

**The CCSM
Climatological Data Atmosphere Model (datm6)
Version 6.0**

**Combined
User's Guide,
Source Code Reference,
and Scientific Description**

Brian G. Kauffman

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Community Climate System Model
National Center for Atmospheric Research, Boulder, CO
<http://www.cesm.ucar.edu/models>

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1 Introduction

CCSM coupled model is based on a framework which divides the complete climate system into *component models* connected by a *coupler*. This design requires four component models – atmosphere, sea-ice, land, and ocean – each connected to the coupler, and each exchanging data with the coupler only.

The Climatological Data Atmosphere Model (datm) functions as the atmosphere component in a CCSM configuration. The datm atmosphere component interacts with the coupler just like any atmosphere model would, but it is not an active model, rather, it takes atmosphere data from an input data file and sends it to the coupler, ignoring any forcing data received from the coupler. Typically the input data file contains mean daily data generated by an active CCSM atmosphere model (it's unlikely that real world observations exists for all the required fields). Such a "dummy" atmosphere model is useful for doing ocean + ice spinup runs.

Important note: When assembling a CCSM configuration, the user must carefully consider the limitations and requirements of all components and make sure that the complete set of component models will interact in a meaningful way. In particular, the user must verify that the data provided by this model is adequate for their specific application.

2 Input Datasets

2.1 Atmospheric Data

The model cycles thru netCDF data files containing all the data the coupler expects from an atmosphere model. Each file contains one year's worth of data – 365 daily mean fields. This input data must have the same domain (resolution and coordinate arrays) as the datm model. The model can cycle thru a multi-year sequence of data. Generally the input data files are created from history files that are output from the CCSM's active atmosphere component model (CAM or CCM). These files can be replaced by other data files that are in the same format. Because netCDF files are self describing, one can query the file itself for specifics about the file format.

2.2 Domain Data

On startup, the model reads in domain data from a netCDF file. Data exchanged with the coupler will be on the model domain. This file contains x & y coordinate arrays. The model uses a rectilinear grid with 2d coordinate arrays $x(i,j)$ & $y(i,j)$. Because the input atmosphere data (above) is on the same domain as the datm model, and because the input atmosphere data contains domain information, any input atmosphere data file can also serve as a domain data file. In fact, the first file in the input data file sequence is used as the domain data file

2.3 Namelist

On startup, the model reads an input namelist parameter file from stdin. The model has very few input namelist parameters. Typically the only input parameters that are required are those that specify how often the model will communicate with the coupler, and those that specify the sequence of input atmosphere data files. See the section on input namelist variables for a complete list and description of namelist parameters.

3 Namelist

The model reads an input namelist from stdin at runtime.
Following is a list and description of available namelist input parameters.

case_name
Type: character(len=16)
Default: "null"
Required: no, but highly recommended
Description: This is the case name text string that appears in output files to help identify the model run.

case_desc
Type: character(len=64)
Default: "null"
Required: no, but highly recommended
Description: This is a short text string (typically less than 80 chars) which is included in output files to help identify the model run.

ncpl
Type: integer
Default: 24
Required: no
Description: This specifies how many times per day the model communicates (exchanges data) with the coupler.

data_dir
Type: character(len=256)
Default: "null:"
Required: yes
Description: This specifies where the land data input file sequence is found. Examples:
(1) data_dir = "cp:~jdoe/data " => look for input data in user djoe's home directory in the data subdirectory.
(2) data_dir = "mss:/JDOE/data " => look for input data on NCAR's Mass Storage System archival device.
(3) data_dir = "null:/whatever " => the "null:" prefix indicates that the data has already been pre-positioned in the execution directory.

data_fname
Type: character(len=256)
Default: "null"
Required: yes
Description: This specifies file names of the input data files. The data files are assumed to contain one year's worth of data -- 365 daily averages. The file name can be any valid unix file name. This is a template file name, that is, somewhere in the file name must be the text substring "yyyy" which will be replaced by a specific year to create the actual file name. For example, if data_fname = "f20.005.cam2.h1.yyyy-01-01-00000.nc" and datm model needs data for year 2002, it will construct the file name "f20.005.cam2.h1.2002-01-01-00000.nc", and look for this file in the directory data_dir described above.

