

An introduction to LIVVkit 2.0

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CLIMATE CHANGE SCIENCE INSTITUTE
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Confidence feeling or belief that one can rely on something

Credibility the quality of being trusted and believed in



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V&V is a set of confidence building techniques



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V&V is a set of confidence building techniques

- **Software verification**
Did we build what we intended?
- **Numerical verification**
Are we solving the equations correctly?
- **Performance validation**
Did we build what the users needed?
- **Physical validation**
Are we using the right physics?



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V&V is not enough! Credibility relies on

- Reproducibility
- Transparency
- Discoverability



LIVVkit 1.0

- Publicly released July 9, 2015.
- Used to verify 16 pull requests
 - \approx 180 commits
- Included:
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 - Software verification
 - Performance verification
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 - Worked with Jeremy Fyke, Lauren Vargo, Marcus Lofverstrom
 - Too complicated
 - Large dev. burden to learn LIVVkit and generate output
 - LIVVkit requirements unclear...



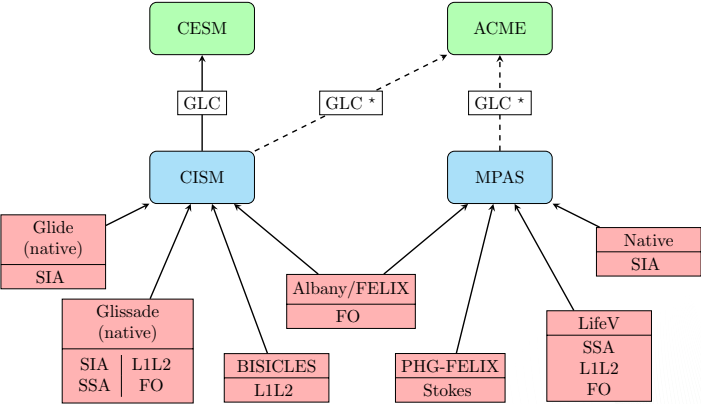
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- Move beyond CISM-Glissade...



Models and dycores, and solvers, oh my!



LIVVkit 2.0

Release planned for: July 8, 2016

Paper submission to JAMES in July

- glossary
- defined purpose, philosophy, and requirements
- example analyses

Improvements:

- reduced command line options (5, 3 primary)
- modern python practices
 - packaged and installable (pip)
 - is a library
 - python 3 (or cross compatibility between 2,3)
 - documentation via Sphinx
 - anaconda



LIVVkit 2.0

“Full” coverage of V&V

- verification
 - numerical
 - software
 - performance
- validation
 - performance
 - physical

Validation structure has been improved

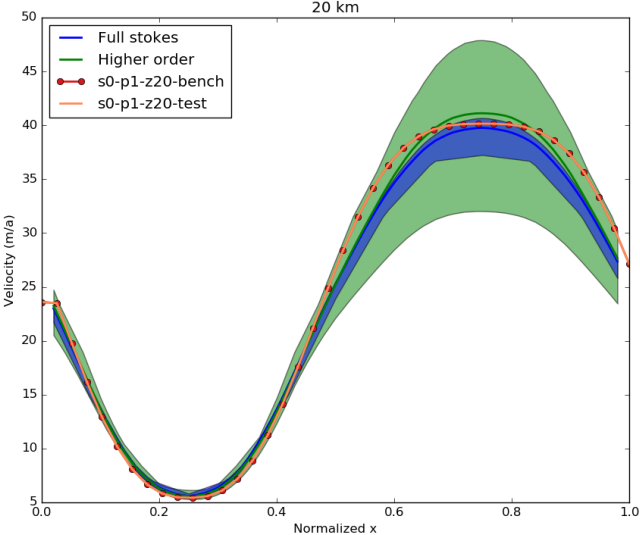
- Clarity and ease of use
- LIVVkit automatically renders output
 - ‘element helper’

