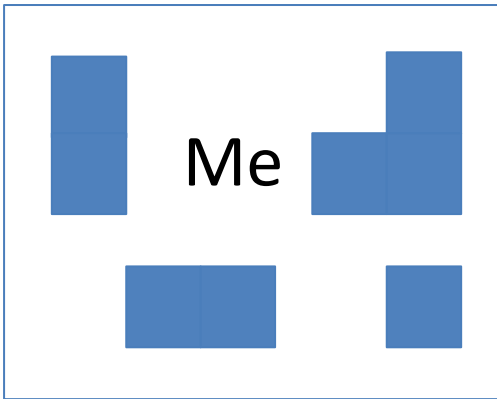
One-sided communication



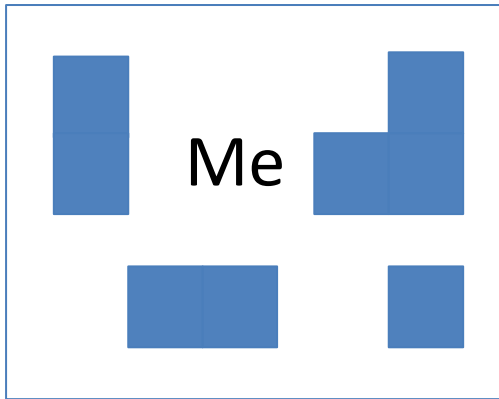
Me

Everyone
Else

One-sided communication

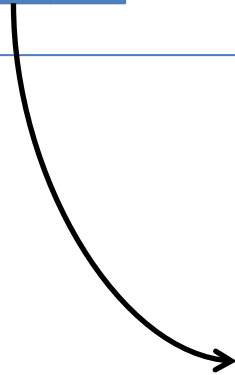
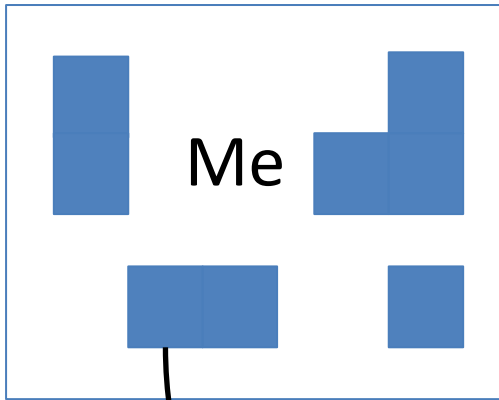