data_year0
Type: integer
Default: 1

Required: yes
Description: This specifies the first year in the input atmosphere data file sequence.

data_nyear
Type: integer
Default: 1
Required: no
Description: This specifies the number of years in the input atmosphere data file sequence.

data_oyear
Type: integer
Default: 1
Required: no
Description: This specifies the "offset year" for the input atmosphere data file sequence. The data file for data_year0 will coincide with the simulation year data_oyear.

mss_rmlf
Type: integer boolean (0 <=> false)
Default: 0
Required: no
Description: This specifies whether to remove the local copy of an input atmosphere data file after it has been read in by the model. Iff mss_rmlf = 0, then the model will not remove the local file.

flux_albfb
Type: integer boolean (0 <=> false)
Default: 0
Required: no
Description: If flux_albfb = true, then albedo feedback is activated.

flux_swfact
Type: real
Default: 1.0
Required: no
Description: This factor is applied to all shortwave fields. This can be used to arbitrarily increase or decrease shortwave values.

info_dbug
Type: integer
Default: 1
Required: no
Description: Debugging information level: 0, 1, 2, or 3.
* 0 => write the least amount of debugging information to stdout
* 1 => write a small amount of debugging information to stdout
* 2 => write a medium amount of debugging information to stdout
* 3 => write a large amount of debugging information to stdout

4 Output Datasets

4.1 History Files

The data atmosphere model does not create history files. The only data associated with this model is the data that is already contained in the input datasets.

4.2 Restart Files

The data atmosphere model does not need or create restart files.

4.3 Runtime Diagnostics

The data atmosphere model generates diagnostic messages which are written to stdout. This output consists mostly of brief messages that indicate how the simulation is progressing and whether any error conditions have been detected. Stdout also contains a record of the values of all model input parameters.

5 Data Exchanged with the Coupler

Each component model exchanges data with the coupler only. Component models have no direct connection with each other – all data is routed through the coupler. Most data is in the form of 2D fields. This data is accompanied by certain timing and control information (arrays of scalar real or integer values), such as the current simulation data and time.

5.1 Units Convention

All data exchanged conforms to this units convention:

Sign convention:

positive value \Leftrightarrow downward flux

Unit convention:

temperature	~ Kelvin
salt	~ g/kg
velocity	~ m/s
pressure	~ N/m ² = Pa
humidity	~ kg/kg
air density	~ kg/m ³
momentum flux	~ N/m ²
heat flux	~ W/m ²
water flux	~ (kg/s)/m ²
salt flux	~ (kg/s)/m ²
coordinates	~ degrees north or east
area	~ radians ²
domain mask	~ 0 \Leftrightarrow an inactive grid cell

5.2 Time Invariant Data

This section provides a list of the time invariant data exchanged between the coupler and each component model. Generally this data is the "domain" data: coordinate arrays, domain mask, cell areas, etc.

It is assumed that the domain of all models is represented by a 2D array (although not necessarily a latitude/longitude grid).

5.2.1 Data Sent to Coupler

```
domain data
* grid cell's center coordinates, zonal      (degrees north)
* grid cell's center coordinates, meridional (degrees east)
* grid cell's four vertex coordinates, zonal  (degrees north)
* grid cell's four vertex coordinates, meridional (degrees east)
* grid cell area (radians squared)
* grid cell domain mask ( 0 <=> not in active domain)
* ni,nj: the dimensions of the underlying 2D array data structure

time coordination data
* ncp1: number of times per day the component will communicate (exchange
data) with the coupler.

other information
* IC flag: indicates whether the coupler should use model IC's contained
on the coupler's restart file or IC's in the initial message sent from
the component model.
```

5.2.2 Data Received from Coupler

```
time coordination data
* date, seconds: the exact time the coupler will start the simulation from.
```

5.3 Time Variant Data

This section provides a list of the time-evolving data sent exchanged between the coupler and the data model. Generally this is state, flux, and diagnostic quantities.