Models and dycores have now been encapsulated

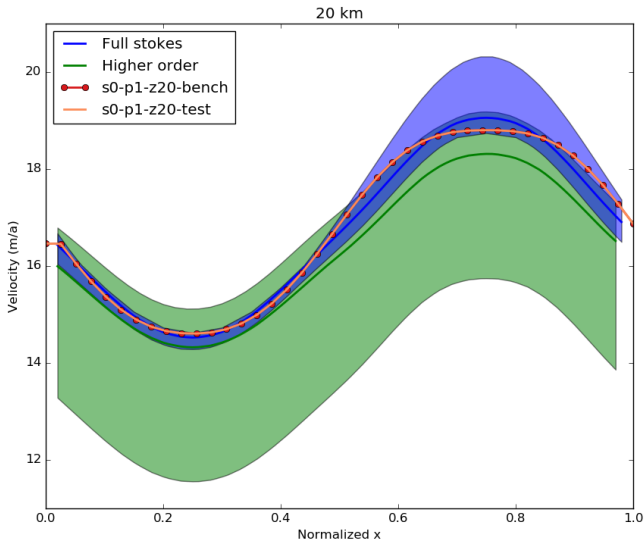
- ‘Bundles’
- LIVVkit and model-specific functionality separated



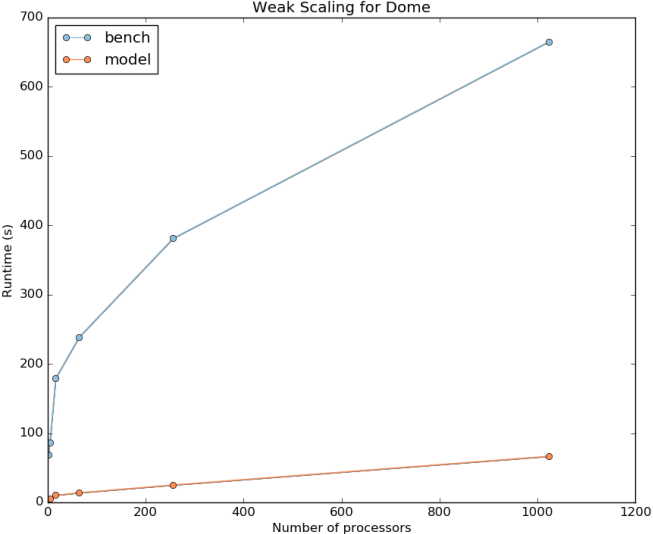
Numerics: ISMIP-HOM A



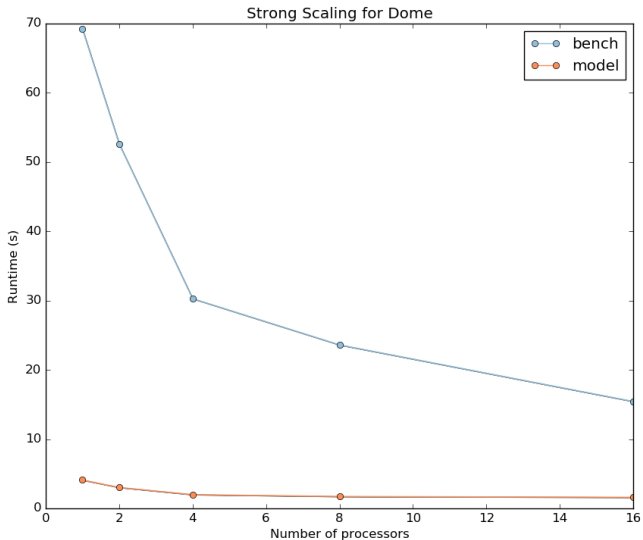
Numerics: ISMIP-HOM C



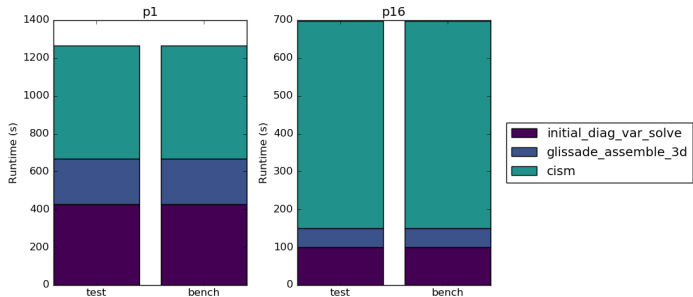
Performance: dome, weak scaling



Performance: dome, strong scaling



Performance: dome, timing



Validation: element helper

```
import matplotlib.pyplot as plt
from livvkit.util.datastructures import ElementHelper

...

plt.savefig(plot_file)
plt.close()

el = ElementHelper.image_element(
    title,
    description,
    plot_file)
)

return el
```

Next...



**WE NEED
YOU!**

Validation: we need a list of **variables of interest** and **data** sources...

Workshop summer 2017, AGU session and/or town hall 2017...



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