One-sided communication



window

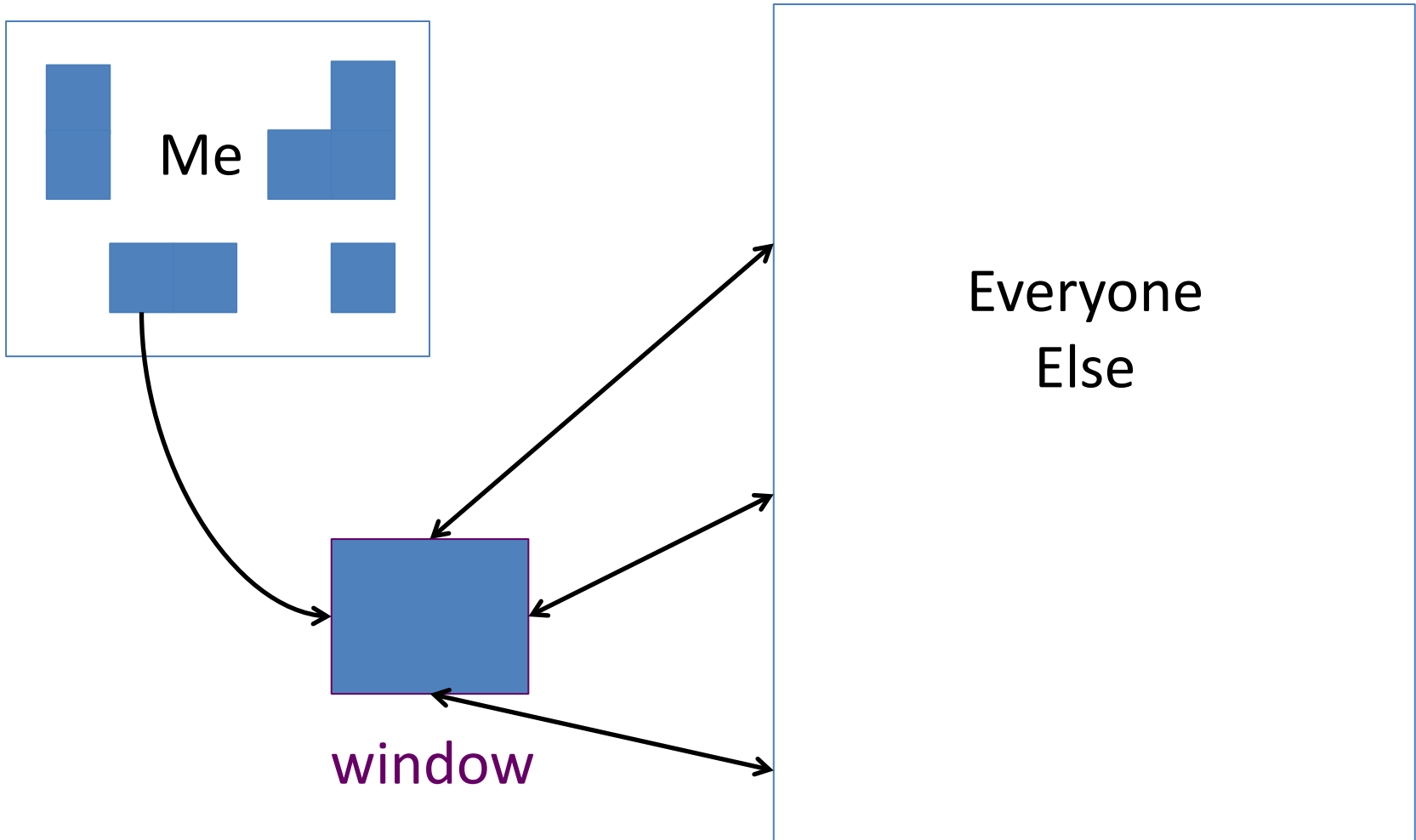
One-sided communication



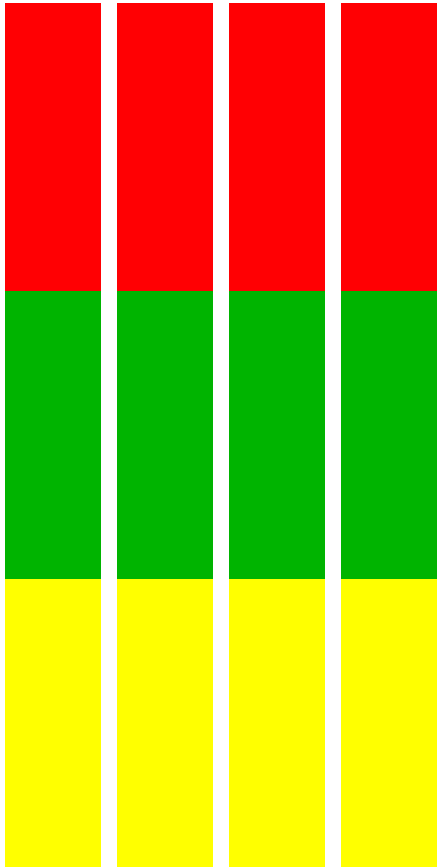
window



One-sided communication



One-sided communication



1

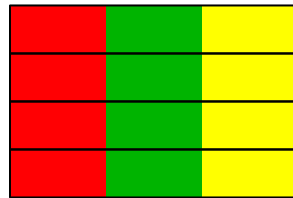
2

3

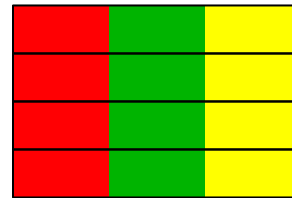


One-sided communication

1



2



3

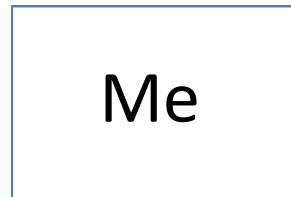