Each data model provides the coupler with a set of output fields. Output fields from a model include output states (which can be used by another component to compute fluxes) and output fluxes (fluxes that were computed within the model and which need to be exchanged with another component model).

The coupler provides each component model with input fields. Input fields sent to a model include input states (the state variables of other models, which are needed to do a flux calculation) and input fluxes (a forcing fields computed by some other component).

Flux fields sent to or from the coupler are understood to apply over the communication interval beginning when the data was received and ending when the next message is received. The data models must insure that fluxes sent to the coupler are appropriate in this context.

5.3.1 Data Received from Coupler

```
states
* albedo: visible      , direct
* albedo: near-infrared, direct
```

- * albedo: visible , diffuse
- * albedo: near-infrared, diffuse
- * surface temperature (Kelvin)
- * snow height (m)
- * ice fraction
- * ocean fraction
- * land fraction (implied by ice and ocean fractions)

fluxes

- * zonal surface stress (N/m²)
- * meridional surface stress (N/m²)
- * latent heat (W/m²)
- * sensible heat (W/m²)
- * longwave radiation, upward (W/m²)
- * evaporation ((kg/s)/m²)

diagnostic quantities

- * 2 meter reference air temperature (Kelvin)

5.3.2 Data Sent to Coupler

states

- * layer height (m)
- * zonal velocity (m/s)
- * meridional velocity (m/s)
- * temperature (Kelvin)
- * potential temperature (Kelvin)
- * pressure (Pa)
- * equivalent sea level pressure (Pa)
- * specific humidity (kg/kg)
- * density humidity (kg/m³)

fluxes

- * precipitation: liquid, convective ((kg/s)/m²)
- * precipitation: liquid, large-scale ((kg/s)/m²)
- * precipitation: frozen, convective ((kg/s)/m²)
- * precipitation: frozen, large-scale ((kg/s)/m²)
- * longwave radiation, downward (W/m²)
- * shortwave radiation: downward, visible , direct (W/m²)
- * shortwave radiation: downward, near-infrared, direct (W/m²)
- * shortwave radiation: downward, visible , diffuse (W/m²)
- * shortwave radiation: downward, near-infrared, diffuse (W/m²)

diagnostic quantities

- * net shortwave radiation (W/m²)

5.3.3 How Output Fields are Derived

Data from the input data sequence is assumed to be daily average data. This data is linearly interpolated in time to get instantaneous fields, and this data is sent to the coupler. All data sent to the coupler is taken directly from the input data files, with a few exceptions (see below). The datm input data files are in the same format as history files created by CAM3 (normally they are created by CAM3). The derivations below are based on algorithms that the CAM atmosphere model would have used if it were able to put these fields on a CAM history file.

1. (bottom layer pressure) = (surface pressure)*(hybrid coeff B) + (reference pressure)*(hybrid coeff A)
2. (bottom layer potential pressure) = (bottom layer temperature) * ((surface pressure) / (bottom layer pressure)) ** ((dry air gas constant)/(specific heat of dry air))
3. (bottom layer density) = (bottom layer pressure) / ((bottom layer temperature)*(dry air gas constant))
4. It is assumed that downward longwave is missing from the data file, but that the file does contain net and upward longwave data, thus downward longwave is computed by subtracting upward from net longwave..
5. It is assumed that rain is missing from the data file, but that the file does contain net precipitation and snow data thus rain data is computed by subtracting snow from net precipitation.
6. If a user explicitly changes the default value of namelist variable flux_swfact, all shortwave fields (net and downward) can be multiplied by an arbitrary factor. See the flux_swfact option in the Namelist section of this document. Note that this means that the datm does not ignore all input from the coupler – datm output to the coupler is now a function of input from the coupler.
7. If a user explicitly changes the default value of namelist variable flux_albfb, which activates the albedo feedback option, the net shortwave radiation sent to the coupler is derived using the four downward shortwave components and the four corresponding albedos received from the coupler:

$$shortwave_{net} = \sum_{m=1}^4 (1 - albedo^m) * shortwave_{down}^m$$

This allows the net shortwave radiation to be more consistent with the surface albedos (e.g. sea ice extent). See the flux_albfb option in the Namelist section of this document. Note that this means that the datm does not ignore all input from the coupler – datm output to the coupler is now a function of input from the coupler.