One-sided communication

1

2

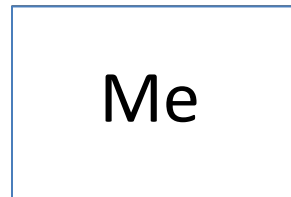
3



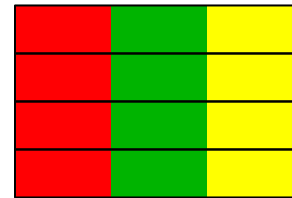
One-sided communication



1



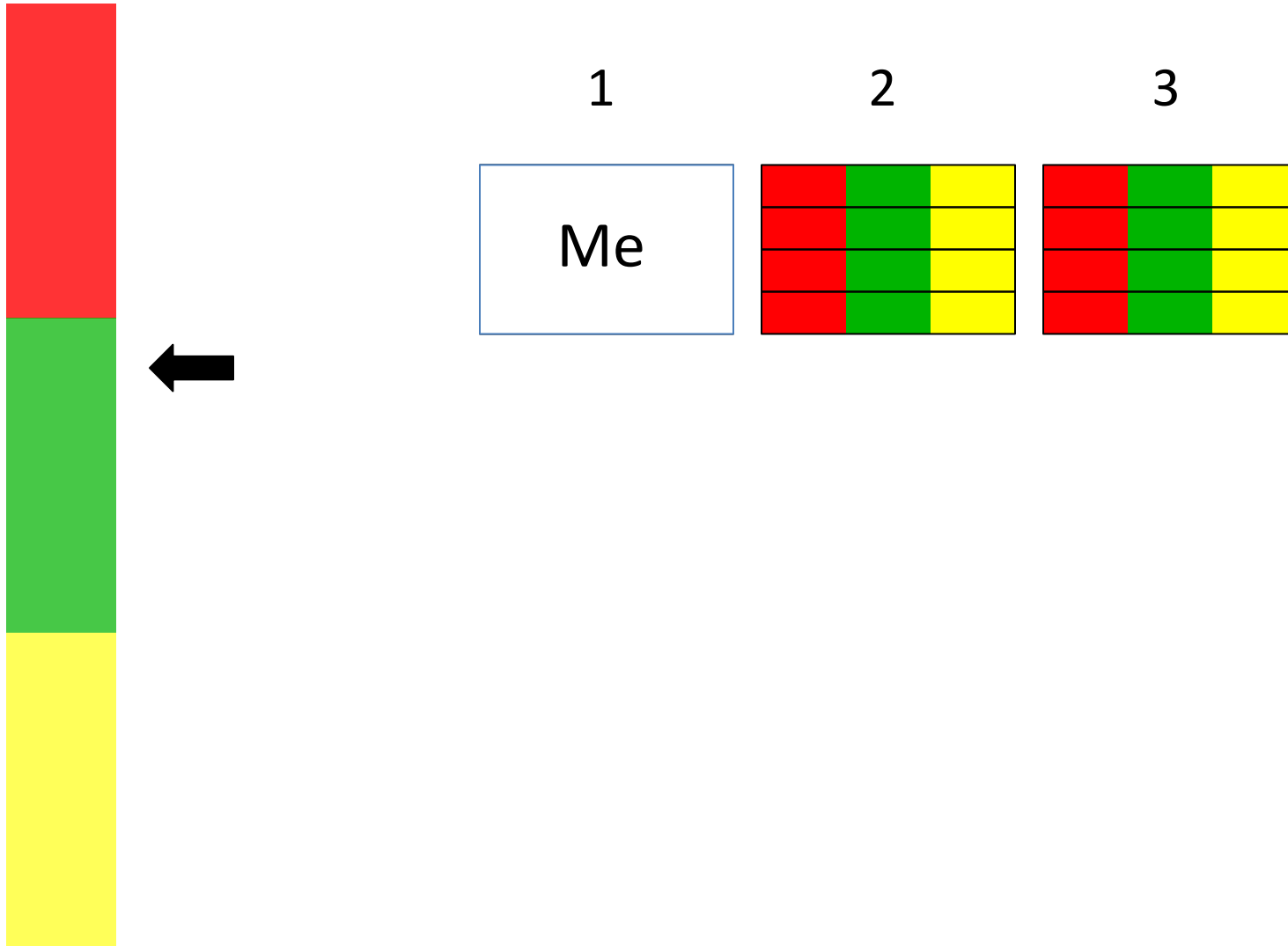
2



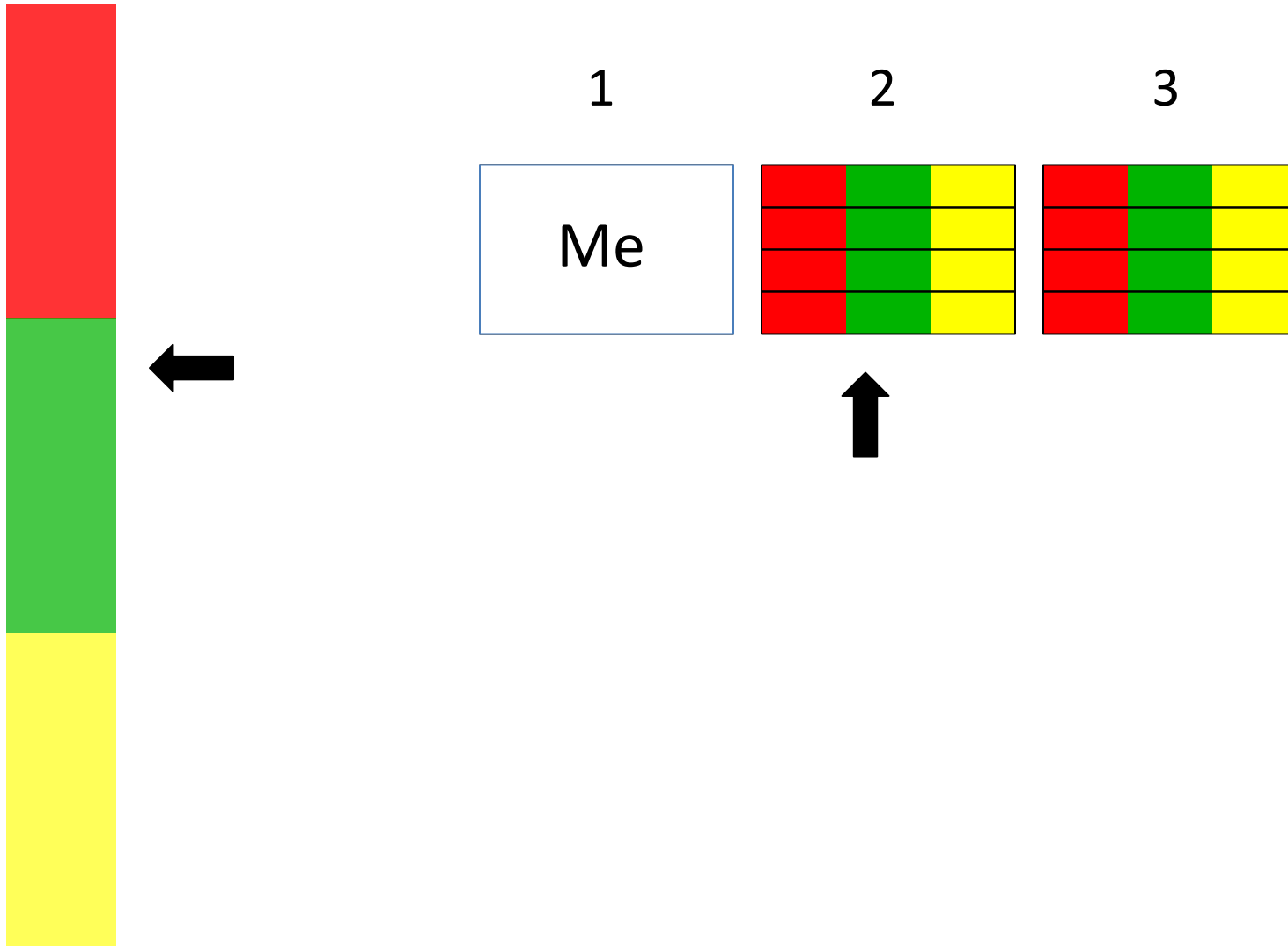
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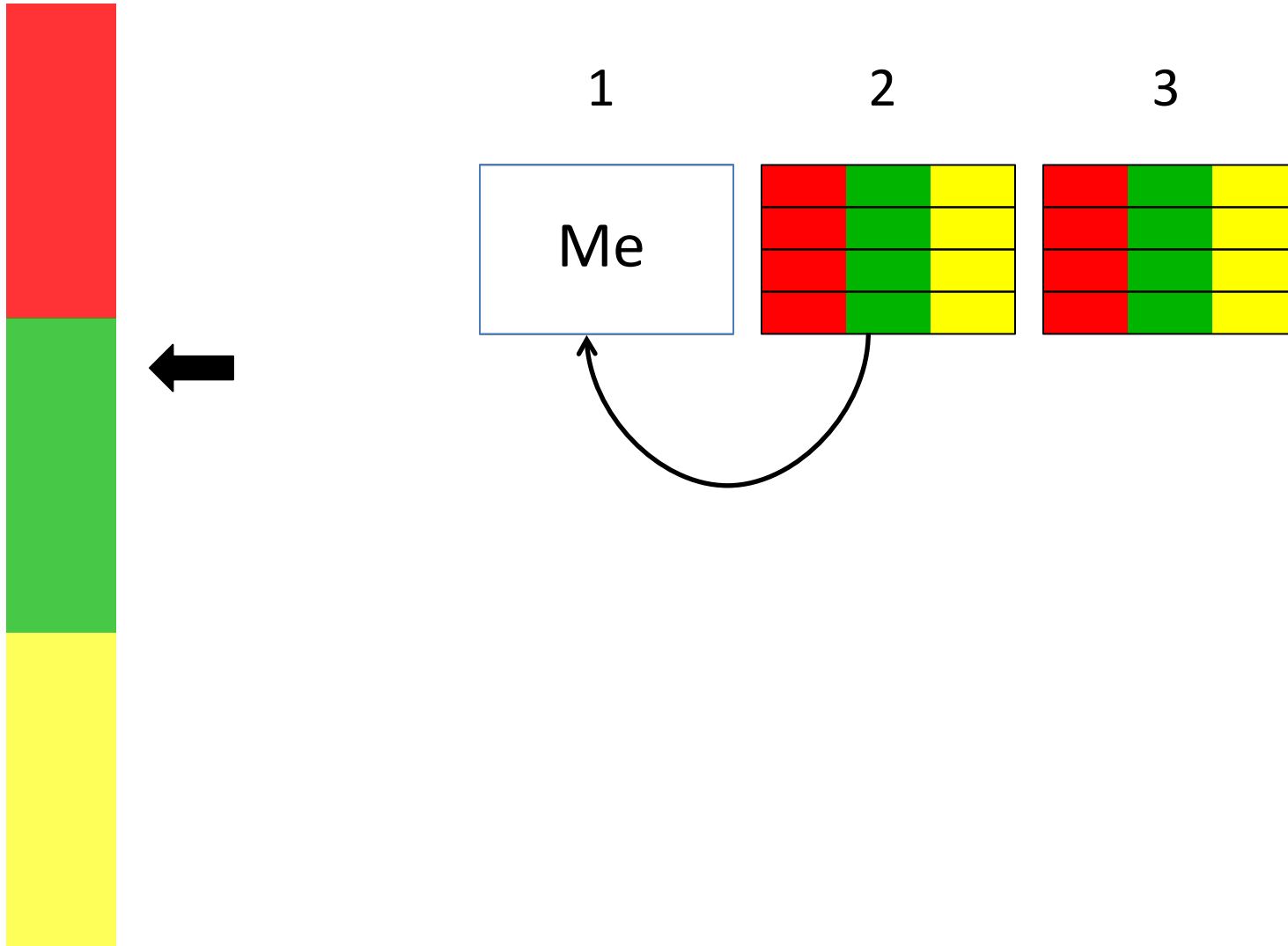
One-sided communication



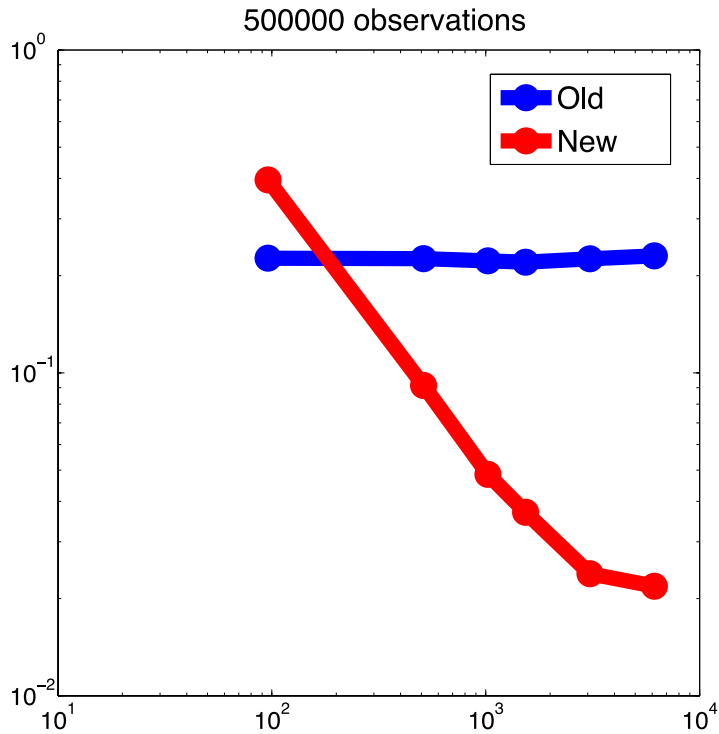
One-sided communication



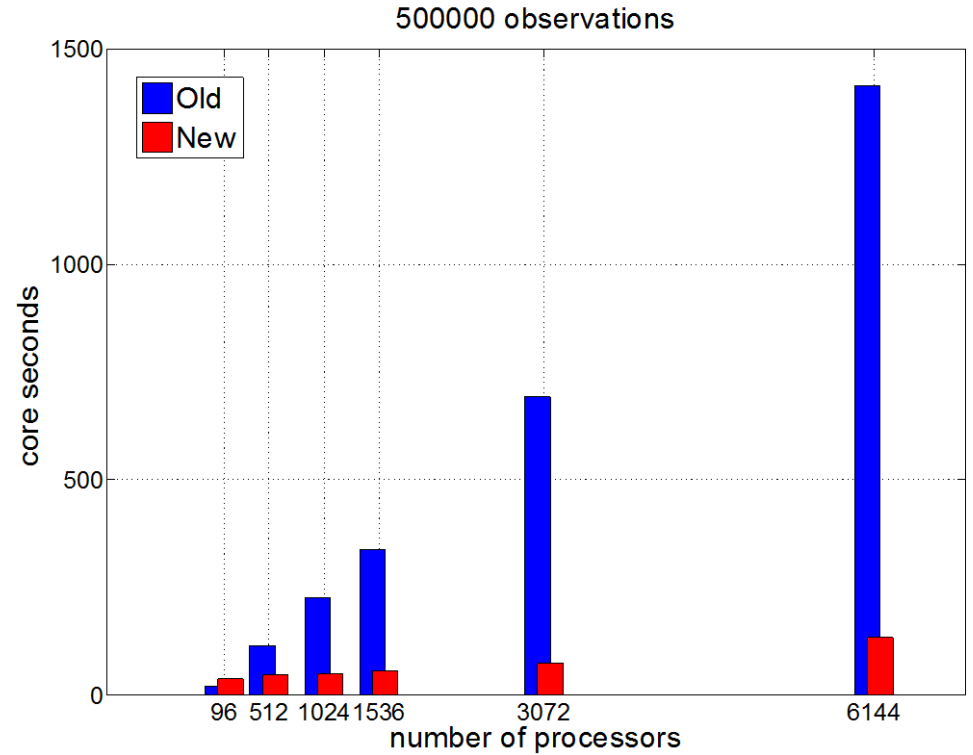
One-sided communication



Toy 10 000 element model



Time

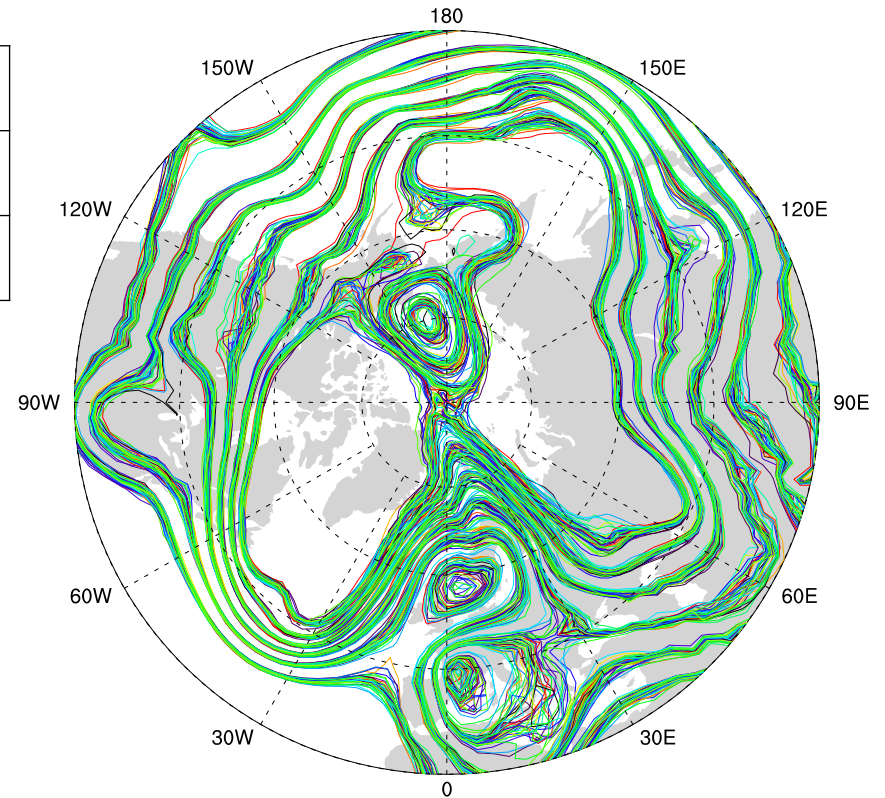


Cost

CAM FV forward operator

Specific humidity only : 23 090 observations

| | | |
|-------------------|------------|-------------|
| processors | 512 | 4096 |
| old | 1.01s | 0.96s |
| new | 0.73s | 0.18s |