6 Running the Data Model

6.1 Overview

The datm cannot run by itself, it can only execute in the context of running the complete CCSM system – a framework that requires atmosphere, ice, land, and ocean components, as well as a coupler component. The scripts that build and run the CCSM system are described in detail in the CCSM User's Guide, a holistic guide to running the complete system. This Guide includes a line-by-line explanation of the master run script and data model "setup scripts". A brief description of the CCSM run scripts is below. See the CCSM User's Guide for complete information.

6.2 Master Run Script and Component Setup Scripts

Two levels of c-shell scripts are used to build and run the CCSM system. A master "run script" coordinates the building and running the complete system while the component model "setup scripts" are responsible for configuring each individual CCSM component (including datm). Each CCSM component setup script is run in its own, separate subdirectory, where its executable resides and in which all of its input and output files are kept. The CCSM execution is controlled by the master script, referred to as "the run script".

The run script has the following tasks:

- a. Set batch system options
- b. Define common build and run environment variables
- c. Select multi-processing and resolution specs
- d. Run the setup script for each component
- e. Run the CCSM Integration.
- f. Archive/harvest/resubmit when this run is finished

The common build and run environment variable defined in the run script are automatically propagated to each of the component model setup scripts. These variables define such things as the machine architecture, the number of CPUs to run on, common experiment and file naming conventions.

Once the master run script has defined the common environment, each of the component models (cpl, atm, ice, lnd, and ocn) are configured using individual component setup scripts (e.g. datm.setup.csh) which:

- a. Parse the environment variables sent from the master run script. These are, in effect, input variables that might be required by a setup script or otherwise might alter the behavior of the setup script.
- b. Position or create any input data files, as necessary, including input namelist data files and climatological data files.
- c. Build the component model executable.

Finally, when all of the component model setup scripts have successfully completed, the run script executes all CCSM components simultaneously. The CCSM component models run simultaneously as a multi-program/multi-data (MPMD) message passing system, using MPI to exchange data.

7 Source Code Maintenance

7.1 Obtaining Source Code

The source code is available as part of the CCSM distribution at <http://www.cesm.ucar.edu/models/>. This distribution includes the source code for all CCSM component models. Documentation for other CCSM component models, as well as input data for running the models, is also available at this site.

7.2 Data Model Source Code

The source code is written using standard Fortran 90.

The source code was developed using the CVS revision control system, but only one "tagged" version of the code is available within any source code distribution. The code contains CVS information that can be used to identify the code contained in a particular distribution.

7.3 Shared Source Code

The datm model source code itself (found in `.../models/atm/datm6/` in the CCSM distribution) is incomplete and cannot be compiled (due to missing subroutines) unless it is compiled along with "CCSM shared code" (found in `.../models/csm_share/`). This shared code is an un-compiled library of support routines.

The source code itself has no machine dependencies, although the CCSM shared code does have some machine dependencies. One function of the shared code is to collect and isolate machine dependent code, and to provide CCSM component models with machine-independent wrappers to such code.

Another function of the shared code is to provide a mechanism for the various component models to be consistent with one another, for example, to use an identical value for pi or for the latent heat of fusion. Similarly, the shared code contains a library routine for calculating a solar angle, so that all component models can be consistent in their solar angle calculations.

7.4 Shared Build Environment

The CCSM distribution includes a shared build environment which includes a makefile (a GNU makefile), a variety of machine-dependent makefile macro files and a dependency generator. This common build environment is used to build all CCSM components including datm. The build environment is found in `.../models/bld/` subdirectory of the CCSM source code distribution.

The makefile, which requires the use of gnu-make, is machine independent, but it "includes" (a standard make functionality) a machine-dependent macros definition file. Several macros files are included in the distribution, but because such macro definitions are typically very machine and site specific, it is expected that end users will need to create a new macros definition file for their site.

Also part of the build environment is a dependency generator. This is written in standard c, and thus is compiled with the standard Unix cc command. The dependency generator is particularly useful when hacking code, either by modifying some files or adding new ones.