CONTOUR FROM 5200 TO 5700 BY 100

More scalable forward operator

Memory



More scalable forward operator

Memory



More scalable forward operator

Memory



More scalable forward operator

Memory



Calculation



4 tasks doing all
observations for 1 copy

More scalable forward operator

Memory



Calculation



4 tasks doing all observations for 1 copy



Lots of tasks doing some observations for all copies

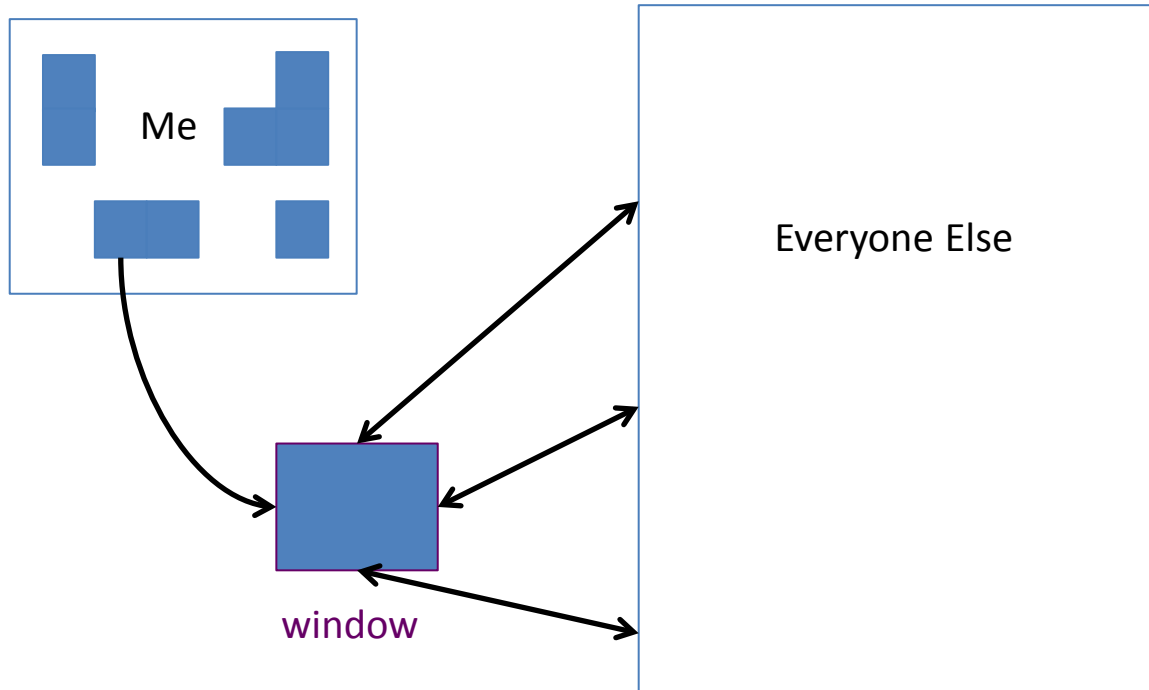
Further Complications

Or, software engineering concerns

Further Complications

Or, software engineering concerns

Need to remain user extensible



Questions?



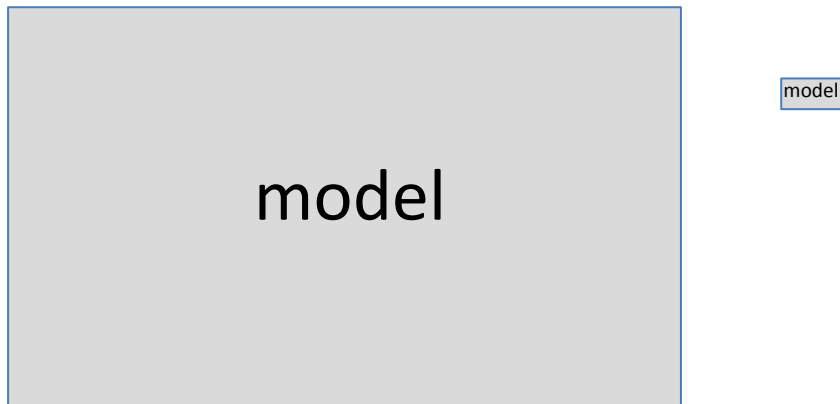
<http://www.image.ucar.edu/DARes/DART>

dart@ucar.edu

Further Complications

Or, software engineering concerns

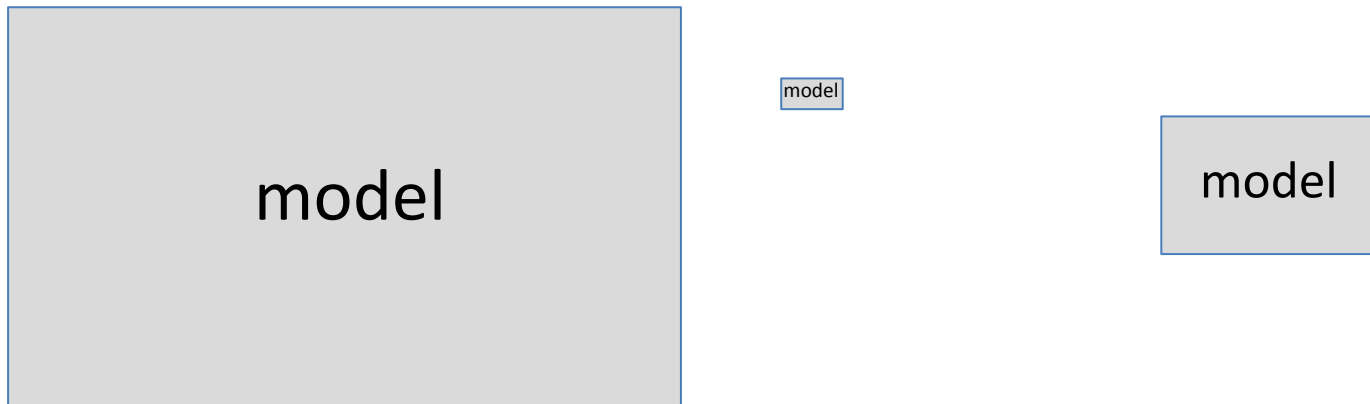
What about all the users who are happy with DART as it is?



Further Complications

Or, software engineering concerns

What about all the users who are happy with DART as it is?



10

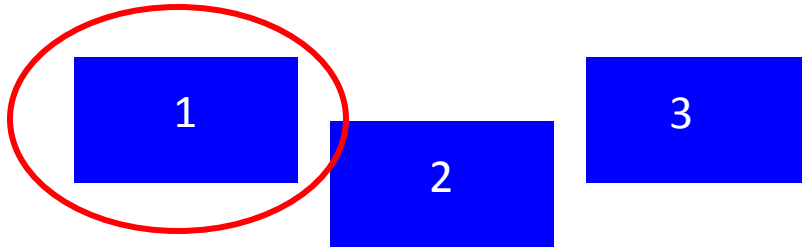
IO

Models do not run ensemble complete



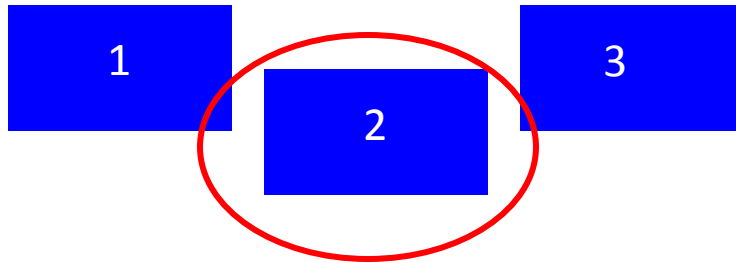
IO

Models do not run ensemble complete



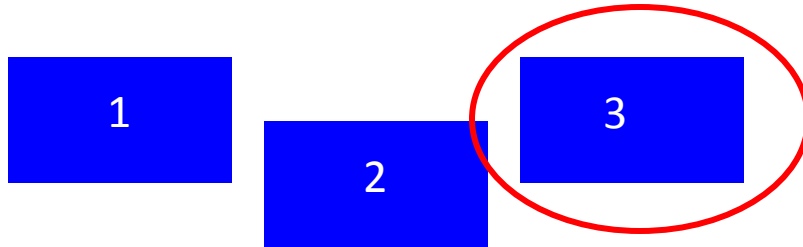
IO

Models do not run ensemble complete



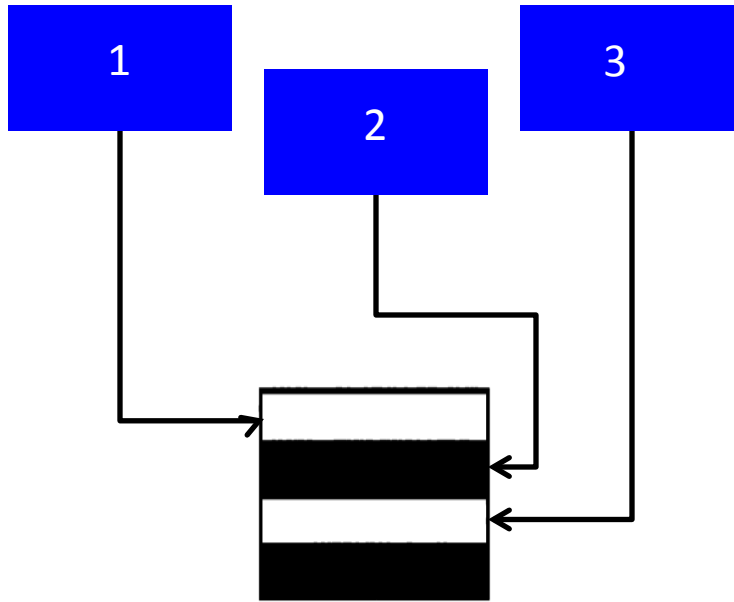
IO

Models do not run ensemble complete



IO

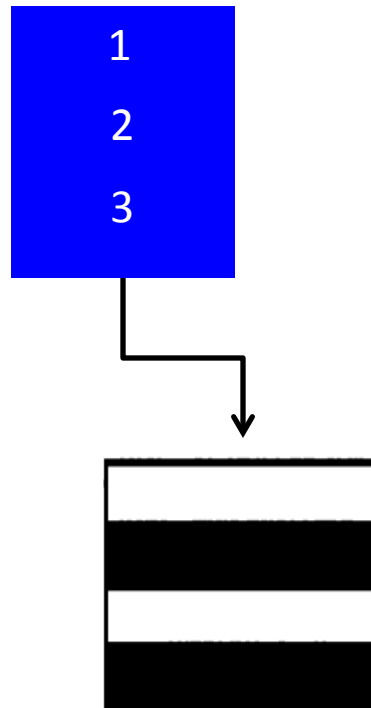
Models do not run ensemble complete



You have to move data from the model to DART

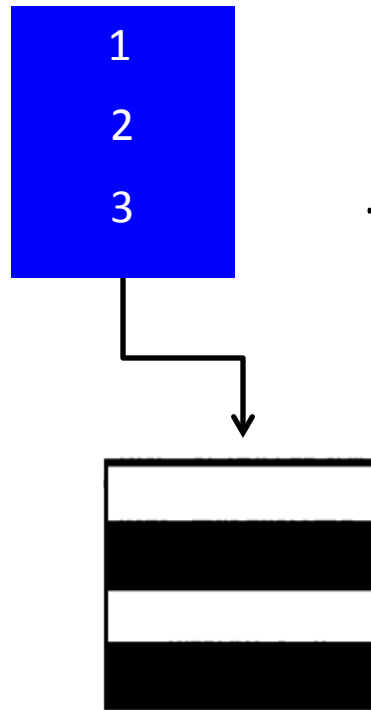
IO

Ideally:



IO

Ideally:

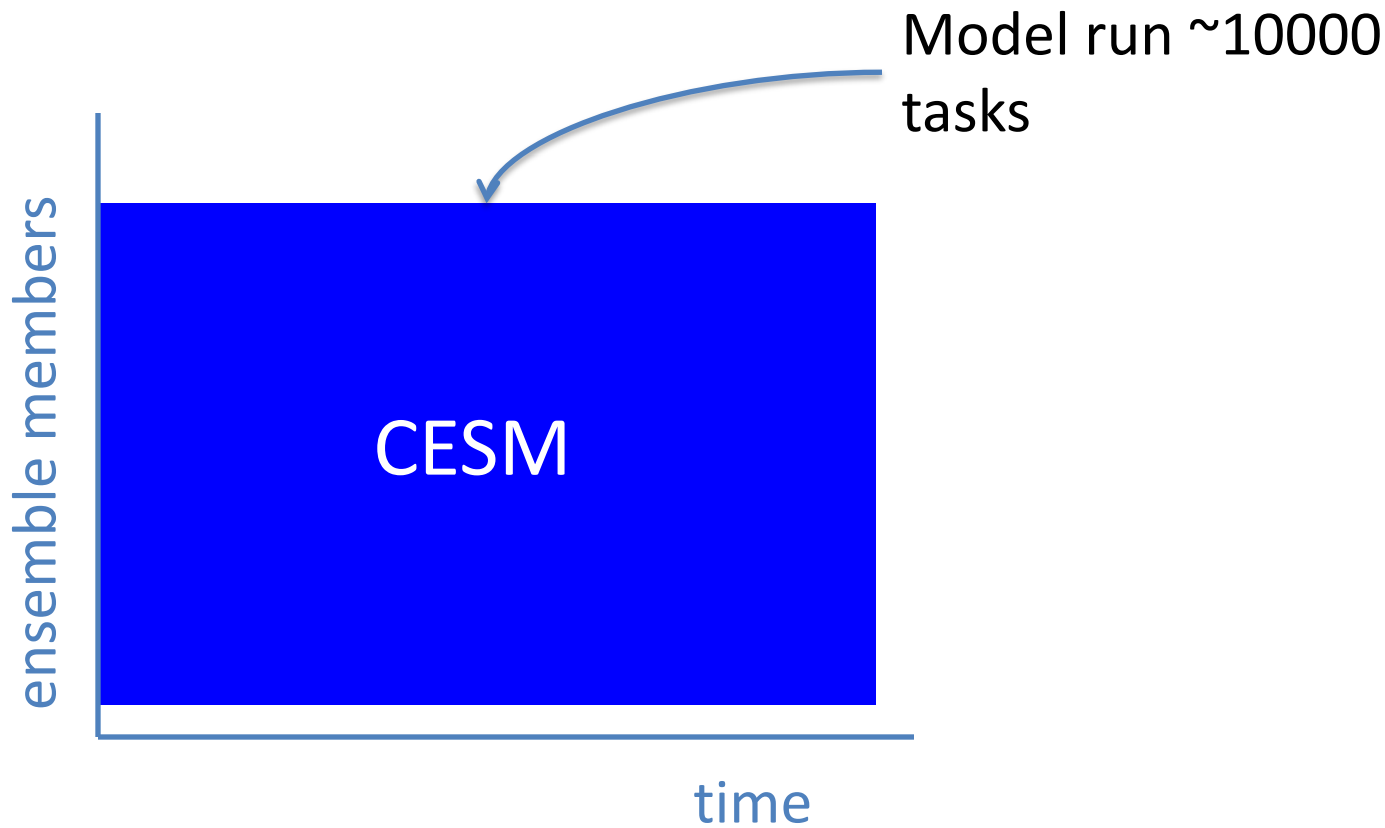


Never looks like
this in memory

10

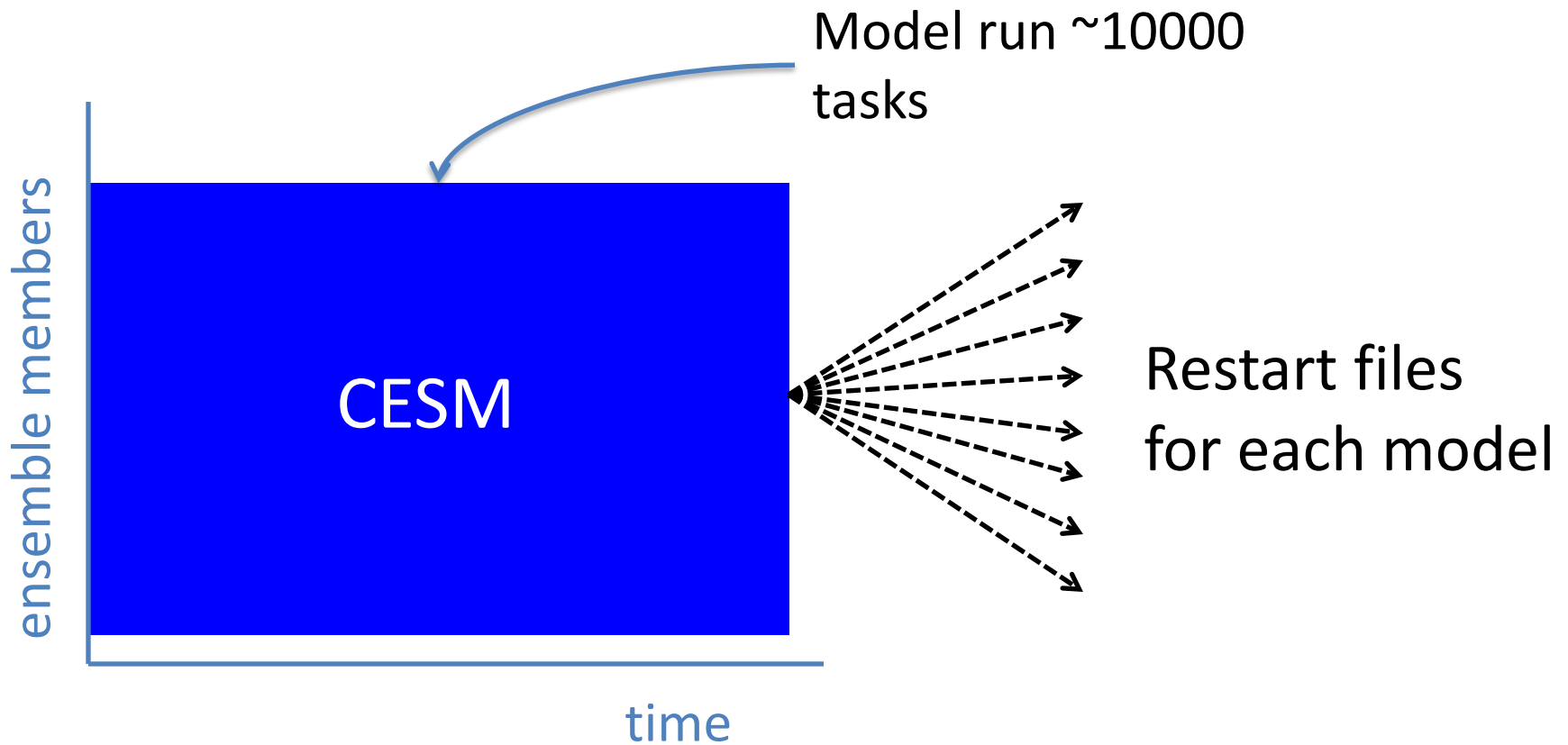
All DART requires is that there are multiple model forecasts

IO



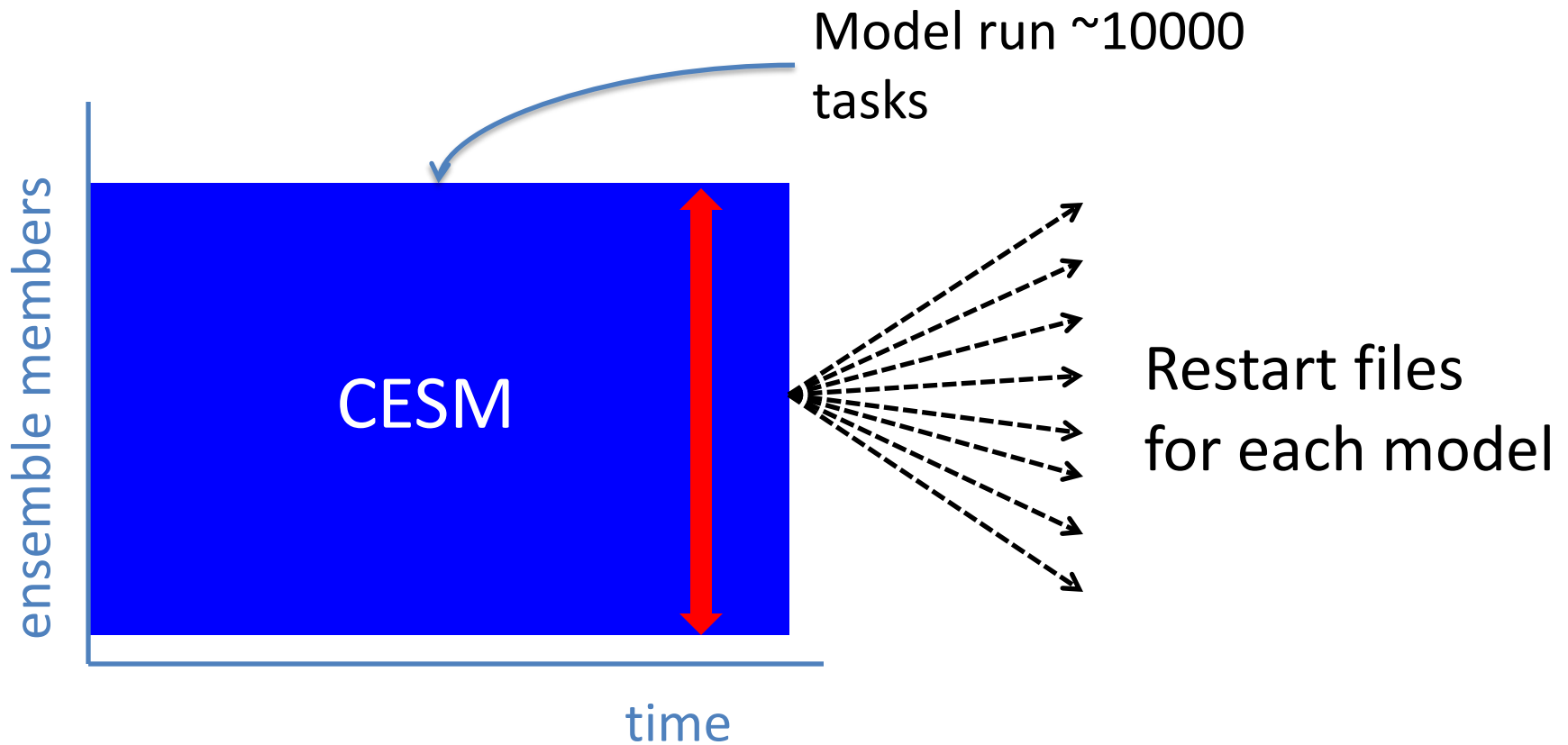
Multi-instance forecasts create the ensemble

10



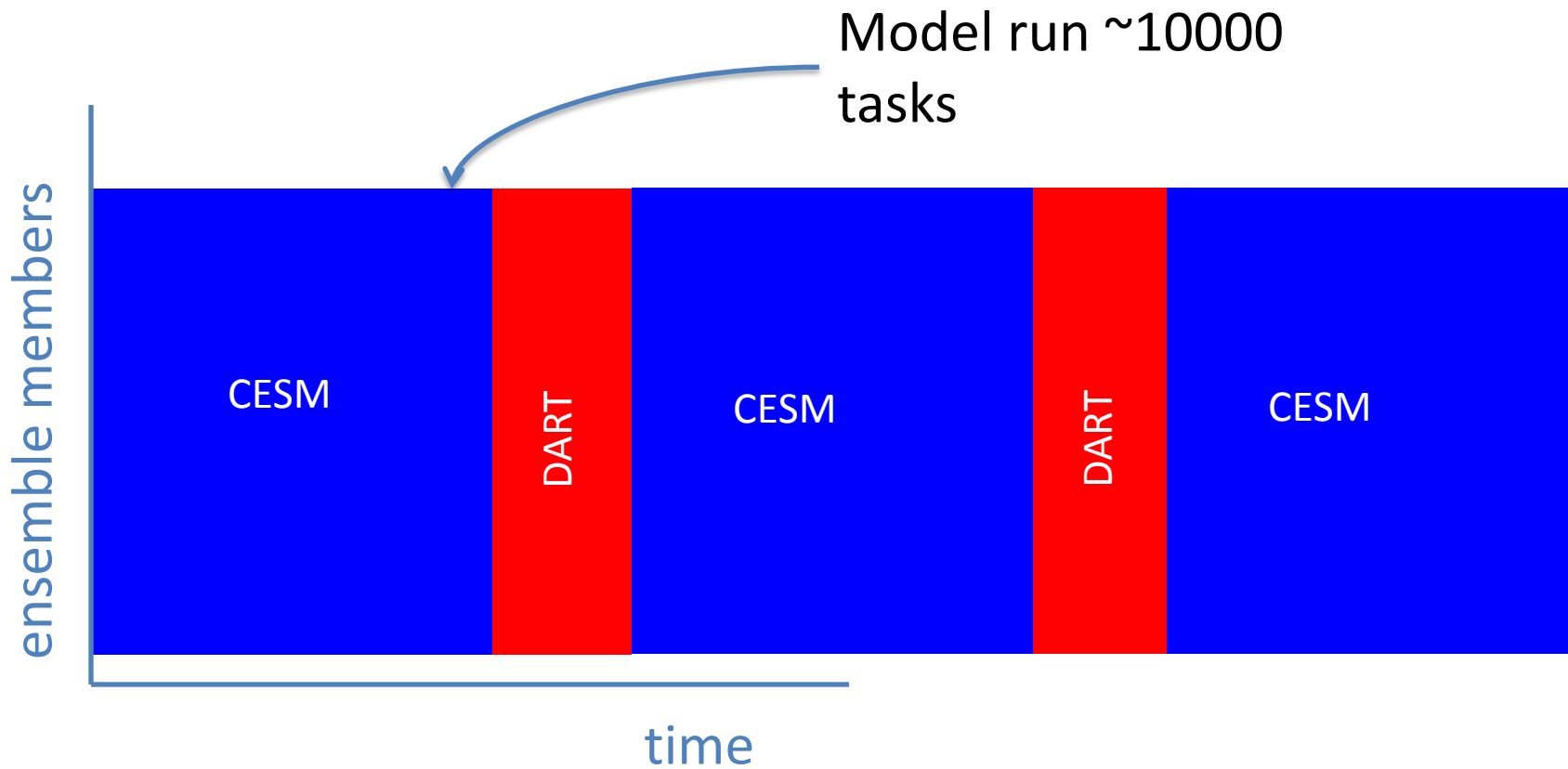
Multi-instance forecasts create the ensemble

IO



Multi-instance forecasts create the ensemble

IO



Multi-instance forecasts create the ensemble

But vectorization is not perfect:

An observation can be in different model levels depending on the state

